

3D wind field retrieval with  
4DVAR technique for assimilation to LM

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Projection: RAOB  
Composite Radar:  
PAB  
RAB  
POZ  
RME  
S41  
LES  
Rainbow (C)  
by GEMTRONIK

# Goals:

- Method for assimilation of radar data that would be alternative to Latent Heat Nudging.
- Verification of “3D Simple Adjoint Velocity Retrievals from Single-Doppler Radar” method (J. Gao, M. Xue, Alan Shapiro *et al.*, Center for Analysis and Prediction of Storms, University of Oklahoma, Journal of Atmospheric and Oceanic Technology, vol. 18, 2001)

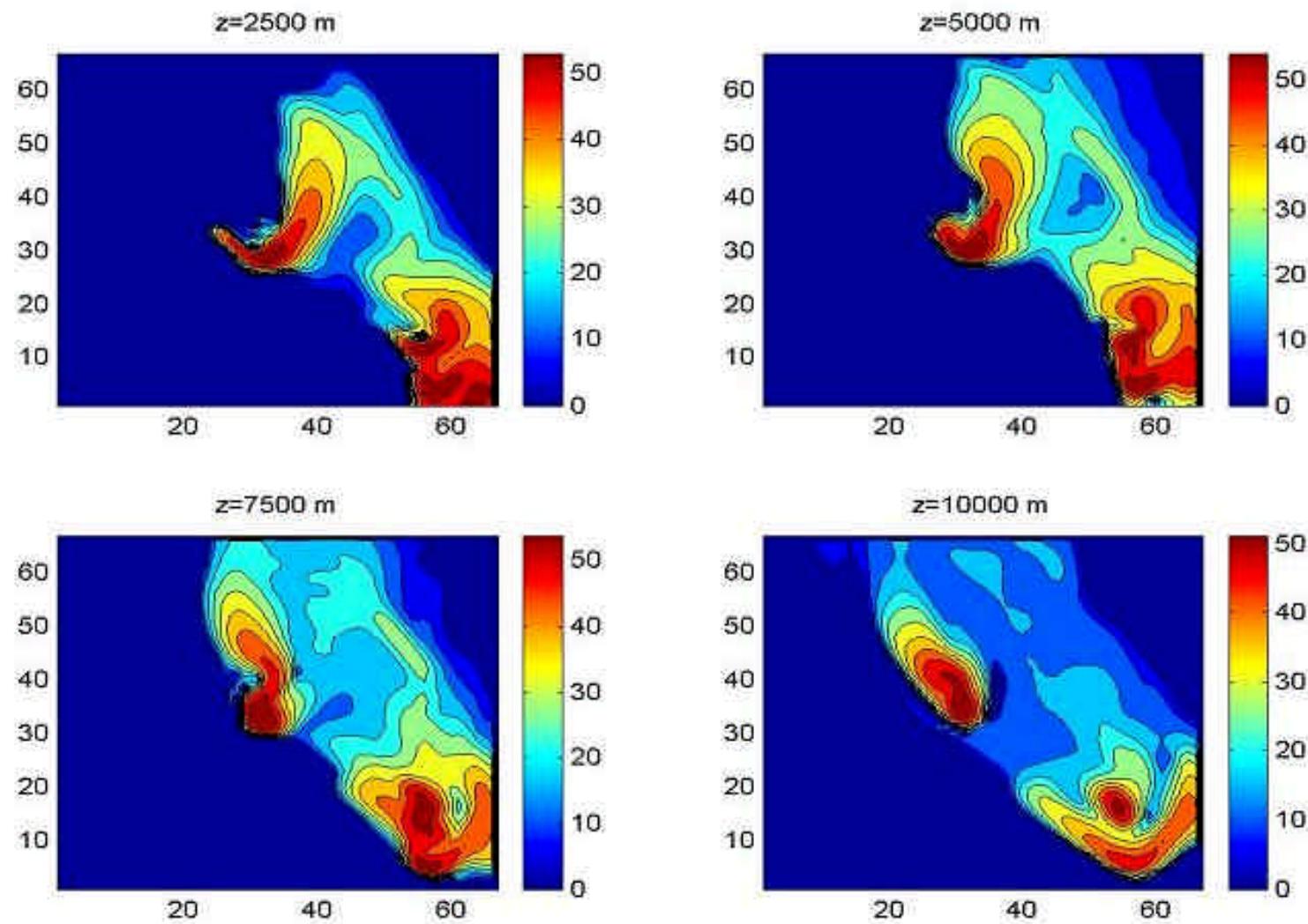
- 1) Choose a first guess for the control vector  $\mathbf{Z} = (u_m, v_m, w_m, F_m, k_h, \text{ and } k_v)$  and integrate the advection equation (3a) with (3b) forward in time from  $t = 0$  to  $T$ . Store the computed field.
- 2) Calculate the cost function using Eqs. (1), (2), (4), (6), (7), and (8) and the fields obtained from step 1.
- 3) Integrate the adjoint equation (16a) backward with (16b) in time from  $t = T$  to 0, and calculate the gradients ( $\partial J / \partial u_m, \partial J / \partial v_m, \partial J / \partial w_m, \partial J / \partial F_m, \partial J / \partial k_h$ , and  $\partial J / \partial k_v$ ) according to Eqs. (10)–(15).
- 4) Use a conjugate gradient or quasi-Newton minimization algorithm (Navon and Legler 1987) to obtain updated values of the control variables,

$$Z_{ijk}^{(n)} = Z_{ijk}^{(n-1)} + \alpha f \left( \frac{\partial J}{\partial Z} \right)_{ijk}, \quad (18)$$

where  $n$  is the number of iterations,  $\alpha$  is the optimal step size obtained by the “line-search” process in optimal control theory (Gill et al. 1981), and  $f(\partial J/\partial Z)_{ijk}$  is the optimal descent direction obtained by combining the gradients from several former iterations.

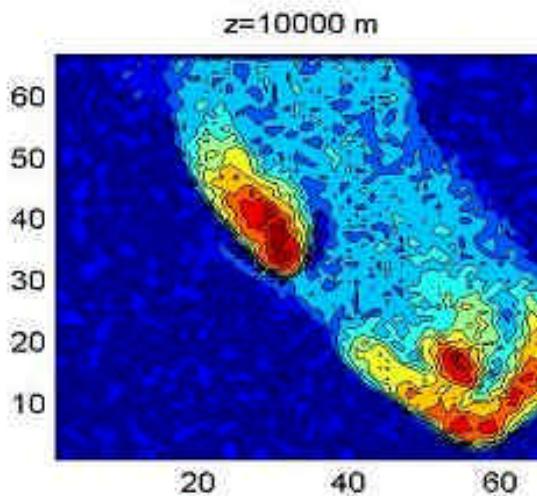
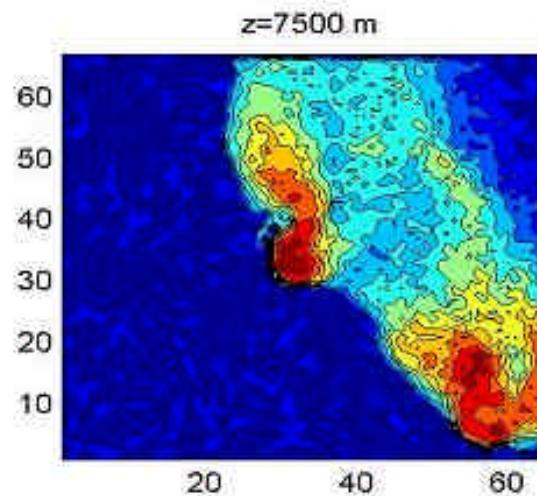
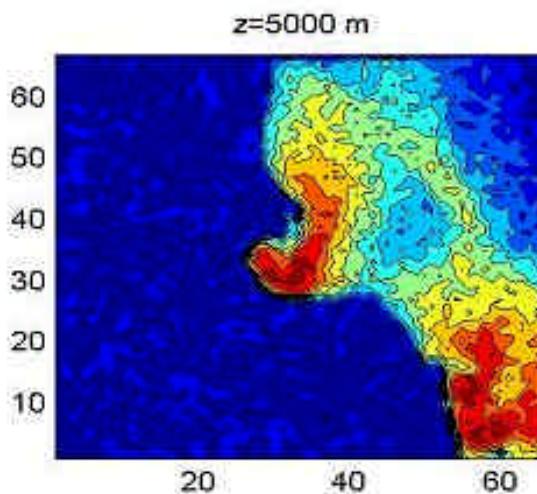
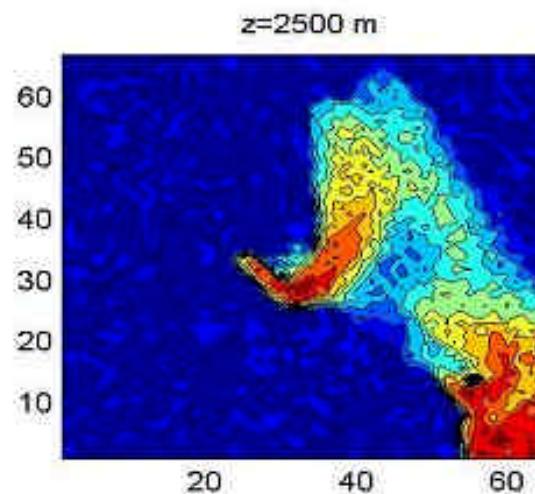
- 5) Check whether the optimal solution has been found by computing the norm of the gradients or the value of  $J$  to see if they are less than a prescribed tolerance. If the criteria are satisfied, stop iterating and output the optimal control vector ( $u_m$ ,  $v_m$ ,  $w_m$ ,  $F_m$ ,  $k_h$ , and  $k_v$ ).
- 6) If the convergence criterion is not satisfied, steps 2 through 5 are repeated using updated values of ( $u_m$ ,  $v_m$ ,  $w_m$ ,  $F_m$ ,  $k_h$ , and  $k_v$ ) as the new guess. The iteration process is continued until a suitable converged solution is found.

