

Task 3.6:

Verification applications (spatial) to HIW - Comparative verification of NWC and NWP using spatial verification methods (SINFONY)

Today:

Extension of object-based verification of NWC and NWP towards “gridded objects” and ensemble forecasts

AWARE report

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- Try to switch to R-package “sf” (simple features) since it provides more functionality in simple calculations and plotting

Calculation of MMI based on polygons in “sf” more than **50% faster** than in previous version (“raster”)

- Provide some statistical output of matched objects, i.e., those objects with a total interest $> x$, where $0 \leq x \leq 1$

→
SOON

Output available but no analysis done yet

- At the moment, a real-time test system of “Sinfony” (Seamless integrated forecasting system) is running (NWP, nowcasting, combination of products, 20+1 members each), so there is a lot of new data for further verification tests

Only few days with complete data are ready

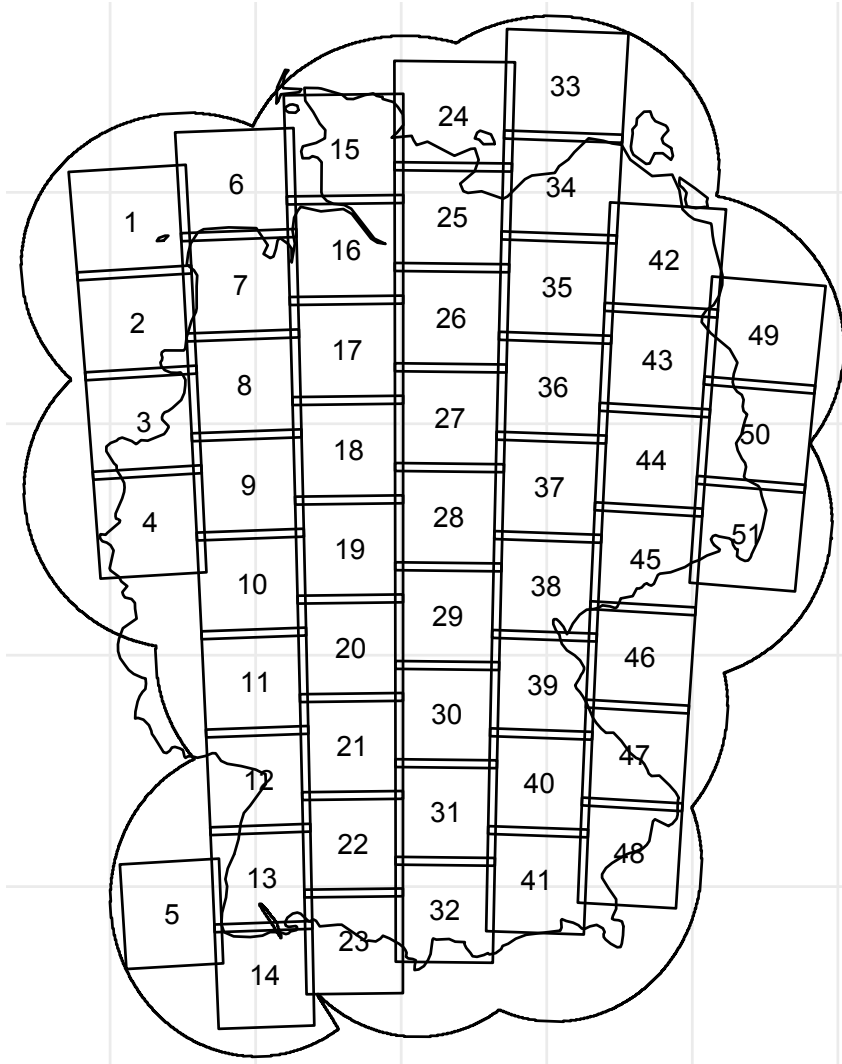
- Note: Since June 2020, there is a new colleague focussing on object-based verification only. This leads to some delay in further results because of induction period

That's me 😊

- Introduction of “**gridded objects**”

