

- PP KENDA-O : Km-Scale Ensemble-Based Data Assimilation for the use of High-Resolution Observations (Sept. 2015 – Aug. 2020)
- Work on KENDA @ DWD:

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- MeteoSwiss: Daniel Leuenberger, Claire Merker, Alexander Haefele, Maxim Hervo, Marco Arpagaus
- COMET: Francesca Marcucci, Lucio Torrisi, (Paride Ferrante)
- ARPAE-SIMC: Virginia Poli, Thomas Gastaldo (Chiara Marsigli \rightarrow DWD)
- Roshydromet: *Mikhail Tsyrulnikov, Dmitrii Gayfulin, (Elena Astakhova)*







- Task 2: extended use of observations
- Task 3: lower boundary:
 - soil moisture analysis using satellite soil moisture data (COMET) fellowship ended (no clear benefit yet, will continue tests in parallel suite, with little (!) FTE)
 - DWD: new fixed position (Gernot Geppert, since March 2019):
 - write *new* SST + snow analysis code in DACE (method: VAR)
 - possibly develop soil moisture analysis for ICON-LAM
- Task 4: adaptation to ICON-LAM
 - particle filter (technically implemented for COSMO, test over 12 hrs)





Overview Task 1: Further development of KENDA



MeteoSwiss \rightarrow meteodrone, MW radiometer, etc. (Task 2)

- regional climatological B matrix: scientific problems (formulation did not work) now trying an alternative formulation (to compute velocity potential, streamfunct.)
 → task is important for future option of regional 3DVar
- statistical evaluation of LETKF analysis increments
- KENDA-1: KENDA at 1.1 km (same LETKF settings as at 2.2km, first test over 3 days promising)

ARPAE-SIMC \rightarrow radar Z (Task 2)

COMET

• investigation of KENDA at 7 km and 2.2 km resolution; incl. use of AMV (sat winds)

Roshydromet (> Stochastic Pattern Generator)

• technique to estimate (additive + mulitplicative) model errors

by using COSMO-2.2km (as a model) vs. COSMO-0.22km

(as the 'truth', tendencies started at the same point in phase space)

shows problems (spin-up) → method might not work (not critical for KENDA project as a whole)





















Task 1:3-D / 4-D LETKF versions
results with COSMO



4-D (Online)-LETKF vs. 3-D MEC-LETKF (COSMO)

Type of verification	with LHN	without LHN
upper-air analysis	neutral – positive	neutral – positive
upper-air first guess (1-h)	neutral – positive	neutral – positive
upper-air forecast	neutral	neutral – positive
surface forecast	neutral – positive	neutral – positive
bias of precip yes/no	neutral	neutral
bias of strong precip	neutral	neutral
accuracy of precip yes/no	positive	positive
accuracy of strong precip	positive	positive





Task 1: 3-D / 4-D LETKF versions summary + implication for VAR



- 3-D LETKF not much worse than 4-D LETKF
- interpolated 4-D LETKF (\rightarrow ICON-LAM) ~ as good as online 4-D LETKF (due to reduced noise when computing $H(\mathbf{x})$ / observation increments?)
- results for high-res. obs (radar, satellite) up to now better with (1-hrly) 3-D approach ٠

implication on **EnVar** (VAR approach expected to be advantageous (for det. ana/fcst)):

- \rightarrow 3-D EnVar: not much degradation due to 3-D limitation expected
- \rightarrow 4-D EnVar (requires time interpolation between model states used in control vector for minimization): no degradation expected
- \Rightarrow additional motivation to develop EnVar for ICON-LAM





Task 2: use of additional observations overview Deutscher Wetterdienst		
• Task 2.1 (a):	radar radial wind Vr	\rightarrow slides (DWD \rightarrow COSMO)
• Task 2.1 (b):	radar reflectivity Z	\rightarrow slides (ARPAE \rightarrow COSMO) (DWD: \rightarrow ILAM)
• Task 2.2:	GPS slant total dela	y → (small) positive impact from combined ZTD + low-elevation STD (DWD)
• Task 2.3/2.4:	SEVIRI IR (WV) :	clear-sky data: small benefit on RH in upper troposph. good basis for extending work to all-sky data (\rightarrow ILAM)
• Task 2.5:	screen-level obs (T2M, RH2M): resources since spring work on innovative parameterized non-lin. bias correct. \rightarrow ILAM	
• Task 2.6:	Mode-S	operational
• Task 2.7:	ground-based remot	te sensing: wind lidar, Raman lidar, MW radiomdeter, meteodrone \rightarrow slides (MCH)