# Reflectivity generated by ARPS (Advanced Regional Prediction System ) for tornado in Del City, Oklahoma, 20th May 1977.



Reflectivity [dBZ] reference data

# Reflectivity generated by ARPS + 10 dbZ noise



Reflectivity [dBZ] reference data + 10 dBZ noise

## Wind V-component retrieved from reference reflectivity

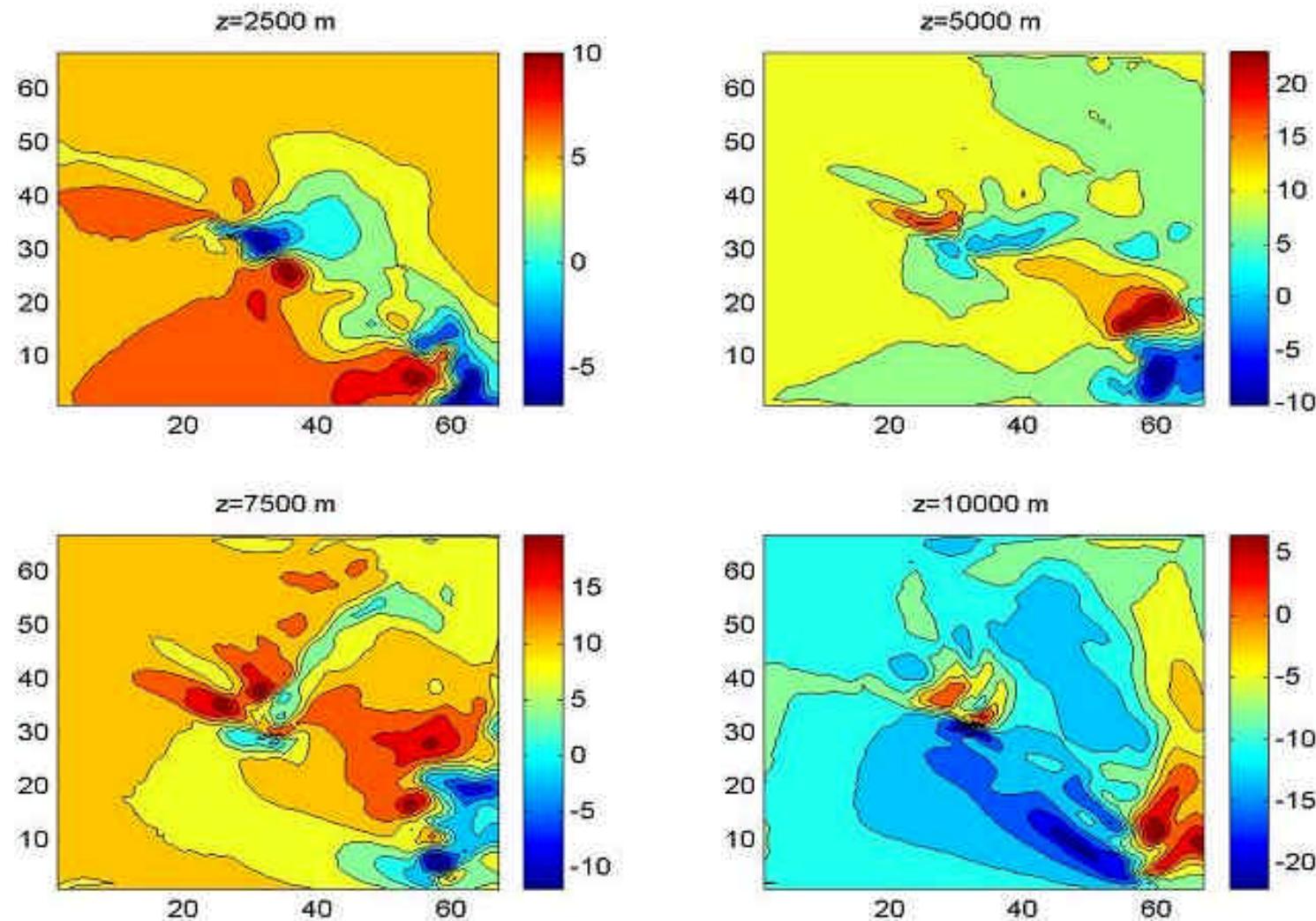


Fig.4. Wind V-component [m/s], reference

## Effect of 10dbZ reflectivity noise on retrieved wind V-component

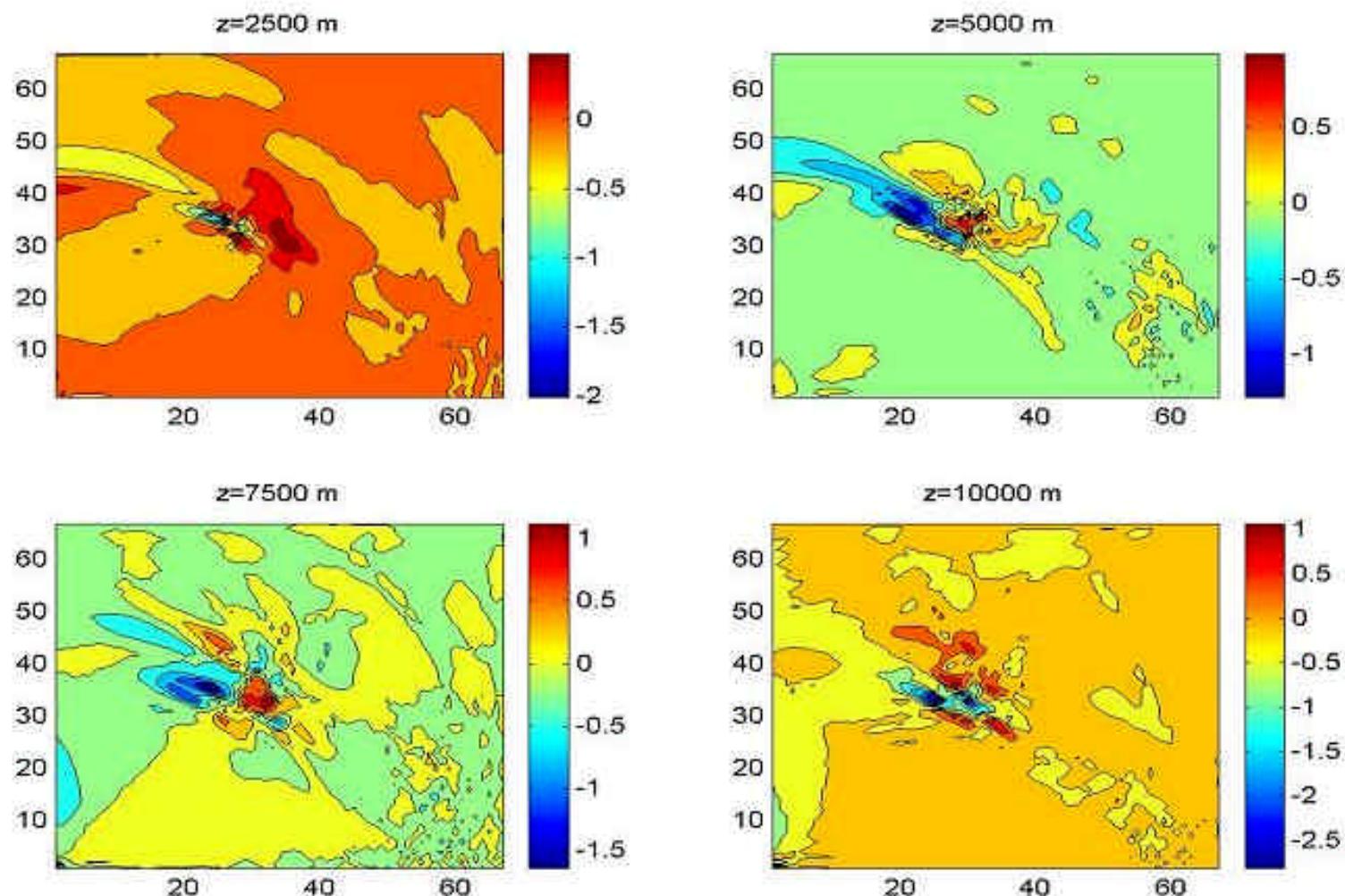


Fig. 6. Effect of 10 dbZ refl. noise on V-component [m/s]