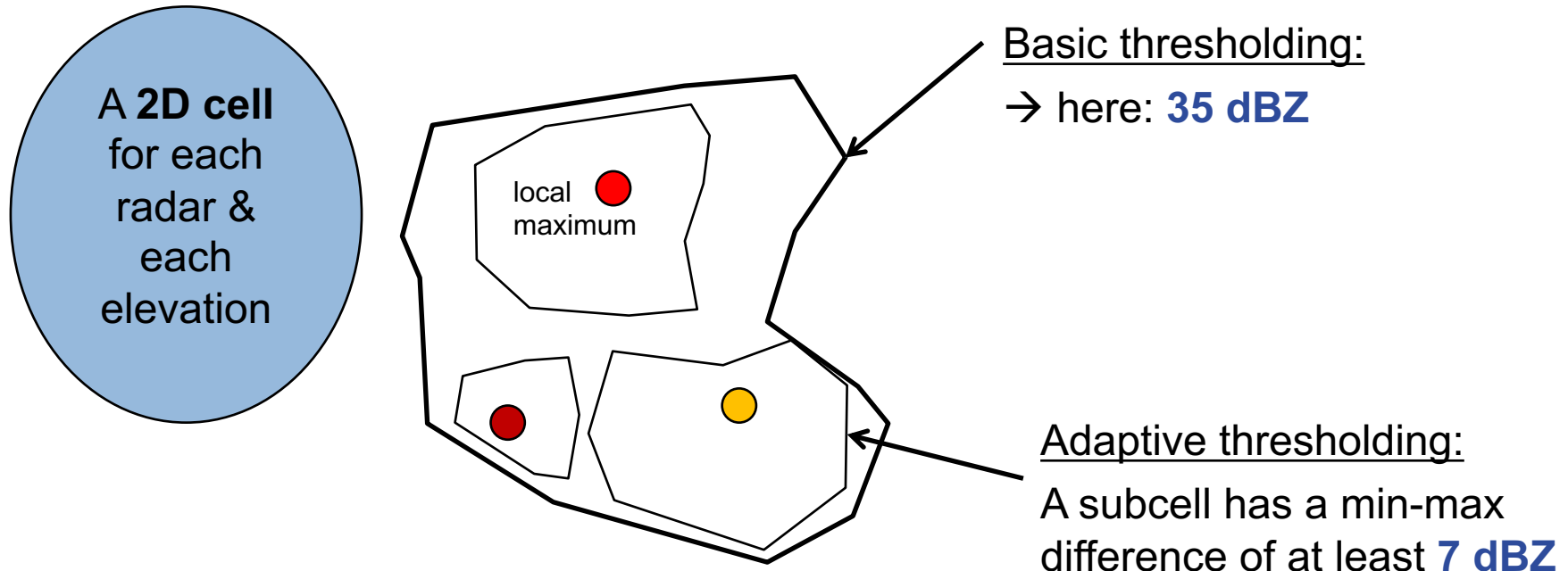
Introduction of “gridded objects”

- For **small-scale convective events** it is unnecessary to compare all objects all over Germany with each other
- Divide region of German radar composite into **51 grid boxes** with edge lengths of about 100 km and assign objects according to their **centroid position**
- **Overlap of 10%** of the boxes allows objects to belong to more than one box (*better more overlap? tests ongoing!*)
- Calculation of **MMI for each box** separately
- **MMI for entire domain** can be calculated additionally



- Many parameter settings → tuning necessary
- Problem “no objects” (MMI not defined) more frequent with smaller grid boxes
 - Solution: set MMI to missing value and count boxes $\left\{ \begin{array}{l} \text{with 0 objects in both the observations and forecasts} \rightarrow \text{good} \\ \text{with 0 objects in either the observations or forecasts} \rightarrow \text{bad} \end{array} \right.$
- Still unclear, how to adapt to Ensemble forecasts
 - Idea: Calculate MMI for each member separately and calculate mean etc.
 - Idea: Calculate “probabilistic objects” (Flora et al., 2019, WAF) and then get MMI from different probability ranges
- How to get number of “correct negatives” for object-based contingency tables
 - Idea: look-up-tables based on climatology for “expected” number and size of objects depending on current weather situation

In-House product: **KONRAD3D** (convective evolution in radar products)



- **3D cells** by combination
- Applied to both, observations and simulations
- Note, the entire identification process is more complex