• WG1 (DWD): SEVIRI VIS (cloud), lightning, land surface temperature, cars,





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Task 2.1:radar radial velocity (Vr)
conclusions at GM 09/18



- **obs errors** depend on elevation and height / range
- **superobbing** (10 km), **vertical** (elevat. 0.5°, 1.5°, 3.5°) + **temporal thinning** (1 h) beneficial
- **positive impact on precipitation** only **small** (in summer), larger without simultaneous use of Mode-S (in Exp. & Ref.)
 - → operational use of radar Vr could increase obs redundancy in the DA system, might mitigate outage of Mode-S (pot. larger impact in areas w/o Mode-S)
- positive impact on wind, especially in first forecast hours \rightarrow useful towards nowcasting
- neutral (or very small positive) impact in winter
- still challenge: radial wind data quality (control) increase of computational cost: COSMO 5 – 10%, LETKF up to 50%
- all experiments with COSMO-DE (2.8 km) so far, experiment with COSMO-D2 (2.2 km) for convective period being set up
- radar Vr in parallel suite for COSMO-D2 since 12 June 2018, with neutral impact in the dry summer so far









- at night: more obs in total, much more obs with large FG departures (> 5 m/s) many of which are related to low reflectivity (< 5 dBz)
 - reason: Vr obs are produced in stable PBL (where reflectivity is low)
 - → decrease influence of obs in analysis by increaseing specified obs error where observed reflectivity is low (linear function betw. 0 10 dBz)















Task 2.1: radar radial wind summary



- modification applied: reduced influence of radial winds by increasing specified obs error where observed reflectivity is low (more often at night)
- negative impact seen in parallel suite removed now small, but consistent positive impact from radar radial winds
- planning to re-introduce Vr into parallel suite (for COSMO !)





screen-level observations Task 2.5: bias correction of 2-m temperature **Deutscher Wetterdienst** Christine Sgoff, Elisabeth Bauernschubert (Roland Potthast, ...) **2m Temperature – Bias Behavior** Cloud cover in okta 0.5 **Observation stations with** bias in Kelvin 2m temperature and cloud cover measurements Diurnal cycle of T2M bias, depending on cloud cover -0.5 (average over all stations) \rightarrow More clouds \rightarrow less pronounced diurnal cycle 5 10 15 20 time in hours





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Approach: dynamic parameterized non-linear bias correction

→ approximate diurnal cycle of bias b with basis functions A_i with a dynamic coefficients a_{ik} update depending on the measured cloud k cover

 $b_k = \sum_i A_i \cdot aik$ 1 sin(nt) cos(nt) sin(2nt) cos(2nt) sin(3nt) cos(3nt)

- → 3Dvar update of a_{ik} each time step with new observation
- Assimilation including bias correction only with reliable statistics (~ 50 updates)
- ➔ Each station has its own set of coefficients a_{ik}









- LETKF/KENDA adjusted to ILAM (model grid structure (→ obs operators, exclusion of obs near lateral BC, ...), parallelisation, writing increments instead of analyses, SST perturbations (derived in LETKF instead of separate program 'adjust_sst_snow'), nudging of soil moisture (towards ICON-EU), ...);
- ICON: DACE obs operators (plus RADVOROP) included for 4-D online LETKF;
- SST- / Snow Analysis adjusted to ILAM;
- DA suite: MEC-based + online ILAM-LETKF implemented in BACY-1, with options for IAU, LHN, SST-/Snow-Analysis etc.; bug corrections, adjustments, and refinements in the
 - model (e.g. shallow convection, SSO parameters, reduced divergence damping, extended upper and lateral boundary relaxation, IAU)
 - data assimilation (hydrostatic balancing, analysis increments for qc, qi, w, MEC-QC against deterministic run, bug fixes and adjustments in LHN, ...)
 - BACY-1 (experimentation script environment developed in DA Section of DWD)