## Effect of 2.5m/s radial noise on wind W-component

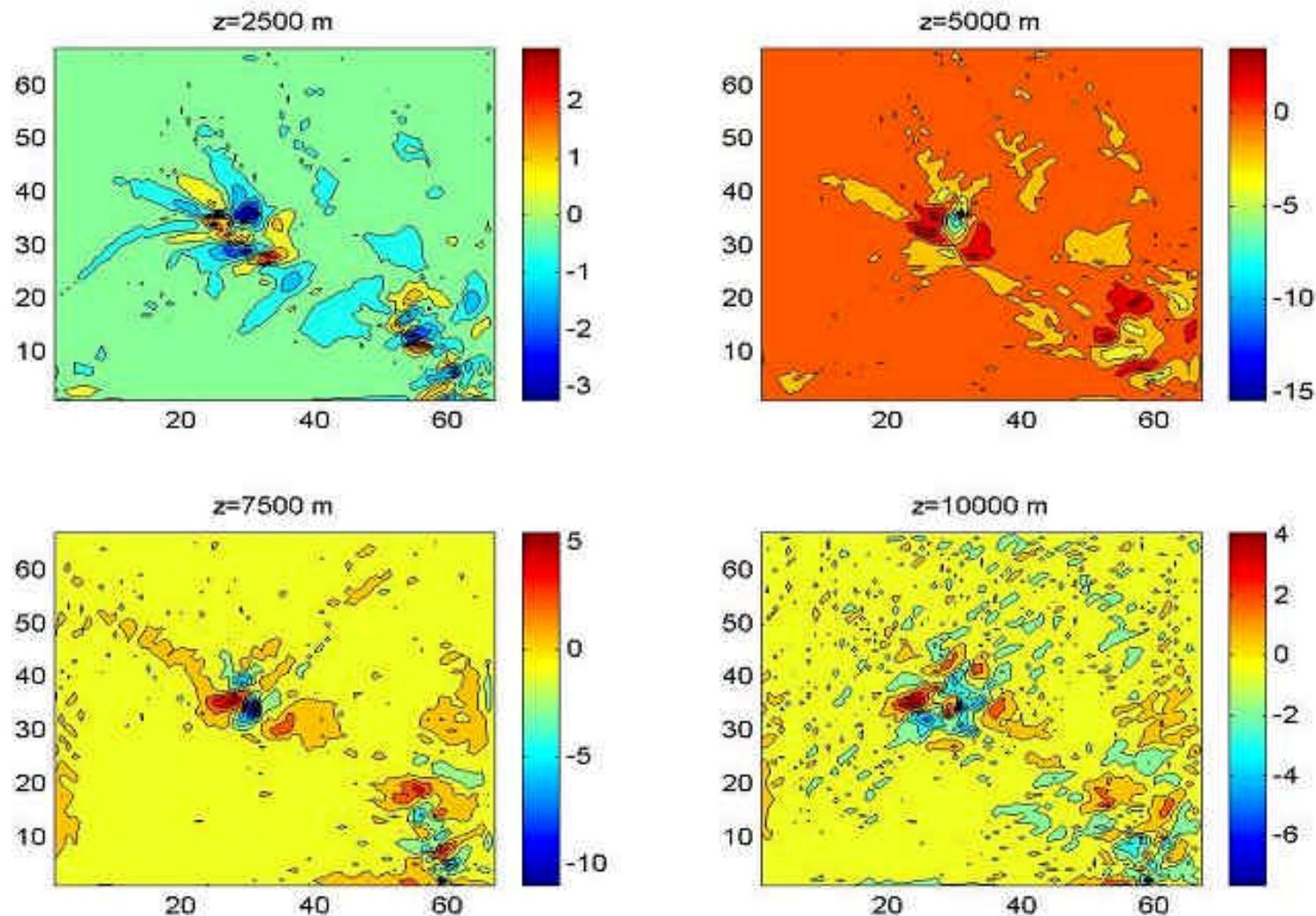


Fig.13 Effect of 2.5 m/s Vr noise on W-component

## Effect of 5m/s radial noise on wind W-component

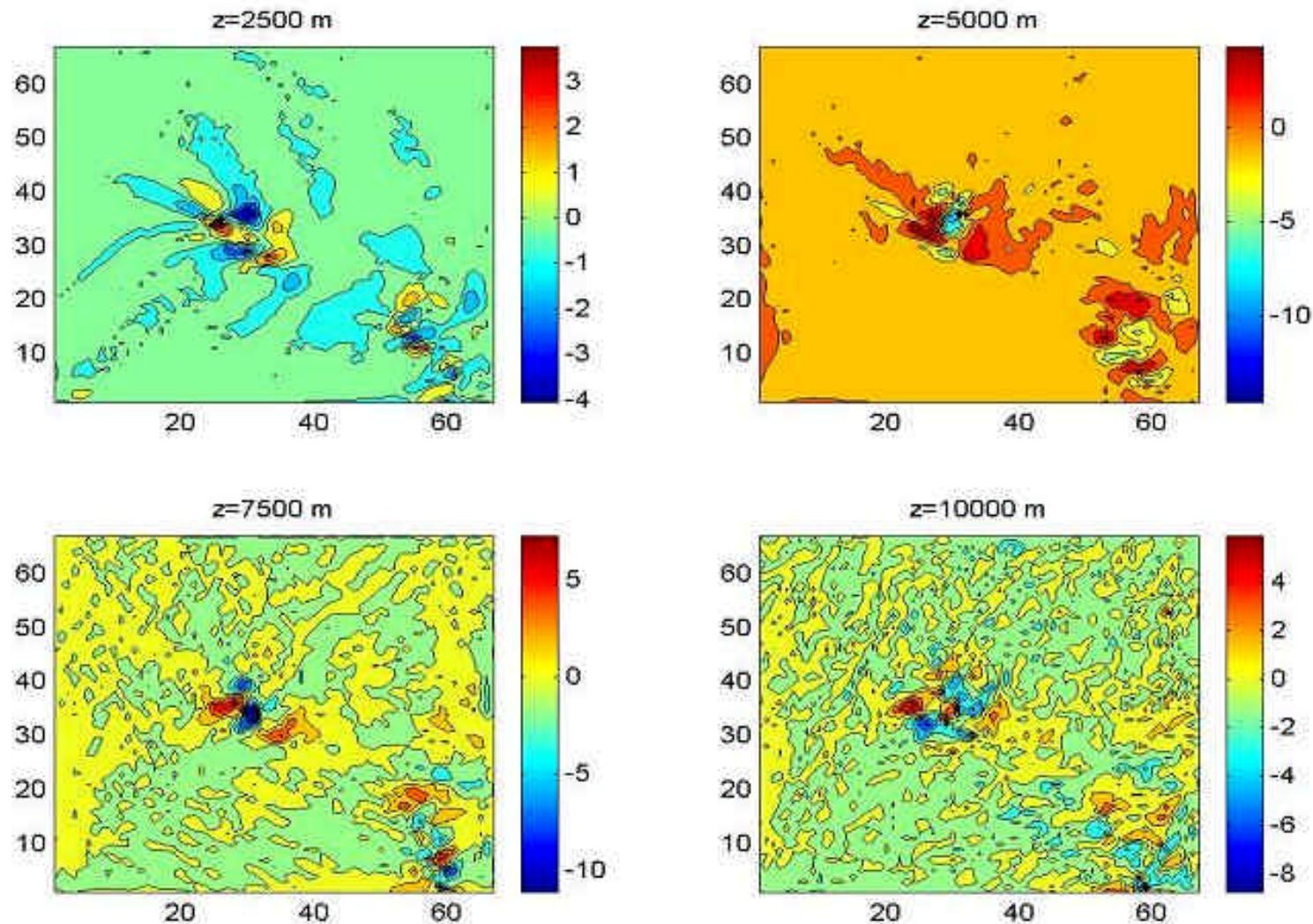
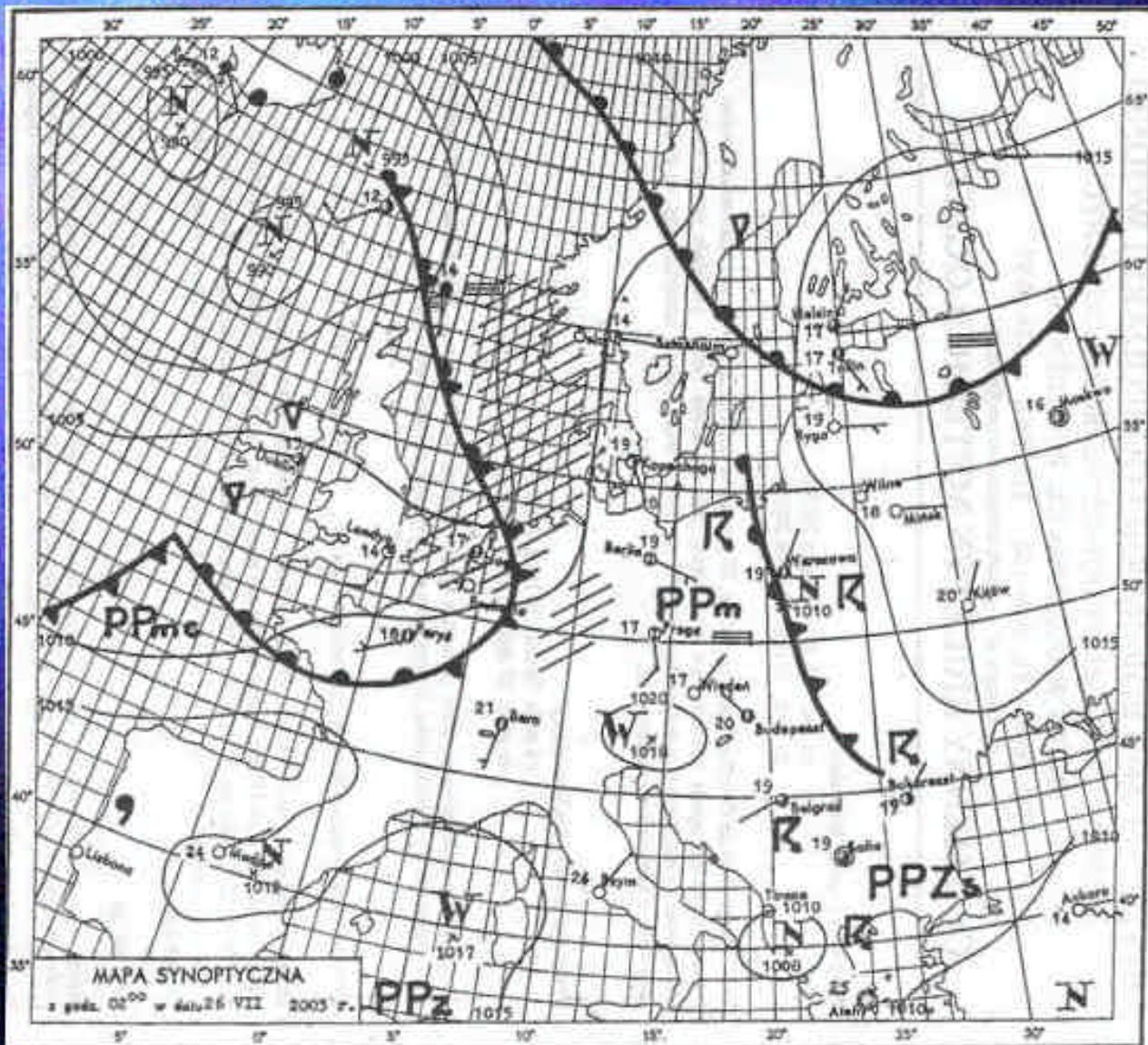