Example of KONRAD3D objects

→ Preliminary data for 3 June 2020

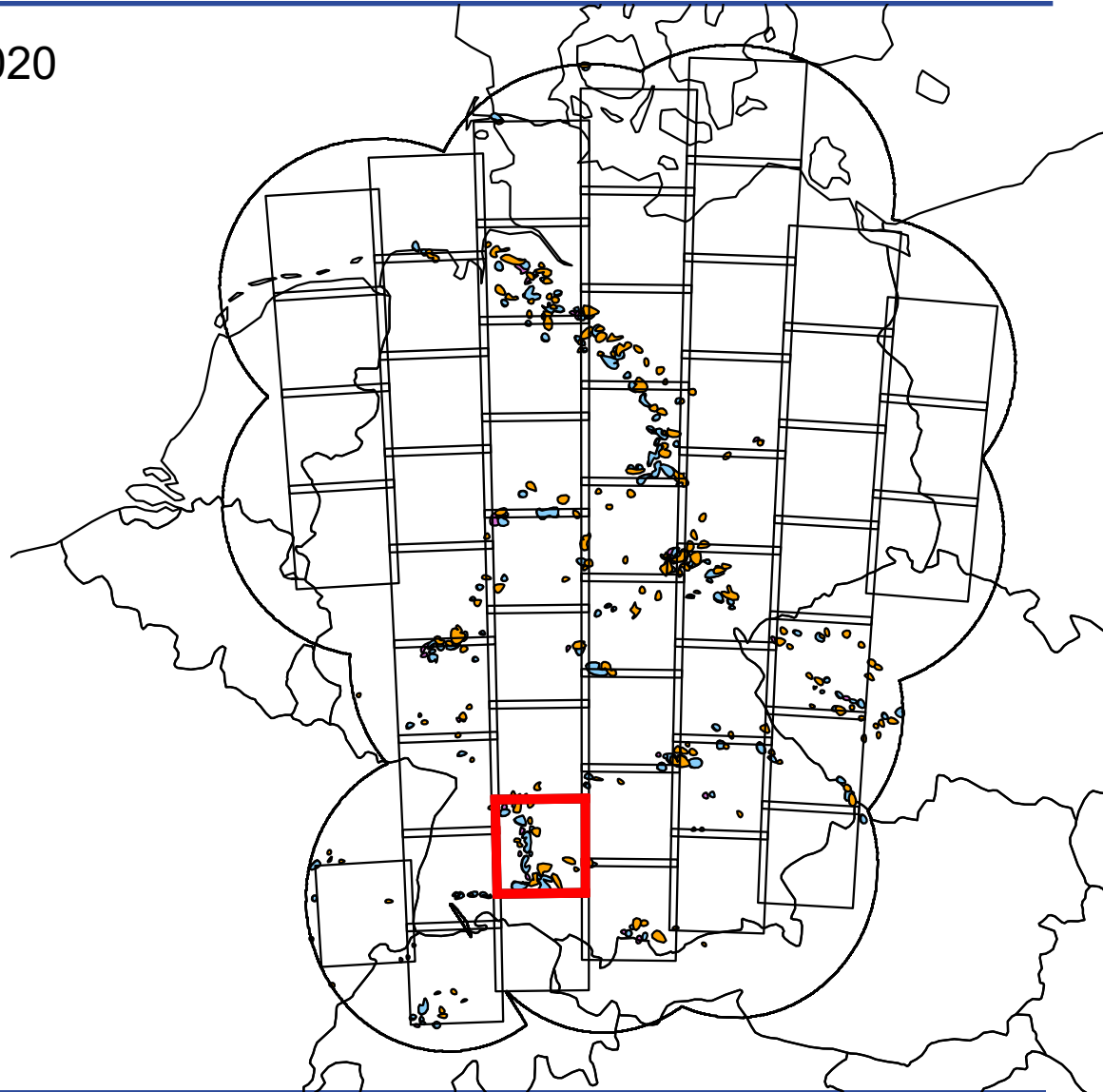
→ Observation 13:05

→ Nowcast for 13:35

→ Observation 13:35

→ Divide domain into grid boxes

→ “Gridded objects”



