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# LHN in ICON-LAM

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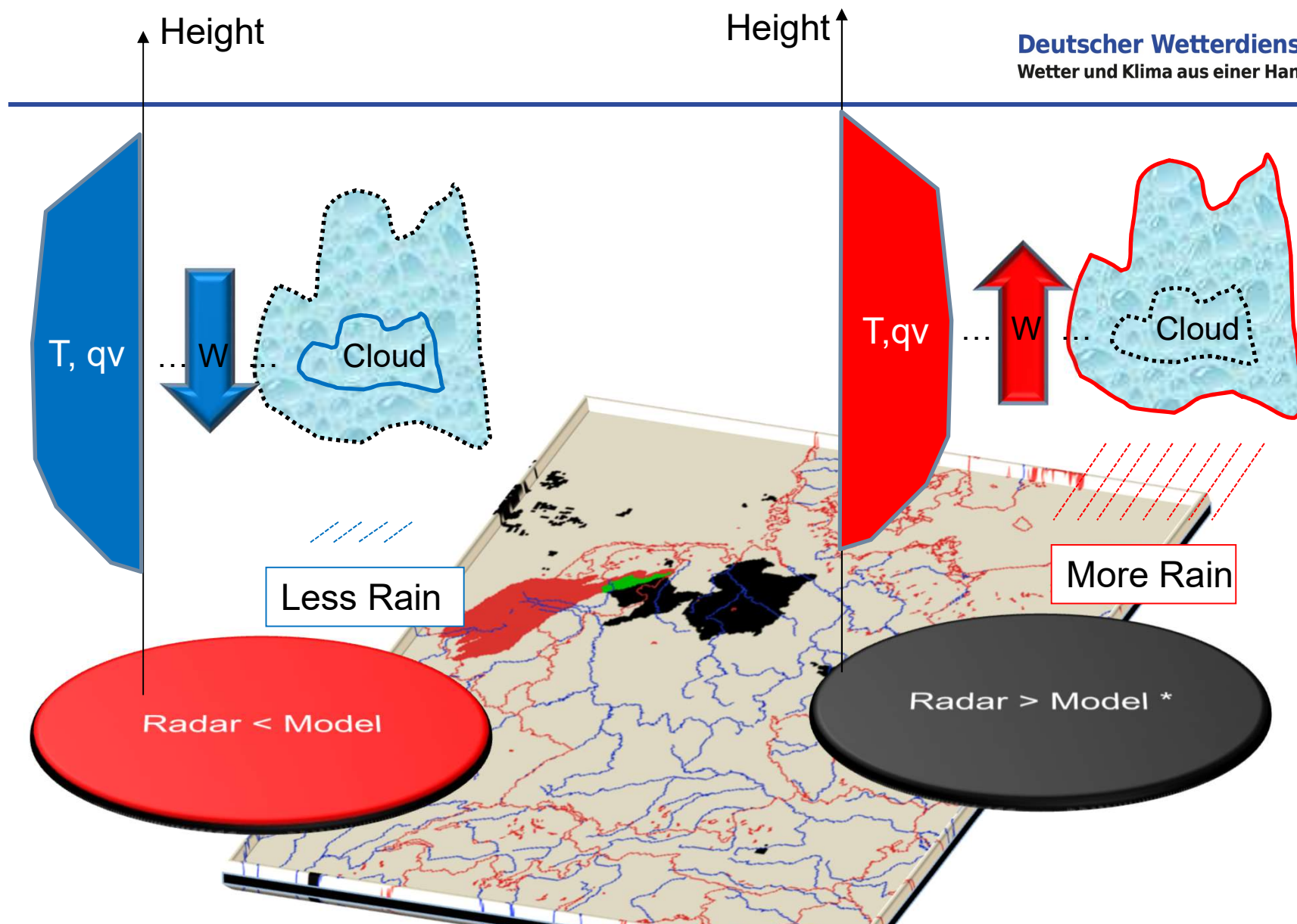
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## Outline

- Motivation and brief description of LHN
- Technical aspects for applying LHN
- Pro & Cons of LHN concerning ICON-LAM
- (OPERA)

## Motivation

- Apart from assimilation of 3d radar reflectivity and radial winds a 2d composite of radar derived precipitation is assimilated via latent heat nudging.
  
- Pro:
  - not all 3d volume data are available yet, at least for German model domain
  - LHN triggers cells in the entire ensemble and therefore helps assimilating 3d volume data
  - LHN corrects amount of precipitation within the model, avoiding a drying out
  
- Cons:
  - LHN adopts the dynamical structure during assimilation, but may lead to imbalances which may lead to spin down effects and different model bias
  - Radar observation error are almost not accounted for



\* If model has no suitable precipitation at the target grid point, a more suitable nearby grid point is searched (COSMO).

If no point can be found, an artificial temperature profile is used for the scaling.

