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ENIAC Project : ICON port to GPU for climate application using OpenACC and CLAW-DSL

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MeteoSwiss, C2SM, ETHZ, CSCS, MPI-M

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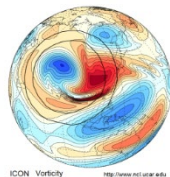
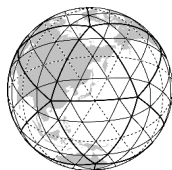
Overview

- The ENIAC project
- Porting strategy
- JSBACH soil model with the CLAW-dsl
- Outlook

ICON ENIAC (Enabling ICON on GPU)

Focus on global climate mode

- Adapt the ICON model to run on GPU and many-core architecture
 - Base line GPU port with OpenACC compiler directives
- Prepare the ICON model for actual use-cases in weather and climate on emerging HPC systems
- Achieving a high degree of performance portability by:
 - using source-to-source translation tool : CLAW
 - using alternative approaches such as the GridTools domain-specific language



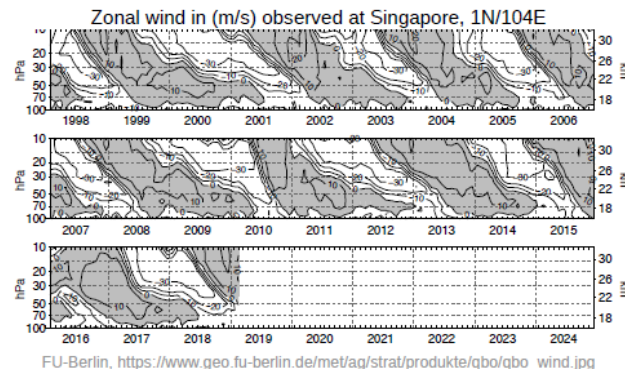
- Participants : ETHZ, C2SM, MeteoSwiss, MPI-M, DWD, DKRZ
- For NWP : IMPACT project, see Remo Dietlicher's tals

Application : QUBICC (MPI-M)

- "Quasi-Biennial Oscillation in a Changing Climate (QUBICC)"
- The QBO winds as observed for ~60 years are fairly regular, except for the breakdown in early 2016. How is QBO affected in a changing climate
- PRACE proposal submitted to run global simulations at ca 2 km on Piz Daint GPU system

Modell configuration

- Dynamics/transport on a 2.5 km grid (R2B10) with ca. 200 layers up to ca. 80 km.
- Radiation: Option A for GPUs: RRTMG; option B for CPUs: concurrent PSRAD
- Vertical diffusion implicitly coupled to JSBACH-lite "Graupel" cloud microphysics & saturation adjustment



Porting Strategy

- First base version OpenACC:
 - Dynamics+Climate physics+interface code : OpenACC
 - JSBACH (soil model) : claw-dsl
- Required code adaptation and changes
- Performance for the full model, cannot not be evaluated yet until a consistent set is ported. Should be available in October 2019
- Report performance for separate component
- Only supported compiler : PGI (requirement for OpenACC 2.6)

Refactoring of the Dynamics

Original OpenACC

```
SUBROUTINE solve_nonhydrostatic_eqns
...
!$ACC PARALLEL LOOP GANG
DO jb = 1, nblocks
  CALL get_indices_c( )
  !$ACC LOOP VECTOR COLLAPSE(2)
  DO jk = 1, nlev
    DO jc = 1, nproma
      prog_var(jc,jk,jb) = f(jc,jk,jb)
    END DO
  END DO
END DO
!$ACC END PARALLEL
:
!$ACC PARALLEL LOOP GANG
DO jb = 1, nblocks
  :
END DO
!$ACC END PARALLEL
:
END SUBROUTINE solve_nonhydrostatic_eqns
```

Optimal GPU nproma: 1000 — 4000

Refactored OpenACC

```
SUBROUTINE solve_nonhydrostatic_eqns
...
DO jb = 1, nblocks
  CALL get_indices_c( )
  !$ACC PARALLEL
  !$ACC LOOP GANG VECTOR COLLAPSE(2)
  DO jk = 1, nlev
    DO jc = 1, nproma
      prog_var(jc,jk,jb) = f(jc,jk,jb)
    END DO
  END DO
!$ACC END PARALLEL
END DO
:
DO jb = 1, nblocks
  CALL get_indices_c( )
  !$ACC PARALLEL
  :
!$ACC END PARALLEL
END DO
:
END SUBROUTINE solve_nonhydrostatic_eqns
```