Fig.11. Effect of 5 m/s noise on wind W-component

# Synoptic situation, 26 July 2003 02.00 UTC



## LEGENDA

Rozmieszczenie danych met.  
Temperatura powietrza — TT

Wiatrki met. — ww (wielkość zachmurzenia)  
Wiatrki met. — ww (kierunek wiatru)  
Wiatrki met. — ww (prędkość wiatru)

### Zjawiska meteorologiczne

• deszcz  
• mgła  
• śnieg  
• grad  
■ nagi  
— zmiękczanie  
K burza  
↳ błyścawica  
+ sztorm

▼ opady przelotne  
■ obraz opadów deszczu  
○ obraz opadów śniegu  
○ obraz opadów błyścaw.

### Masy powietrza:

PP — powietrze polarno  
PA — powietrze arktyczne  
PZ — powietrze zwrotnikowe  
m — morskie  
k — kontynentalne  
z — słone, c — słabo

### Wielkość zachmurzenia i prędkość wiatru:

Wielkość zachmurzenia	Prędkość wiatru
0 nista bezchmurna	0 0 m/s
1/8 pokryta niebem	1 1 m/s
2/8	2 2 m/s
3/8	3 3 m/s
4/8	4 4 m/s
5/8	5 5 m/s
6/8	6 6 m/s
7/8	7 7 m/s
8/8 zacumiony	8 8 m/s
niebo niewidoczne	9 9 m/s

### Fronty:

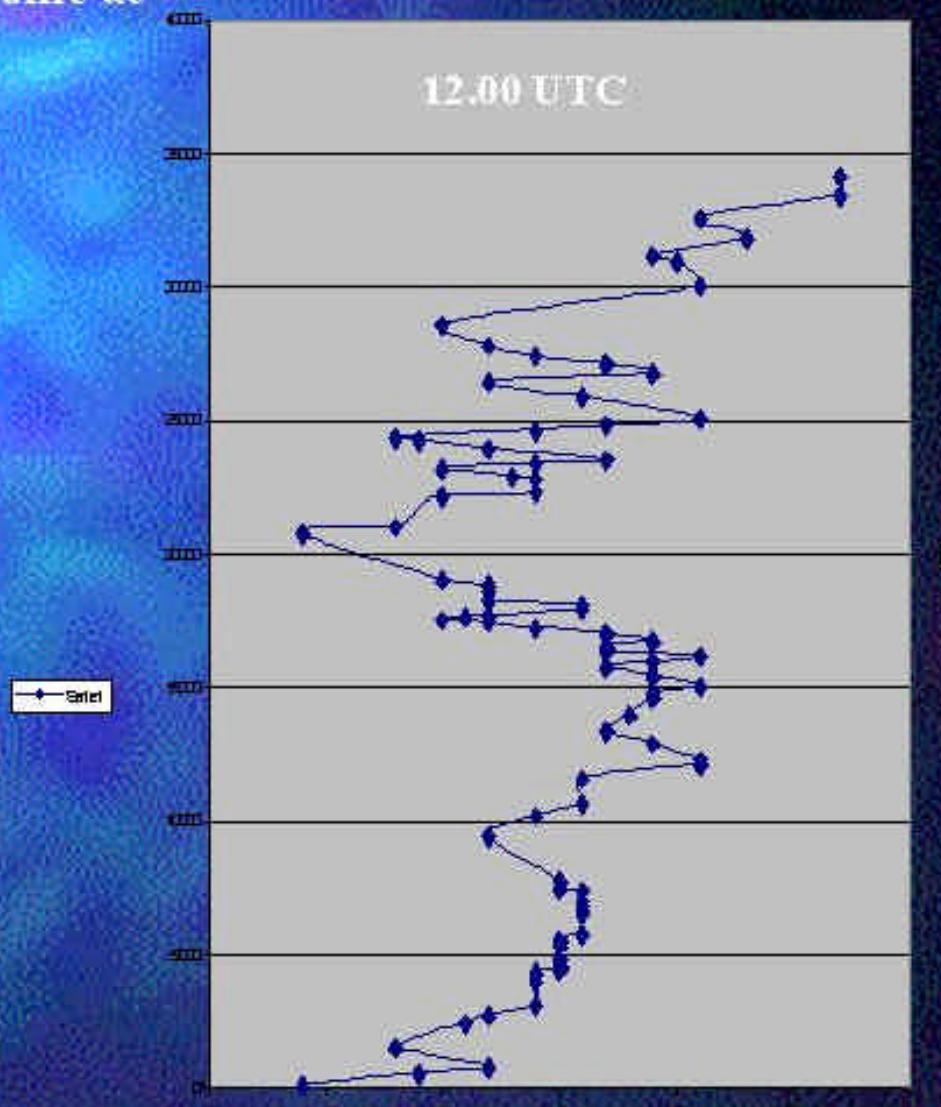
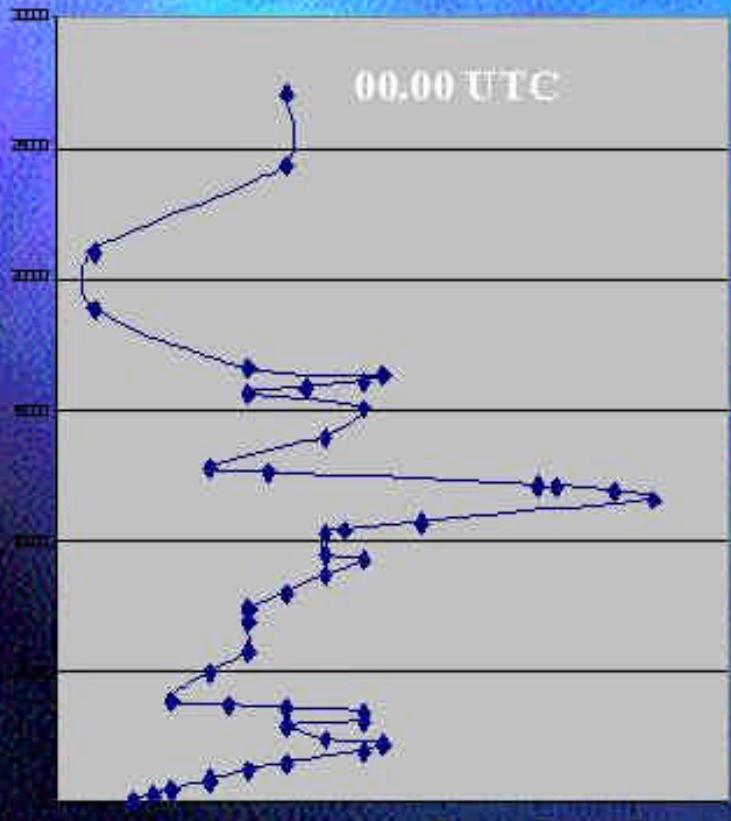
- front zimny
- front chłodny
- front zimnoławowy
- front stacjonarny