Example of KONRAD3D objects

→ Preliminary data for 3 June 2020

→ Observation 13:05

→ Nowcast for 13:35

→ Observation 13:35

→ Attributes of interest

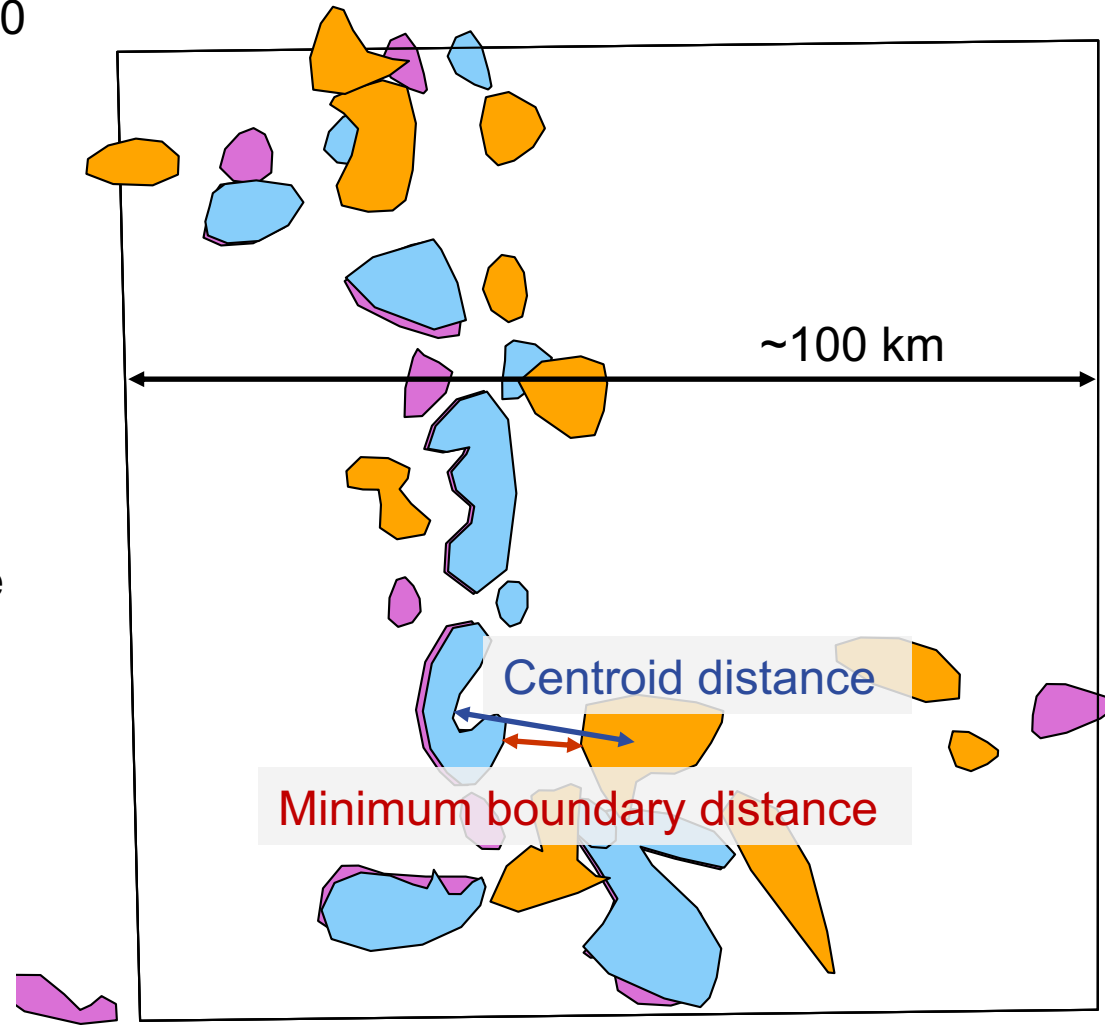
→ Centroid distance

→ Minimum boundary distance

→ Area ratio

→ Intersection area ratio

→ Compare all nowcasted
with all observed objects



→ "Interest" I

$$\rightarrow I_{i,j} = c_i w_i F_{i,j}$$

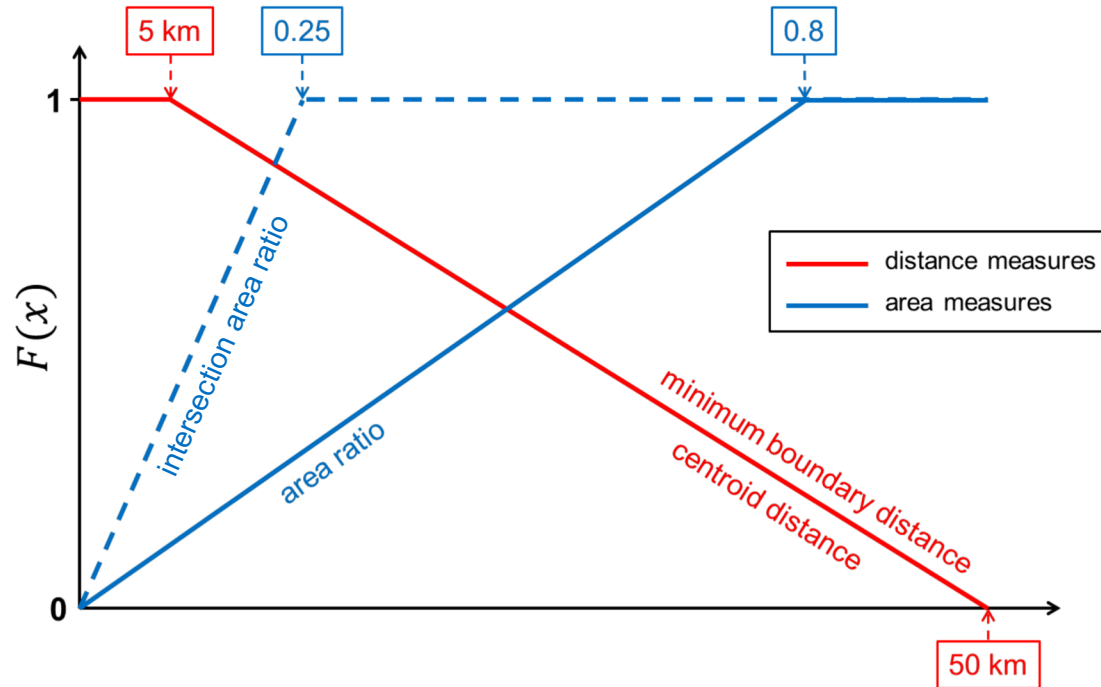
i attribute index

j object pair index

c confidence function

w weight of attributes

F interest function



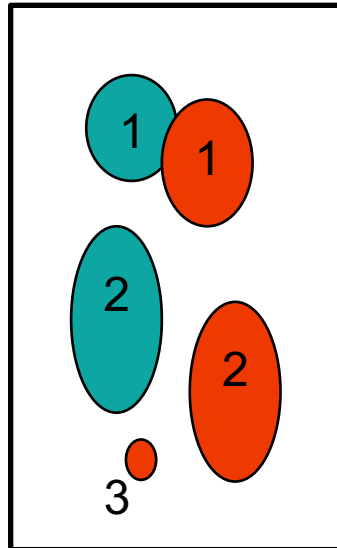
Attribute	Weight	Confidence	f_{\min}	f_{\max}
Centroid distance	28%	Area ratio	10 km	100 km
Minimum boundary distance	40%	1	5 km	50 km
Area ratio	19%	1	0.0	0.8
Intersection area ratio	13%	1	0.0	0.25

“Total Interest” and “MMI”

Combine the “Interest” $I_{i,j}$ of attribute i and object pair j with weights w_i and confidence functions c_i **for each attribute** to the “**Total Interest**” TI_j for all object pairs