- whole ICON-LAM **DA + forecast system** (chain) developed and tested in **BACY-1** so that:
 - all components available + compatible with each other
 - implementation in NUMEX / parallel suite / operational suite made much easier
- → a huge amount of work into adaptation of KENDA to ICON-LAM, incl. testing ! (also for porting forward operators for additional obs, e.g. radar, SEVIRI, etc.)
- \rightarrow thanks to:

Hendrik Reich, Christian Welzbacher, Harald Anlauf, Klaus Stephan, Thomas Rösch, Martin Lange, Thorsten Steinert, Sven Ulbrich, Gernot Geppert, Lilo Bach, Uli Blahak, Christoph Schraff, Roland Potthast, ..., Günther Zängl

- results from a few major tests, with 3-D MEC-based LETKF:
 - impact of LHN (latent heat nudging) in summer
 - comparison of ICON-DE vs. COSMO-DE
 - in summer (convection) with (and w/o) LHN
 - in winter without LHN







Optimization of ICON-LAM model setup in LETKF cycle: Relaxation at **upper boundary Deutscher Wetterdienst**



balance: evolution of mean abs. **surface pressure tendency** 0.3 **ICON-LAM** (vertical wind \rightarrow 0) ICON-LAM (prognostic var \rightarrow ICON-EU, max 0.050) 0.25 ICON-LAM (prognostic var \rightarrow ICON-EU, max 0.075) ICON-LAM (prognostic var \rightarrow ICON-EU, max 0.100) COSMO (prognostic var \rightarrow ICON-EU) 0.2 dPS/dt [Pa/s] 0.15 0.1 0.05 0 500 1000 1500 2000 2500 3000 3500 4000 0 Time [s]



Optimization of ICON-LAM model setup in LETKF cycle: Incremental Analysis Update (IAU) Deutscher Wetterdienst



Task 4.1: Adaptation to ICON-LAM: LHN



- ICON-LAM responds to LHN quite differently than COSMO
- \rightarrow tuning done (climatological profile where rain is missing in model; no log-scaling)



ICON-DE vs. COSMO-DE with LHN (MEC-based 3-D LETKF)

(27 May – 10 June 2016)

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ICON-DE vs. COSMO-DE with LHN (MEC-based 3-D LETKF)

(27 May – 10 June 2016)



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ICON-DE vs. COSMO-DE (MEC-based 3-D LETKF, without LHN)

(26 May – 11 June 2016)

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 surface pressure strongly improved (possibly due to more consistent lateral BC (from ICON-EU); surface pressure in summer has been known as an issue in COSMO-KENDA)





DWD







ICON-DE vs. COSMO-DE without LHN (MEC-based 3-D LETKF)

winter (18 – 31 Jan. 2018)

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ICON-DE vs. COSMO-DE without LHN (MEC-based 3-D LETKF) winter (18 – 31 Jan. 2018) Deutscher Wetterdienst

DWD



Task 4.1: Adaptation to ICON-LAM: status



- LHN (latent heat nudging) adapted to ICON-LAM
 - summer (convection): positive impact in ICON-DE almost as large as in COSMO-DE
 - winter: almost no benefit, LHN needs further evaluation / tuning (ICON-DE has 100 % more precip than radar, LHN may have problems to reduce it)
- impact experiments (MEC-based 3-D LETKF): ICON-DE verifies better than COSMO-DE

(convective summer with & w/o LHN (14d); winter w/o LHN (14d): upper-air T + wind better, T2M, RH2M, 10-m wind much better; precip similar)

first extended impact experiments with 4-D online LETKF for ICON-D2 ongoing

(also testing nudging of soil moisture towards ICON-EU \leftarrow SMA)

- pre-operational suite ICON-D2 with KENDA starting Oct. 2019 (after NUMEX implement.)
- in parallel: development for use of additional observations
- towards 3DVar / EnVar option (for deterministic run):
 - preliminary MEC-based 3DVAR + EnVar exists (for COSMO / ILAM in BACY-1)
 - to do: COSMO obs operators (conventional, + radar etc.!) in DACE + TL/Adjoint; regional B-matrix; tuning, testing, etc.