### Układy olśnienia:

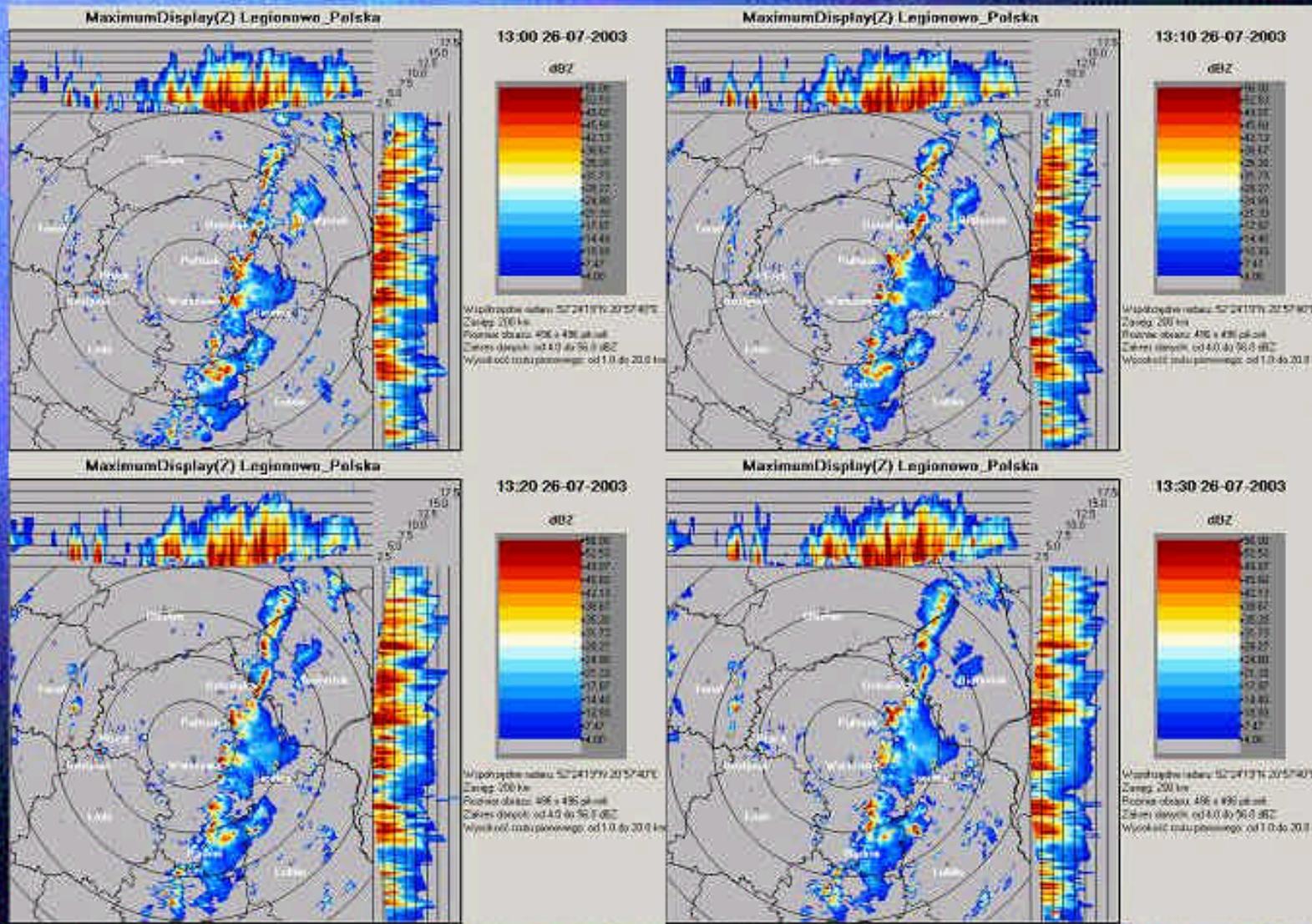
- W — wyl.
- N — niz.
- obraz wifpa

## Wind velocity (knots) - vertical profile at Legionowo, 26.07.2003 r.

Profil wiatru Legionowo 26 lipca godz 00:00

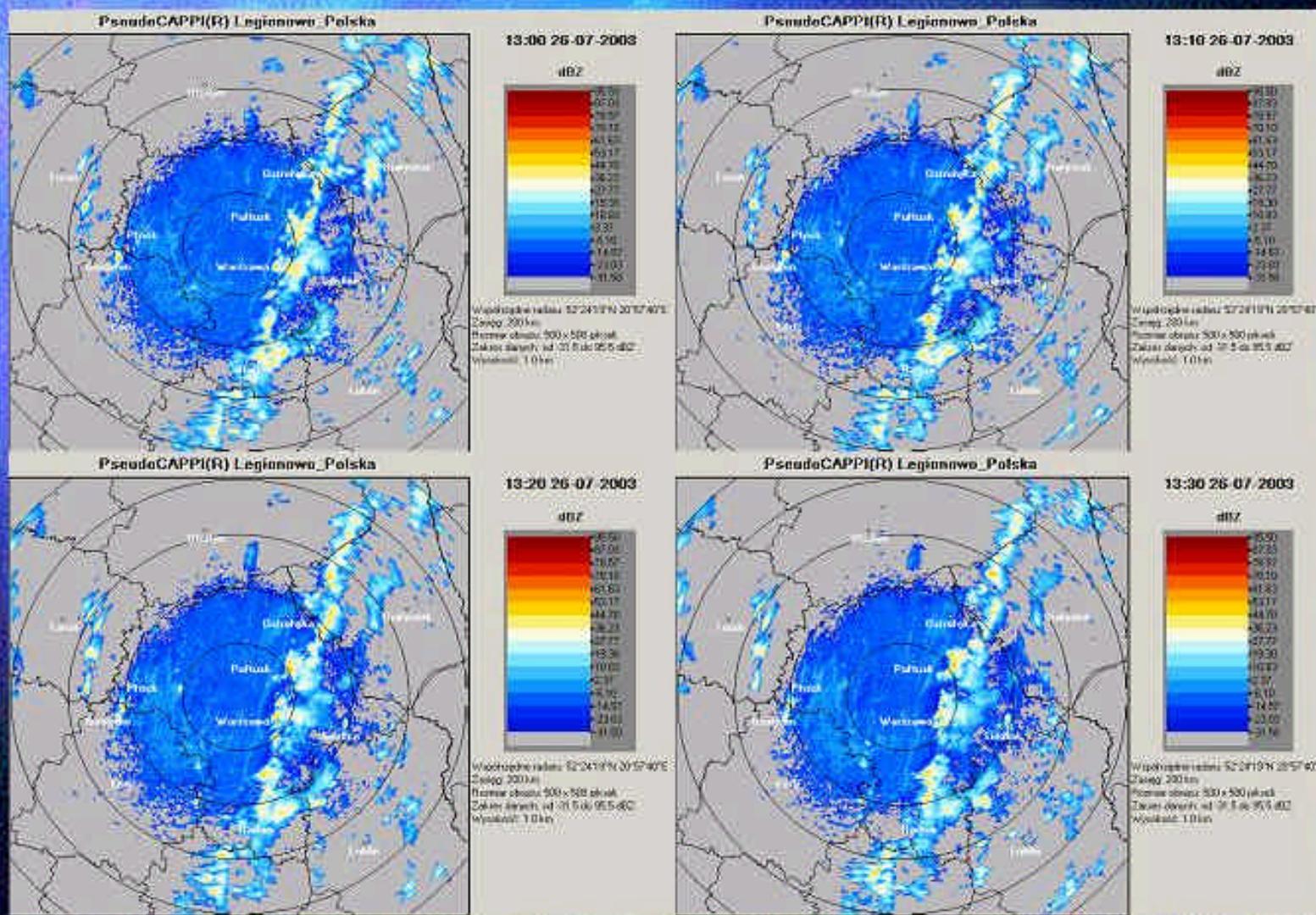


# Projection of 3D maximum reflectivity, Legionowo 26.07.2003- 13.00-13.30 UTC

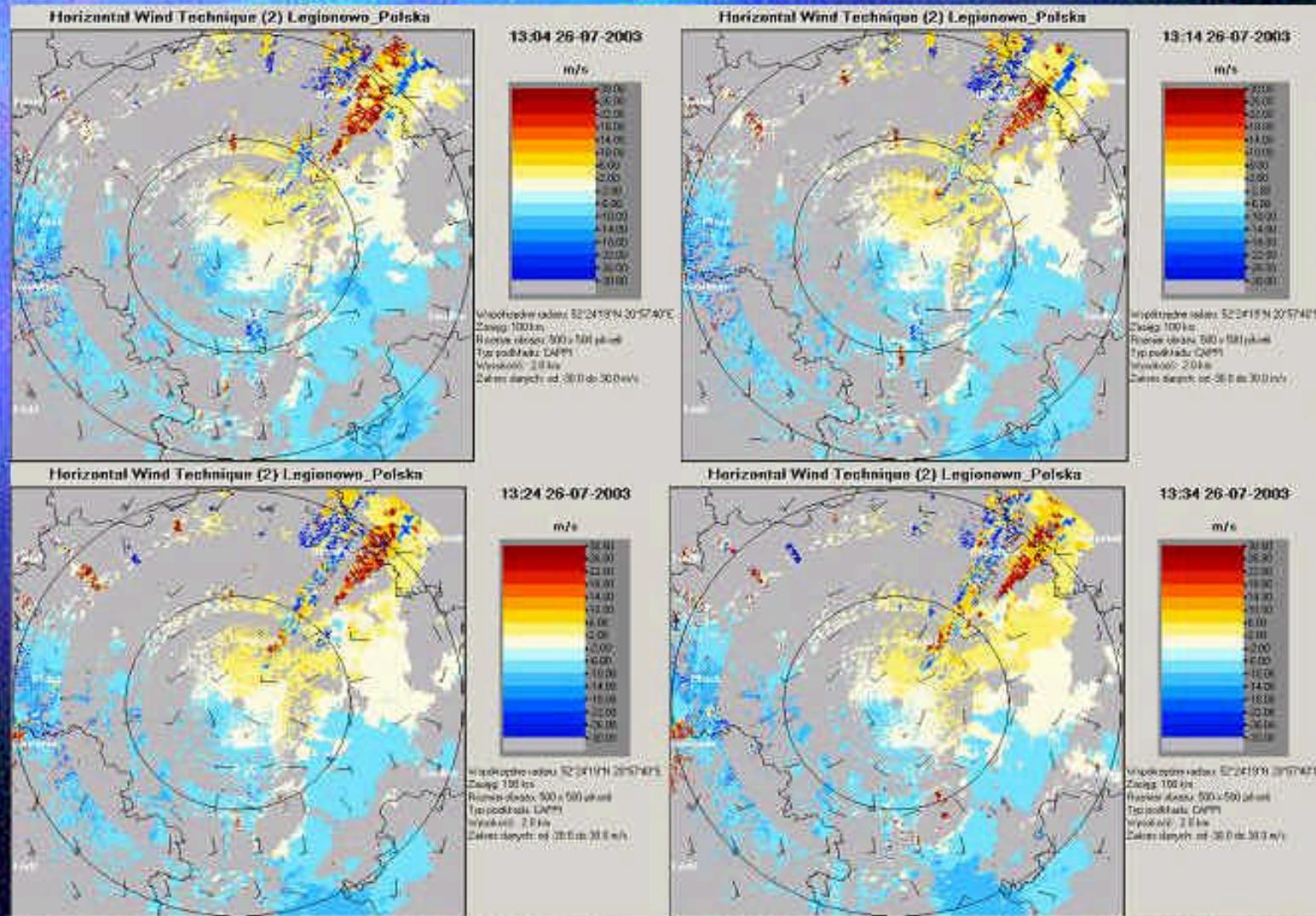


# Horizontal cross-section of reflectivity at 1000m Legionowo

## 26.07.2003- 13.00-13.30 UTC - PCAPPI

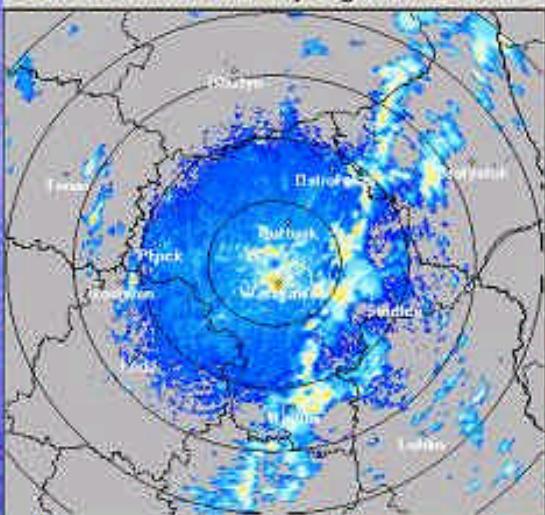


# Horizontal wind vectors on the background of amplitude of radial wind -CAPPI (uniform wind technique) Legionowo 26.07.2003- 13.00-13.30 UTC