Optimal nproma: as big as possible



Difficult patterns for GPUs

Index lists

```
DO jk = slev, elev
  DO je = i_startidx, i_endidx
    IF ( condition(je,jk) ) THEN
      icnt_c1 = icnt_c1 + 1
      idxlist_c1(icnt_c1,jb) = je
      levlist_c1(icnt_c1,jb) = jk
```

`fl_el(je,jk)%p1%lon = arrival_pts(je,1,1,jk,jb)` *Array of structs*

➔ `fl_el%p1%lon(je,jk) = arrival_pts(je,1,1,jk,jb)` *Struct of arrays*

Array syntax

```
IF (lclean_mflx) THEN
  prep_adv%mass_flx_me(:, :, jb) = 0._wp
  prep_adv%vn_traj      (:, :, jb) = 0._wp
ENDIF
```

```
DO jk = slev, elev
```

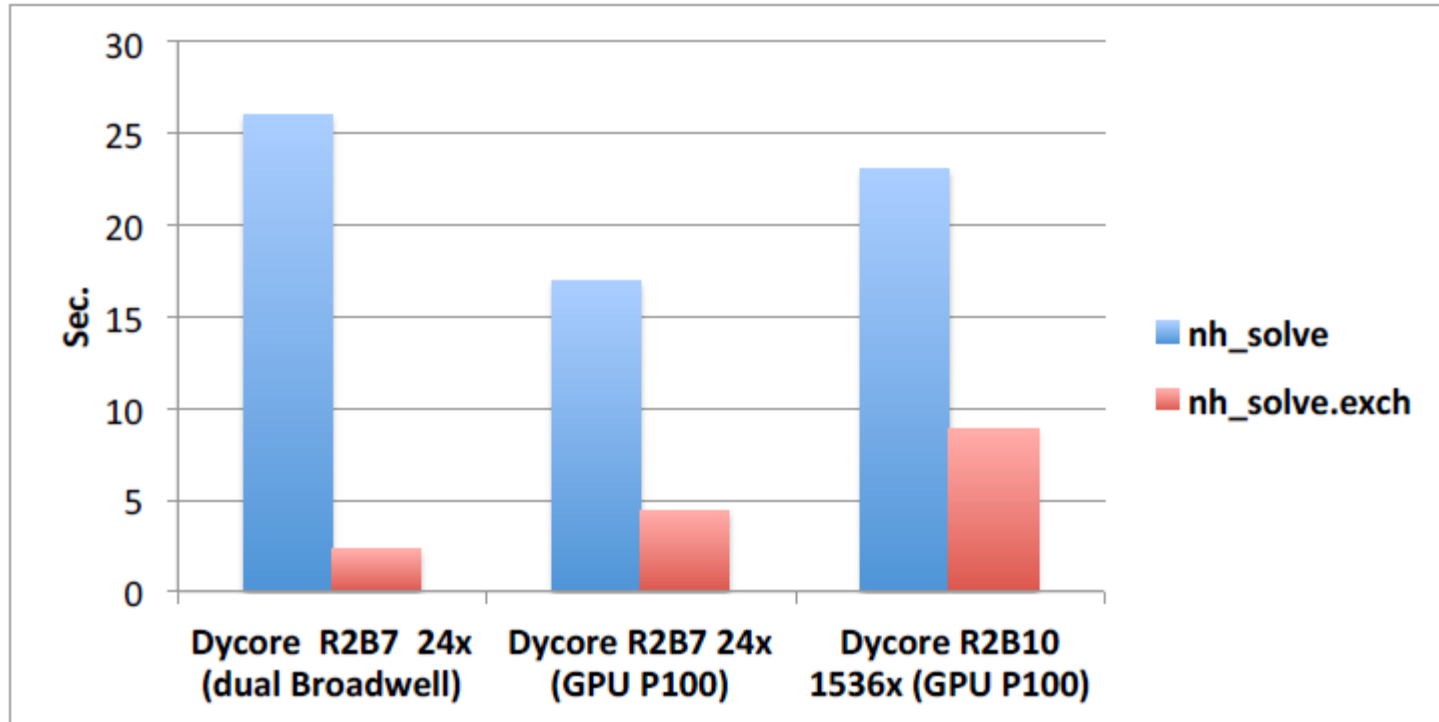
```
  DO je = i_startidx, i_endidx
```

```
    z_gauss_pts(je,3,1) = DOT_PRODUCT(shape_func(1:4,3),z_x(je,1:4))
```