$$TI_j = \frac{\sum_{i=1}^M I_{i,j}}{\sum_{i=1}^M c_i w_i}$$

■ forecast
■ observation



“Total Interest” - matrix

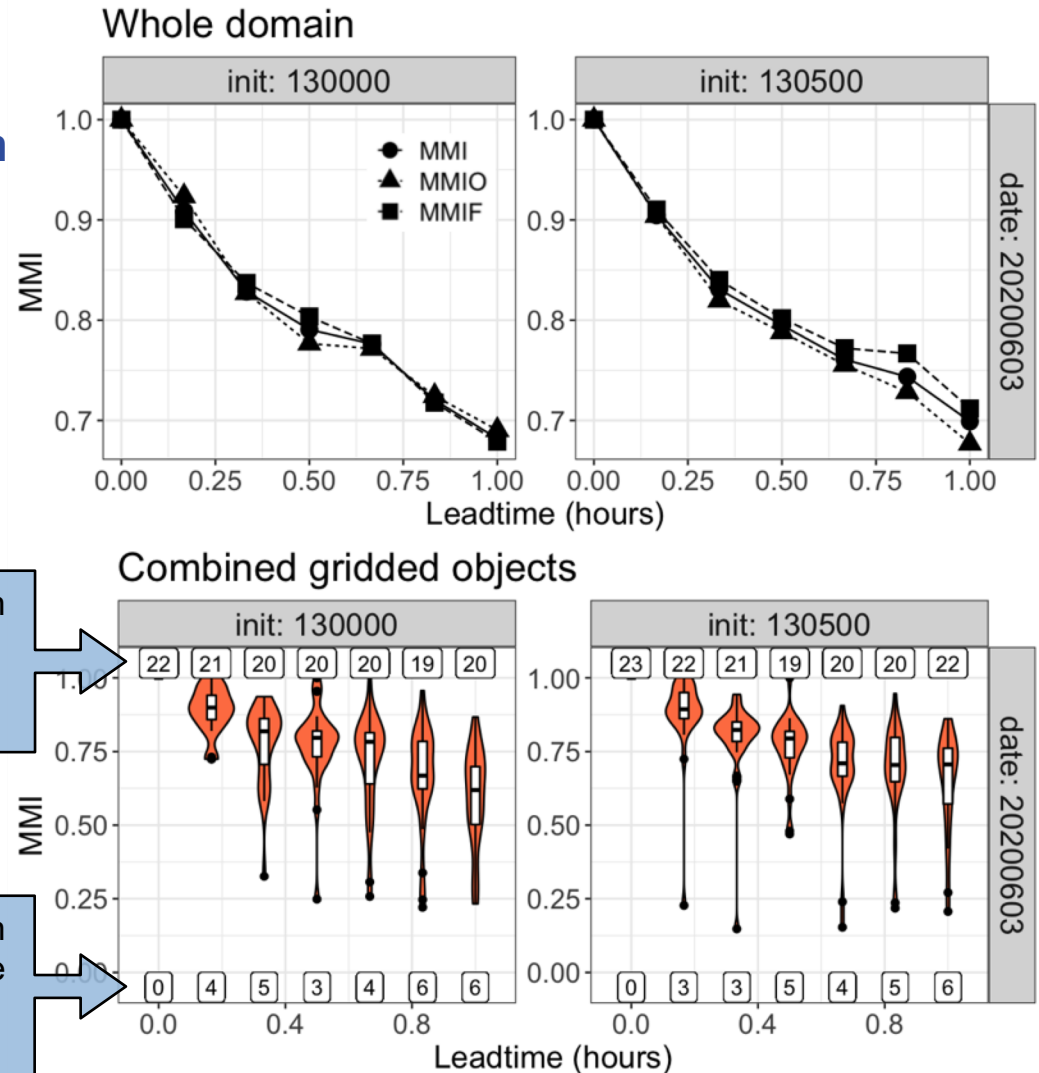
	observed objects			
	1	2	max:	
forecast objects	1	0.90	0.75	0.90
	2	0.50	0.80	0.80
	3	0.40	0.55	0.55
	max:	0.90	0.80	
		0.85 (MMIO)		0.80 (MMIF)

median(0.9, 0.8, 0.55, 0.9, 0.8) = 0.8

→ **Median of Maximum Interest (MMI)**

(Davis et al., 2009, WAF)