# Precipitation intensity at the surface (SRI) Legionowo 26.07.2003- 13.00-13.30 UTC

Surface Rainfall Intensity Legionowo\_Polska

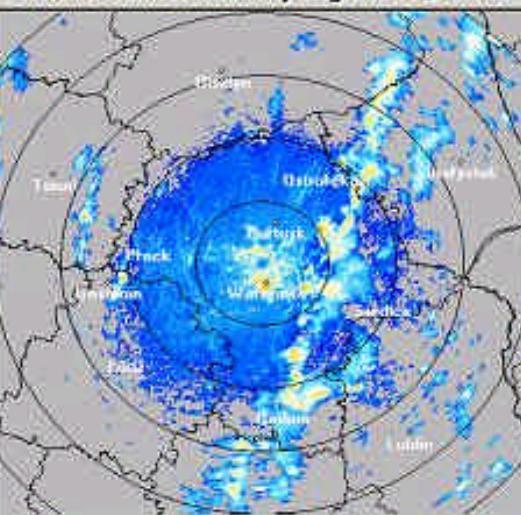


13:00 26-07-2003

dBZ

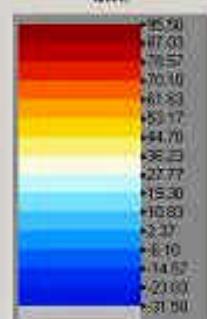


Surface Rainfall Intensity Legionowo\_Polska

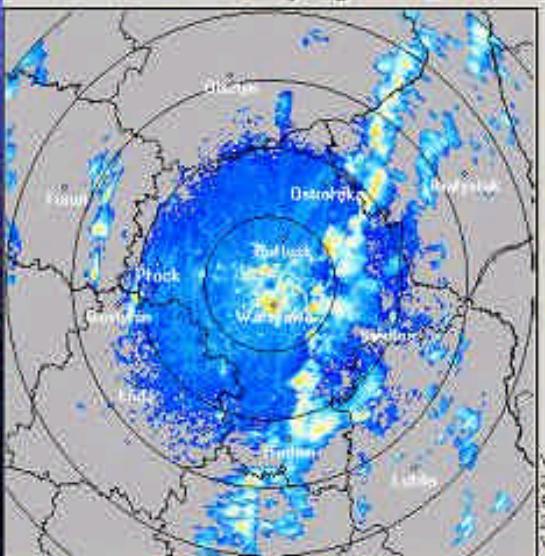


13:10 26-07-2003

dBZ

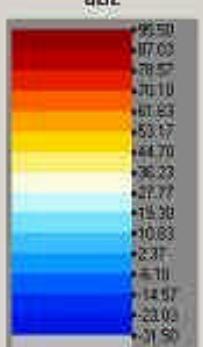


Surface Rainfall Intensity Legionowo\_Polska