Innermost functions

Need to workaround for OpenACC

Performance dynamic component



- R2B7 : Global, ca 20km
- Communication needs to be optimized

Source : Will Sawyer ,CSCS



Status GPU port using OpenACC

Focus on a reduce set of the climate physics

Component	Status	Comments
Dynamics	Done	- new implementation to fit strategy in the physics (large nproma) - Still need to remove updates
ECHAM Physics : surf_update, vdiff, ...	Done,	- Stil neet to remove updates - Optimization on ongoing
Physics: JSBACH	Done	- using CLAW DSL, no plain OpenACC port planned at this stage - Validation need to be finalized
Physics: Radiation (RRTMGT)	On going	- RRTMGP already exist with OpenACC - Need to port interface
Physics:Graupel microphys. (Seifert)	On going	- Almost complete, need to be merged with latest change from MPI (tendency)
Physics: 2 moments microphys. (HAM)	Not started	
aerosol module (HAM-light)	Not started	
Organization code	On going	- Close to completion for QUBICC case. Should be completed in november 2019

Experience porting with OpenACC

- Difficulties, Compiler issues (deep copy, atomics, ...)
- Difficult pattern to port, e.g. large derived type, Object oriented Fortran
- Limited compiler support for newer standard version ≥ 2.6 (only PGI)
- Validation of GPU vs. CPU results is time consuming
- ICON is VERY large : ~800 Fortran module files, ~1mio LOC
- Rapidly evolving code

JSBACH - ICON soil

- Fortran 2003/2008 code style - ~25k LOC
- Special DSL to define storage and access, Pipeline of tasks on different tiles
- 80% of compute code written as ELEMENTALS
- **Elementals function are a special case of single column abstraction with no vertical loop : use claw-dsl**
- CLAW port : ~140 EXPAND kernels automatically generated, ~90 ELEMENTAL (SCA) kernels automatically generated, ~100 files parsed by the CLAW Compiler, ~20 files with deep transformation
- Port is now 99% complete

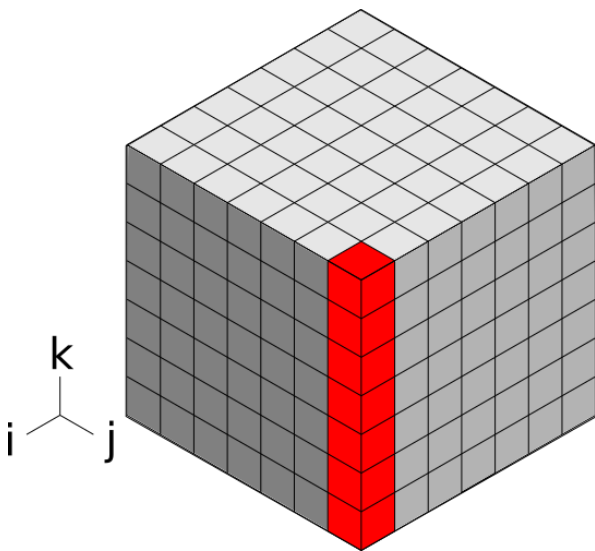
CLAW Single Column Abstraction (SCA)

Targets physical parameterization

- No notion of independent horizontal dimension
- No DO statements over horizontal
- Arrays are demoted to get rid of the horizontal