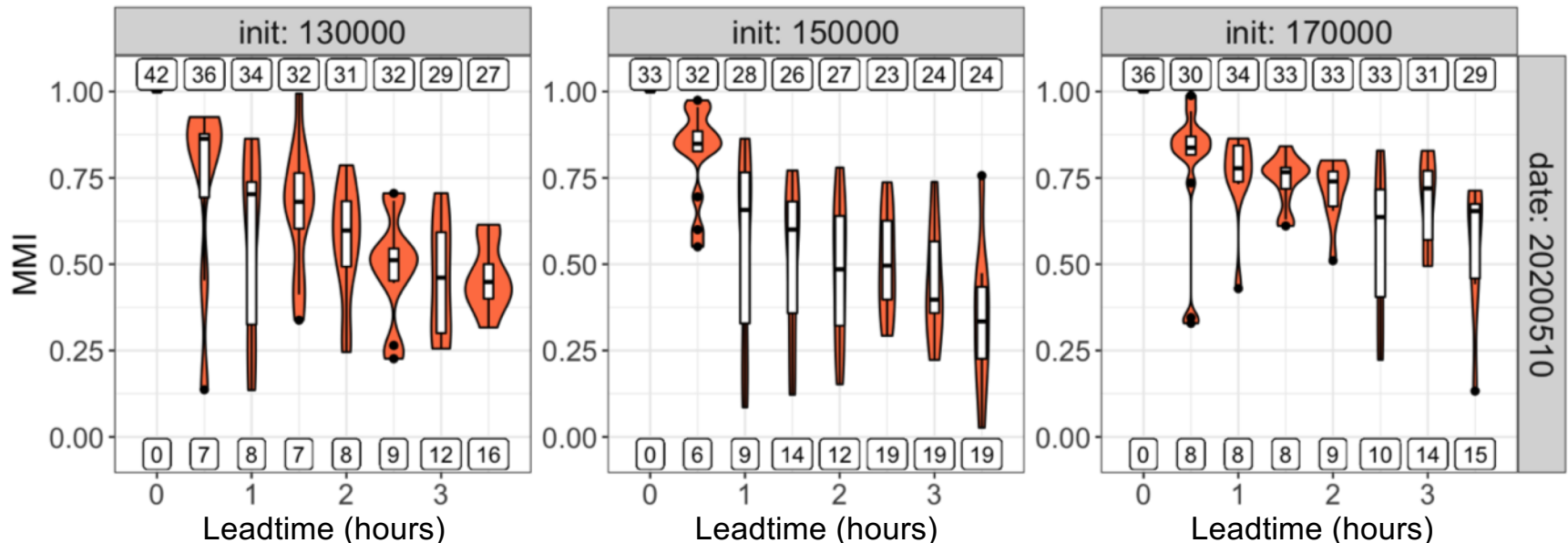
- Extended R-Shiny application **plots single grid boxes separately** or the **entire domain**
- Additionally a **combined violin-/box-plot** shows the probability density and the distribution of the scores of all grid boxes



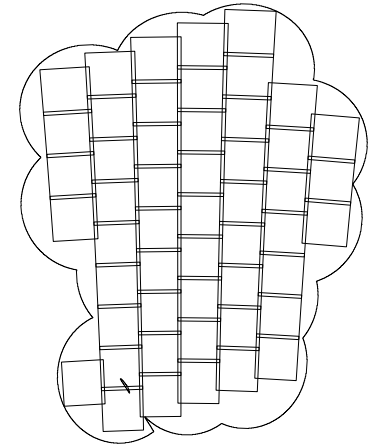
Gridded objects

- Example data for 10 May 2020
- Three initialisation time steps at 13, 15, 17 UTC and a lead time of 3.5 hours
- 13 UTC: 42 of 51 boxes have no objects
- 15 UTC: more boxes with objects; fast decrease of MMI
- 17 UTC: slower decrease of MMI → not so many new objects developing?!