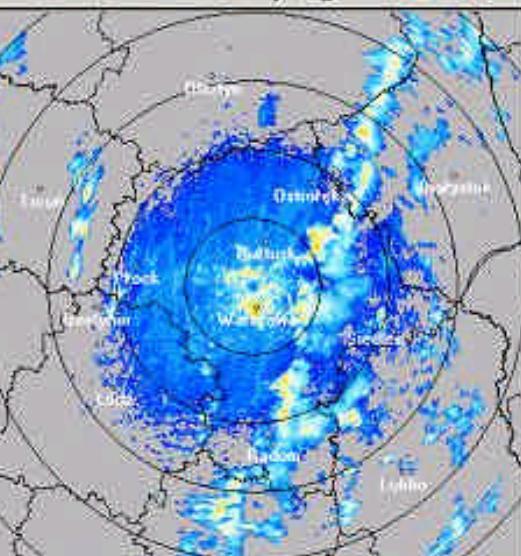


13:20 26-07-2003

dBZ

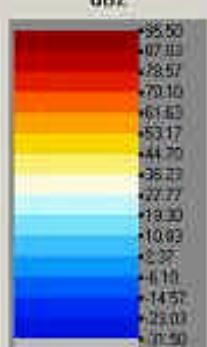


Surface Rainfall Intensity Legionowo\_Polska

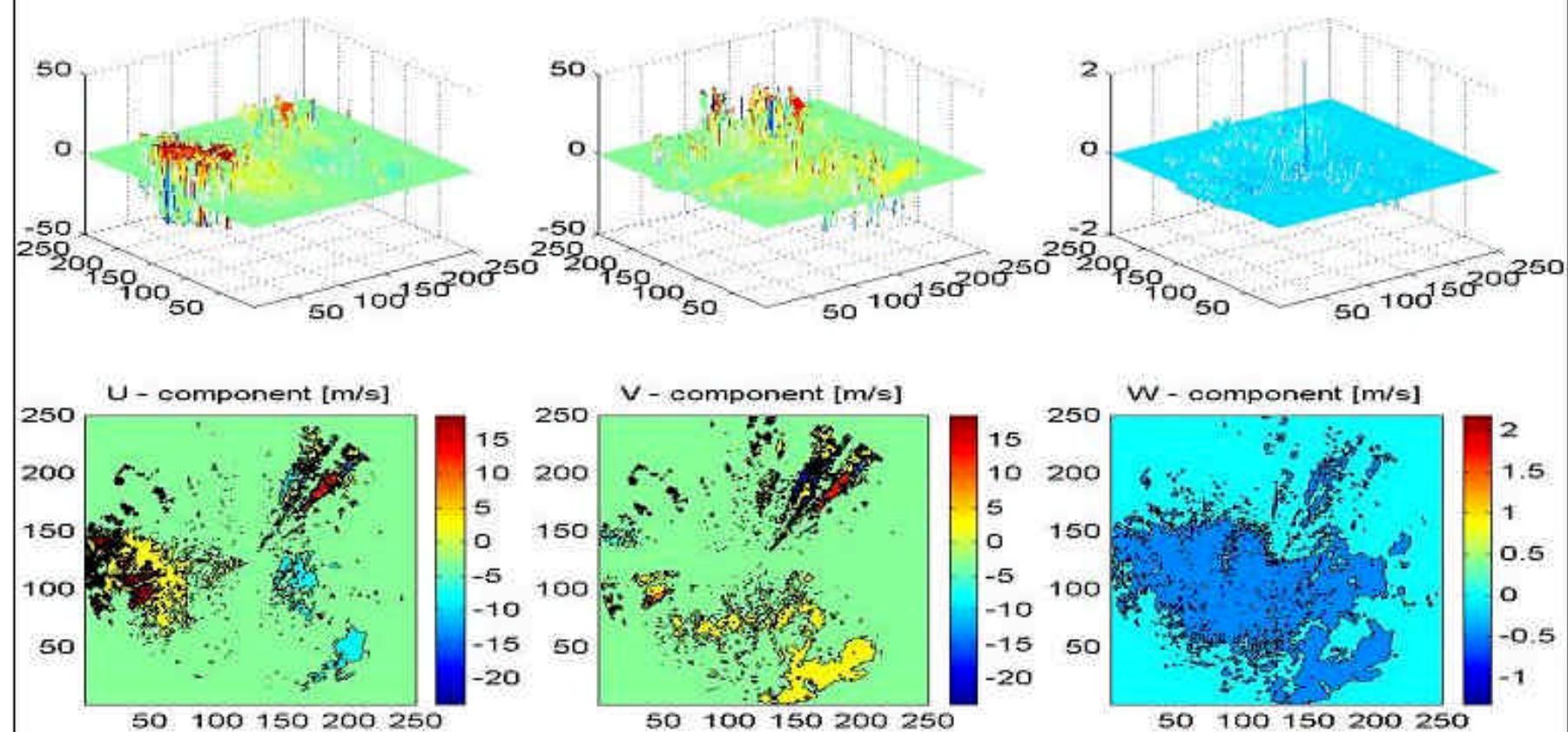


13:30 26-07-2003

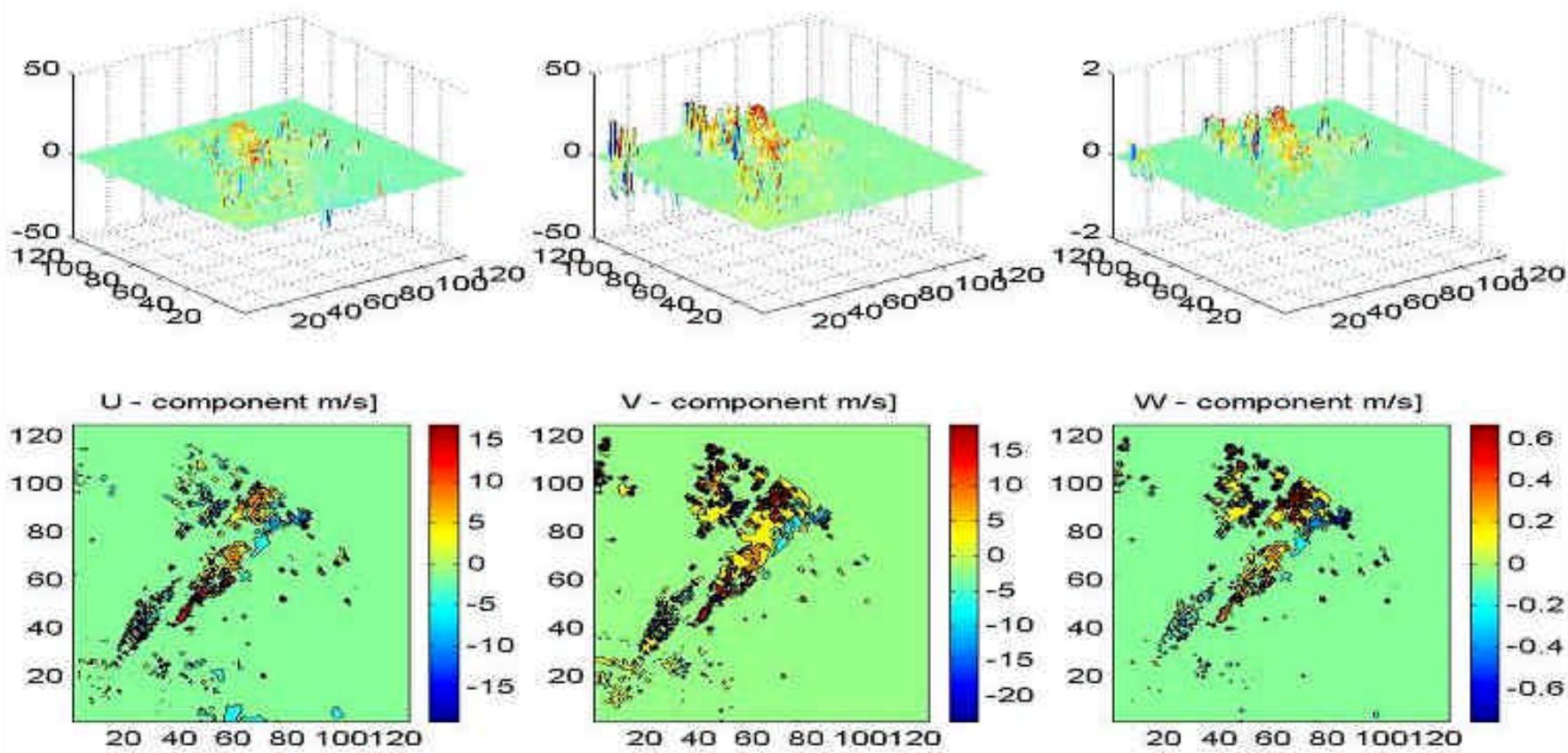
dBZ

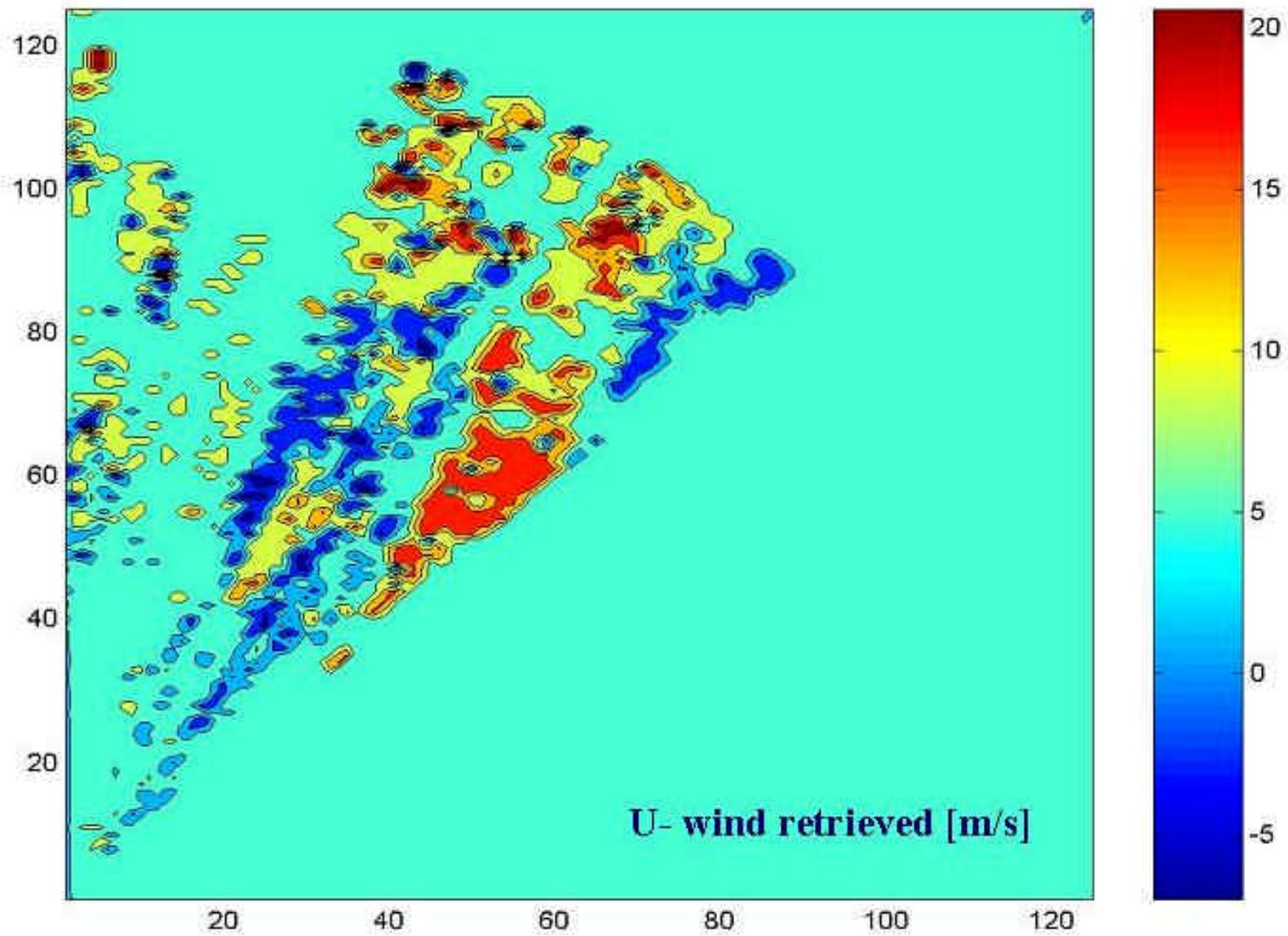


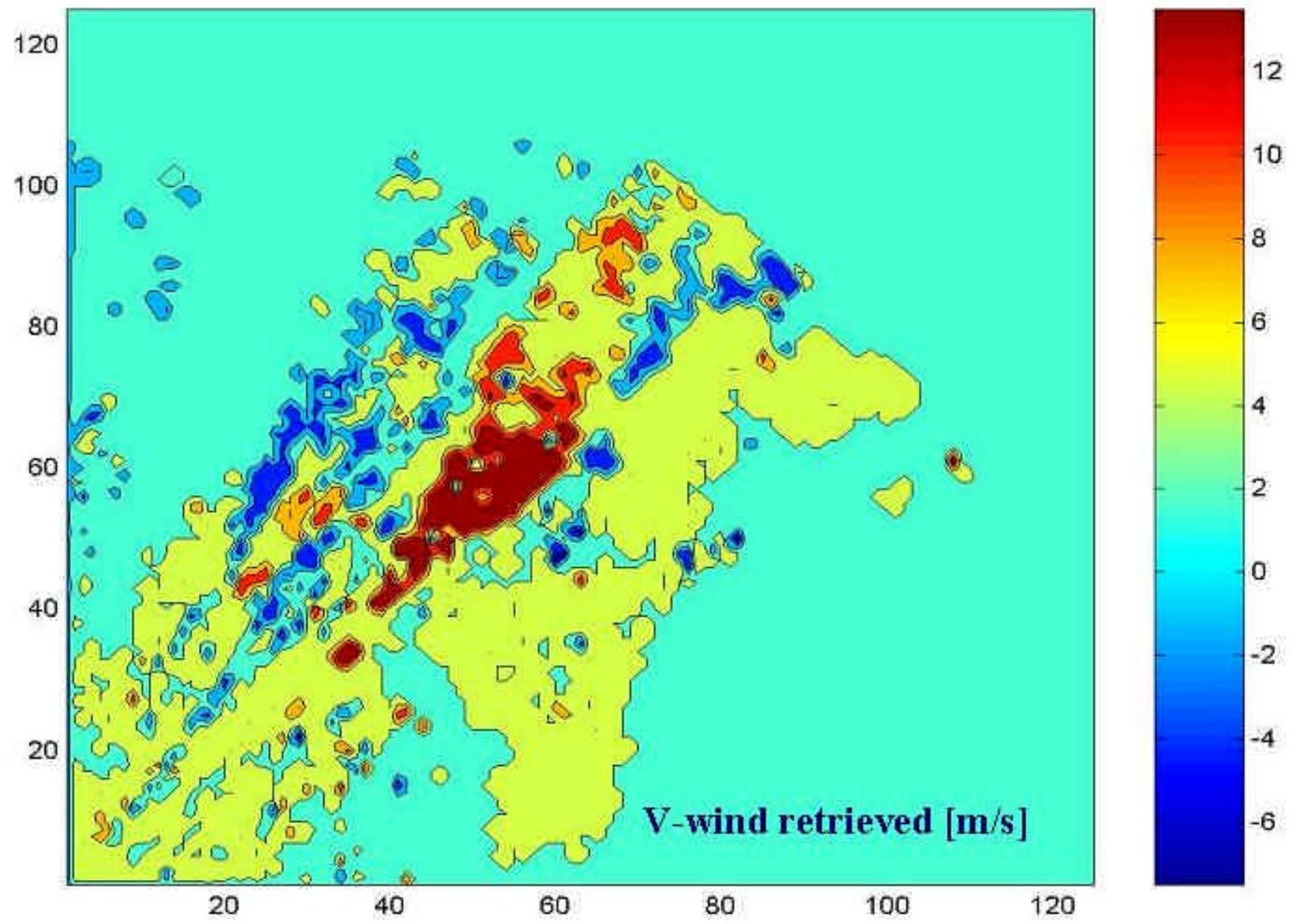
# Decomposition of radial wind component into Cartesian Legionowo 26.07.2003, 13.14 UTC- level 1000 m - PCAPPI