Separation of concerns

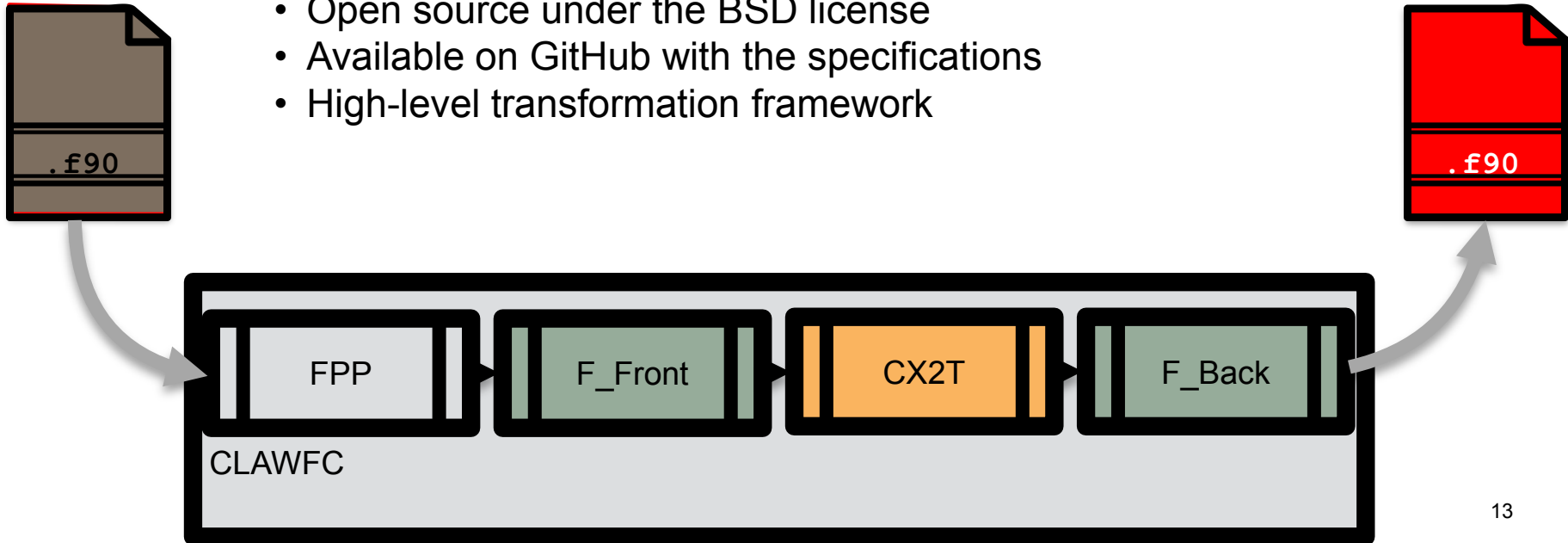
- Domain scientists focus on their problem (1 column, 1 box)
- CLAW Compiler produce code for each target architecture and directive languages



“The CLAW DSL: Abstractions for Performance Portable Weather and Climate Models.” PASC’18 Proceedings. <https://doi.org/10.1145/3218176.3218226>

What is the CLAW Compiler?

- Source-to-source translator
- Based on the OMNI Compiler Project
- Fortran 2008
- Open source under the BSD license
- Available on GitHub with the specifications
- High-level transformation framework



Code example (original + CLAW directive)

CLAW
directives



```
PURE ELEMENTAL SUBROUTINE calc_radiation_surface_net(swvis_down, swnir_down, &
  alb_vis, alb_nir, lw_down, t, rad_net, swvis_net, swnir_net, sw_net, lw_net)

  USE mo_phy_schemes, ONLY: lwnet_from_lwdown

  !$claw model-data
  REAL(wp), INTENT(in) :: swvis_down, swnir_down, alb_vis, alb_nir, lw_down, t
  REAL(wp), INTENT(out) :: rad_net
  REAL(wp), INTENT(out), OPTIONAL :: swvis_net, swnir_net, sw_net, lw_net
  !$claw end model-data
  !$claw sca

  REAL(wp) :: zswvis_net, zswnir_net, zsw_net, zlw_net

  ! Compute net SW radiation from downward SW and albedo
  zswvis_net = swvis_down * (1._wp - alb_vis)
  ...
```