Combined gridded objects

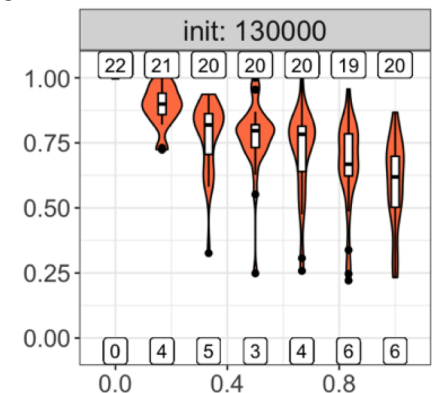


- Implementation of R-package **"simple features (sf)"**
 - Very time-efficient
- Fuzzy logic algorithm for calculation of "Total Interest" and **"Median of Maximum Interest" (MMI)** implemented in R-package for object-based verification
- Scores can now be calculated for **"gridded objects"**, i.e., the subdivision of the German radar composite into 51 grid boxes
- New diagram showing the **distribution of scores** over the grid boxes adds information to the plot of the MMI of the entire domain, e.g., number of boxes with no objects



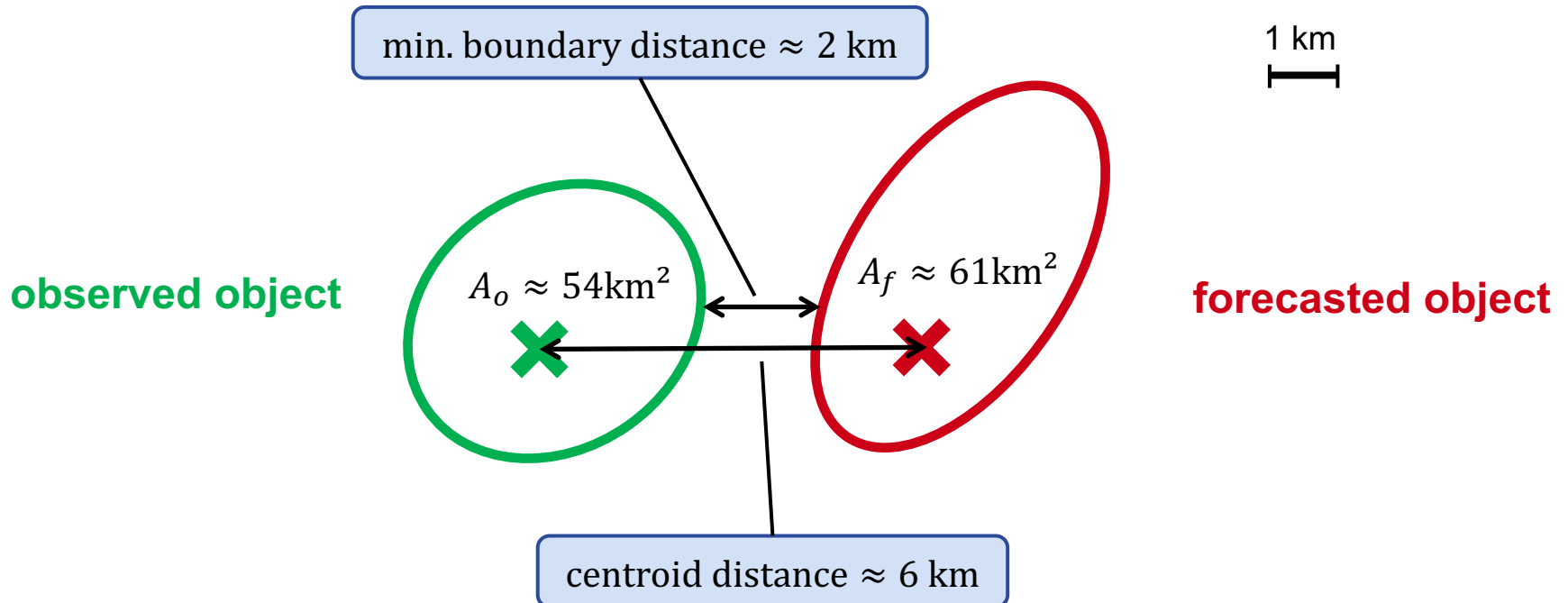
Future work / unresolved issues:

- Compute and analyse **statistics for matched objects**
 - "direction of displacement", "intersection area ratio", ...
- Adapt to **ensemble forecasts**
- Determine number of **correct negatives**



Appendix

Calculate the attributes of an object pair



$$\text{area ratio} = \frac{\min(A_o, A_f)}{\max(A_o, A_f)} \approx 0.88$$

$$\text{intersection area ratio} = \frac{A_{int}}{\text{mean}(A_o, A_f)} = 0$$