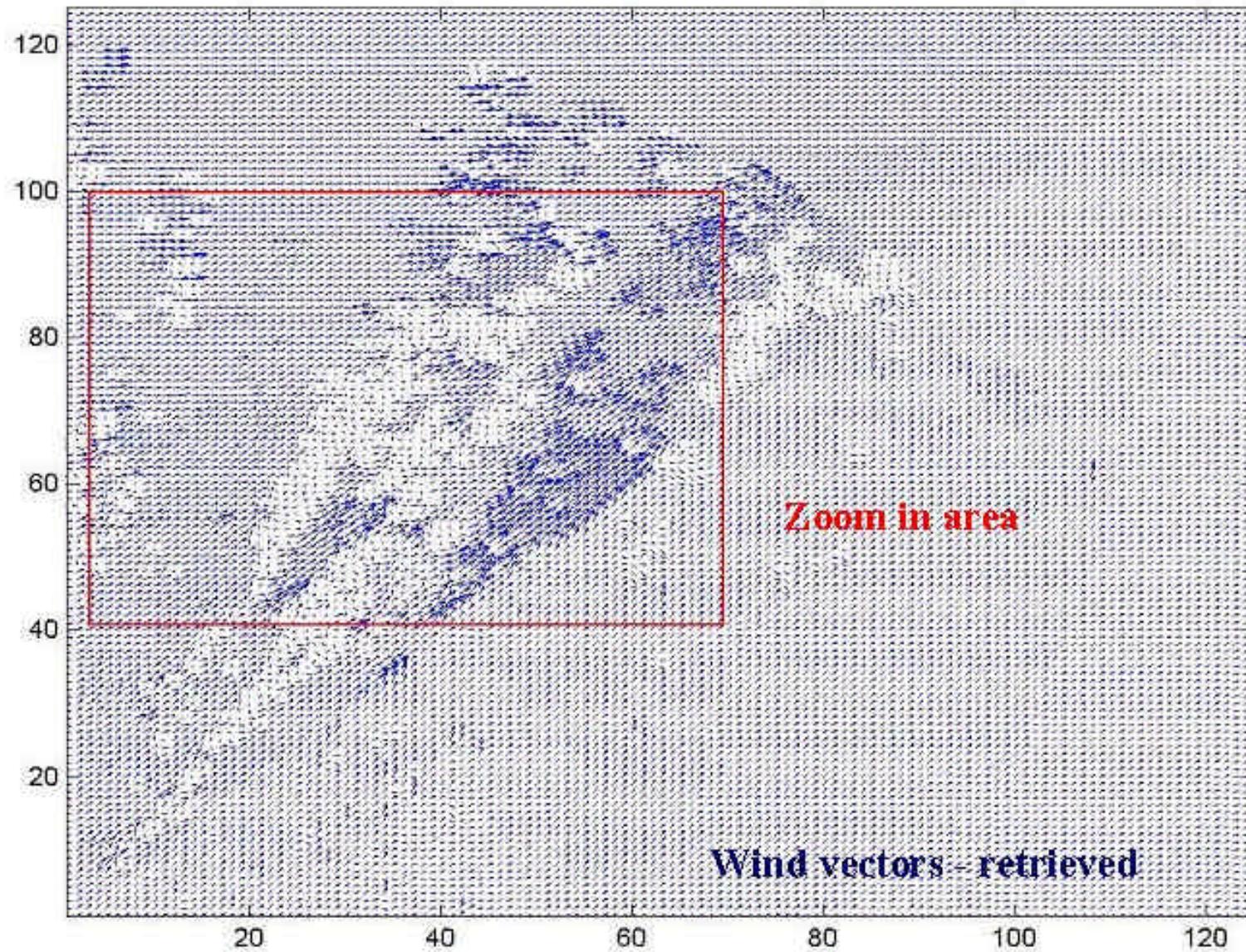


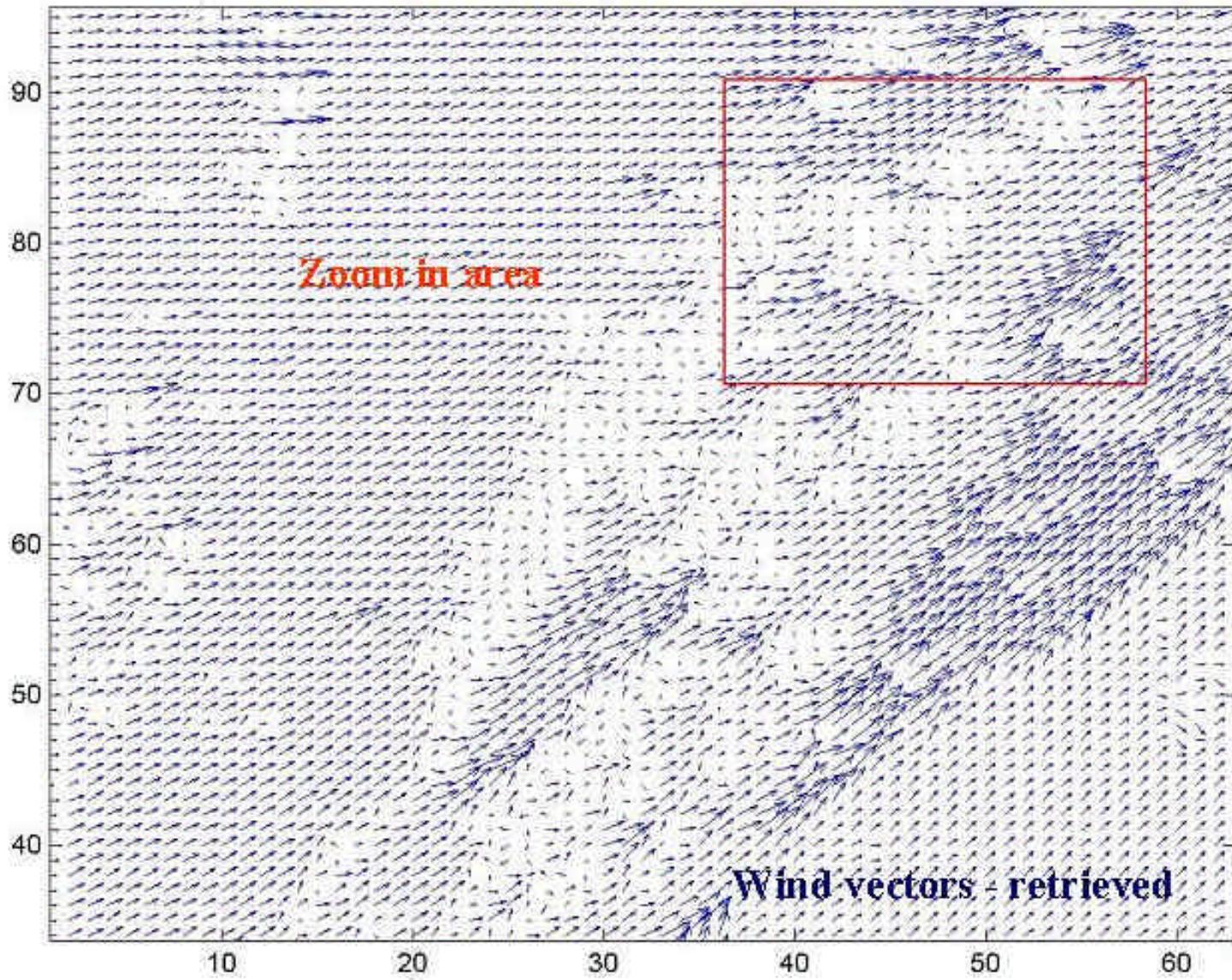
# Decomposition of radial wind component into Cartesian Legionowo 26.07.2003, 13.14 UTC- level 2000 m- PCAPPI











# Conclusions

- Variational method of reconstruction of 3D wind field (Gao *et al.*) based on the radar data (reflectivity and/or radial component) gives good results for input data produced in model ARPS.
  - Method seems to be stable with respect to reflectivity errors (eg. Noise) significantly more than to radial component errors.
  - It pertains especially to wind W-component. This is very important in case of description of convection.
  - For Polish radars (PolRad) this method requires also additional filters and/or interpolation techniques to establish continuity of analyzed fields
- Both CAPPI and PCAPPI cannot establish an optimum input data for reconstruction due to interpolation to Cartesian coordinates.