Code example (transformed)

clawfc -D__ICON__ --model-config=icon_jsbach.toml --target=gpu --directive=acc -o code_transformed.f90 original.f90

```
SUBROUTINE calc_radiation_surface_net ( swvis_down , swnir_down , &
alb_vis, &
alb_nir , lw_down , t , rad_net , swvis_net , swnir_net , sw_net , lw_net)
USE mo_phy_schemes , ONLY: lwnet_from_lwdown
INTEGER , INTENT(IN) :: kproma

REAL ( KIND= wp ) , INTENT(IN) :: swvis_down ( : )
REAL ( KIND= wp ) , INTENT(IN) :: swnir_down ( : )
REAL ( KIND= wp ) , INTENT(IN) :: alb_vis ( : )
REAL ( KIND= wp ) , INTENT(IN) :: alb_nir ( : )
REAL ( KIND= wp ) , INTENT(IN) :: lw_down ( : )
REAL ( KIND= wp ) , INTENT(IN) :: t ( : )
REAL ( KIND= wp ) , INTENT(OUT) :: rad_net ( : )
...
```

```
...
!$acc data &
!$acc present(swvis_down,swnir_down,alb_vis,alb_nir,&
!$acc , lw_down,t,rad_net &
!$acc ,swvis_net,swnir_net,sw_net,lw_net)
!$acc parallel
!$acc loop gang vector
DO horizontal = 1 , kproma , 1
  zswvis_net = swvis_down ( horizontal ) * ( 1._wp - alb_vis ...
  zswnir_net = swnir_down ( horizontal ) * ( 1._wp - alb_nir ...
  zsw_net = zswvis_net + zswnir_net
  zlw_net = lwnet_from_lwdown ( lw_down ( horizontal ) , ...
  rad_net ( horizontal ) = zsw_net + zlw_net
...

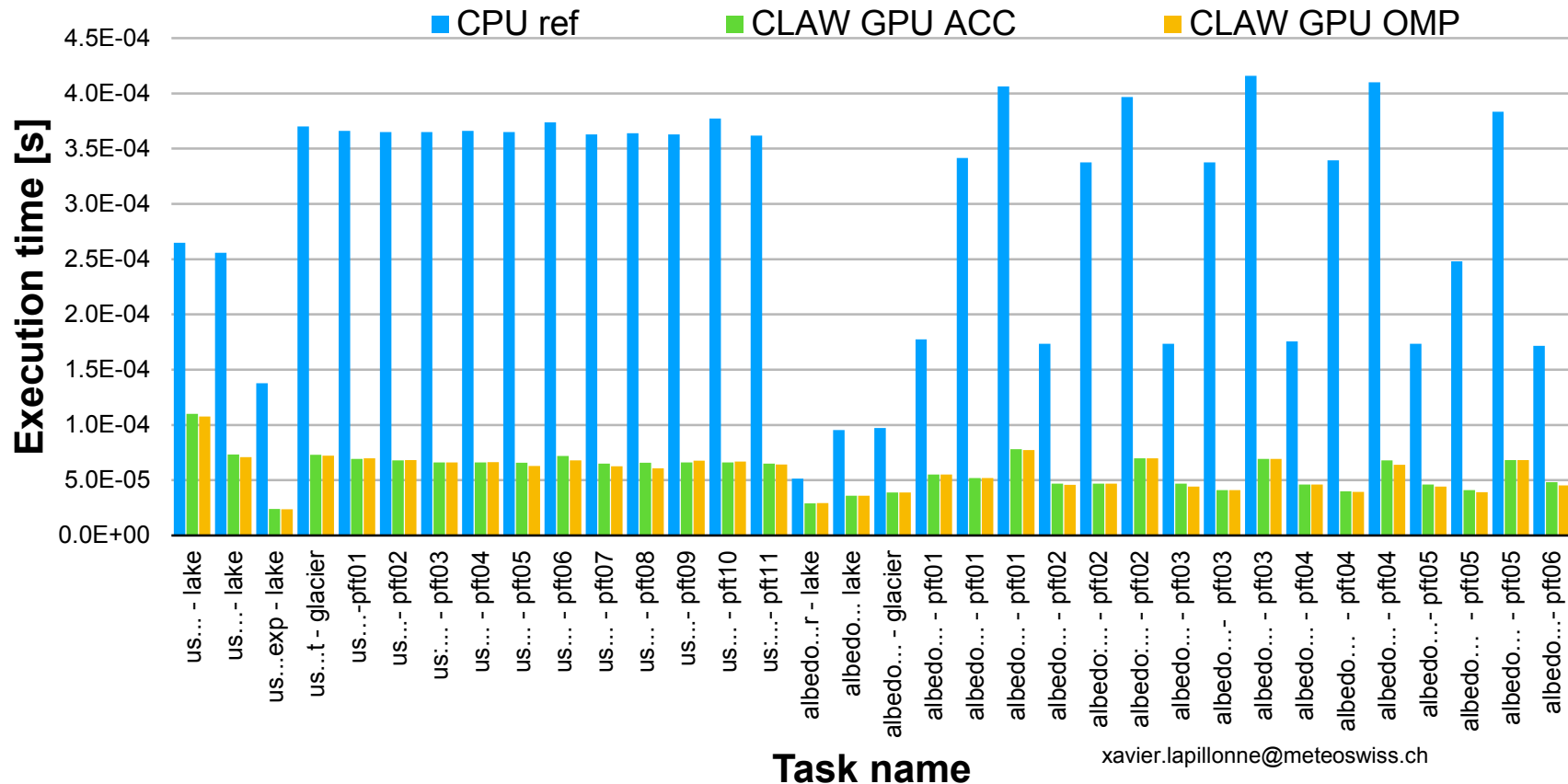
```

Performance Results

- For GPU claw can generate OpenACC or OpenMP for accelerator directives
- OpenACC results obtained using the PGI compiler, timed in full application
- OpenMP for accelerator : Cray. Note : due to current limitation and issues with the compiler the results are obtained with standalone kernels

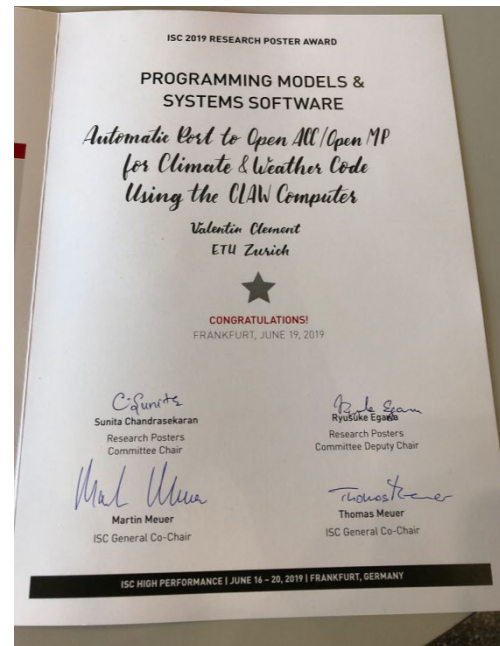
Performance results

Performance comparison (socket to socket) of JSBACH tasks on Intel Haswell E5-2690v3 and NVIDIA P100. Domain size (horizontal grid points x vertical levels) = 20480 x 47



JSBACH CLAW-dsl

- Speed up on GPU between 3 to 8 compare to CPU
- Work with CLAW-dsl : ISC'19 Award
- Will be published
Special issue Supercomputing Frontiers
and Innovations
“Automatic Port to OpenACC/OpenMP for PhysicalParameterizations
in Climate and Weather Code Using the CLAW Compiler”,
accepted with minor modifications



ENIAC outlook and learnings

- First (reduced) GPU version for Climate applications should be ready by Q4 2019 using OpenACC and CLAW-DSL
- MeteoSwiss/C2SM contribution completed in September 2019 (V. Clement + P. Marti)
- Project running until June 2020 (stil funding for MPI-M)
- Potential application : QUBICC, 2km Global on Piz Daint
- Learnings :
 - More difficult and complex to work and port ICON to GPU than COSMO
 - Coordination is critical, regular meeting and video calls with MPI-M,DKRZ,CSCS was key to advance in the project.



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