# Latent Heat Nudging

## Basic Assumptions:

- vertically integrated latent heat release  $\propto$  vertically integrated precipitation flux within each model column
- relation is similar in model and nature
- relation is linear and constant in any meteorological situation

$$T_{LH,obs} = RR_{obs} \frac{T_{LH,mod}}{RR_{mod}} = \frac{RR_{obs}}{RR_{mod}} T_{LH,mod} = \beta T_{LH,mod}$$

$$\frac{\partial T}{\partial t} = F(X, t) + \alpha (T_{LH,obs} - T_{LH,mod}) = F(X, t) + \alpha (RR_{obs} - RR_{mod}) \frac{T_{LH,mod}}{RR_{mod}}$$

In addition increments of specific humidity are added (optionally but recommended) to remain relative humidity constant (*lhn\_hum\_adj*)



- LHN is applied at **any integration step** between (*nlhn\_start* and *nlhn\_end*)
- $T_{LH,mod}$  is collected from **all processes associated with latent heat release** within every integration time step, separately.
- $\alpha$ : nudging coefficient (*lhn\_coef*), which decides how much of the increment is added. Setting to „0“ means no increment is added, but all monitoring is available
- $\beta$ : ratio between observed precipitation and a model equivalent ( $RR_{mod}$ ).  $RR_{mod}$  can be surface precipitation or a **vertical mean of the precipitation flux** (*lhn\_qrs*). This accounted for temporal evolution of precipitation within model column. The extent of the vertical average is a tuning property (*rqrsgmax*). We have to avoid a bias between this equivalent and the model precipitation itself.
- $\beta$  will be limited by *fac\_lhn\_up* and *fac\_lhn\_down*. As closer  $\beta$  is limited too 1 as lower an increment will be.
- We recommend to restrict increments to model levels, showing a **positive latent heat release** (*lhn\_incloud*)
- The increment itself can also be limited by *abs\_lhn\_lim* and *lhn\_limit*.

- In case of **too little precipitation** simulated, an artificial temperature profile can be applied (*lhn\_artif*, *tt\_artif\_max*, *zlev\_artif\_max*, *std\_artif\_max*).
  - In **COSMO** still a **searching for a more suitable neighbouring grid point** will be applied first (*lhn\_search*)
- Take into account **only moisture increments** (*lhn\_no\_ttemp*)
- Take into account **only artificial temperature profile** (*lhn\_artif\_only*)
- Scale ***abs\_lhn\_lim*** with height using a Gaussian function (same function as defined for artificial temperature profile) by ***lhn\_limitp*** instead of ***lhn\_limit***
- LHN routine may provide **more diagnostic output** (*lhn\_diag*) within YULHN (COSMO) or *lhn.log* (ICON). Herein also an **online verification** against the radar data can be provided between ***nlhnverif\_start*** and ***nlhnverif\_end***.

- Radar data has to be **interpolated to model grid** (i.e. aggregation in space). Both radar and model can be **smoothed spatially** (*lhn\_relax, nlhn\_relax*)
- Radar data are **interpolated in time** between observations (observation frequency has to be specified by *lhn\_dt\_obs*)
- A **detection for bright band** can be applied, when a radar height information is given. (*lhn\_bright, height\_file*)
- A **blacklist** file can be applied (*lhn\_black, blacklist\_file*). This blacklist can be obtained by comparison against satellite products
- A **spatial quality index** can be applied (*lhn\_squal*, not tested yet in ICON). The quality index has to be included within the *radardata\_file* and is prepared in pre processing quality control



## → Pro:

- LHN corrects amount of precipitation within the model, avoiding a drying out of the soil
- not all 3d volume data are applicable yet, at least for German model domain
- LHN triggers cells in the entire ensemble and therefore helps assimilating 3d volume data

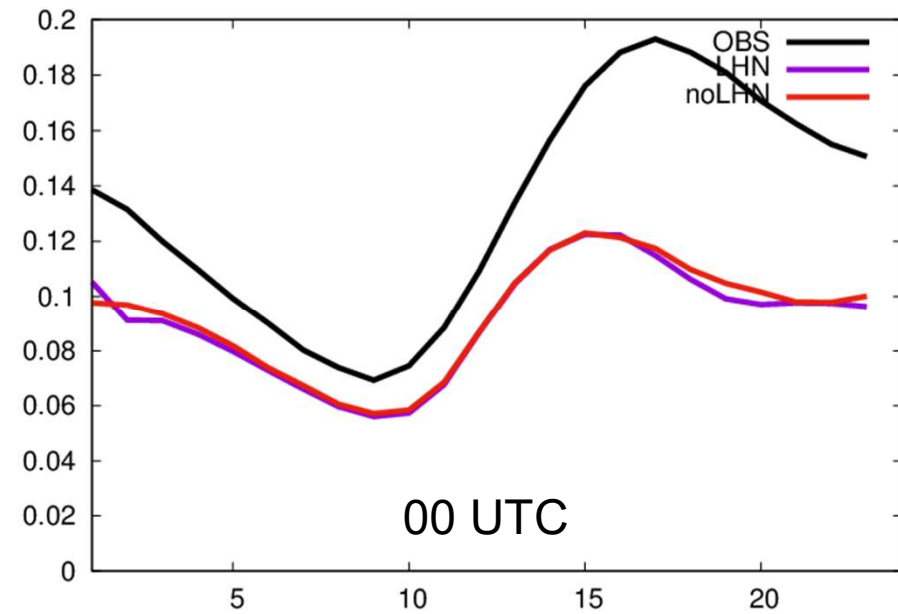
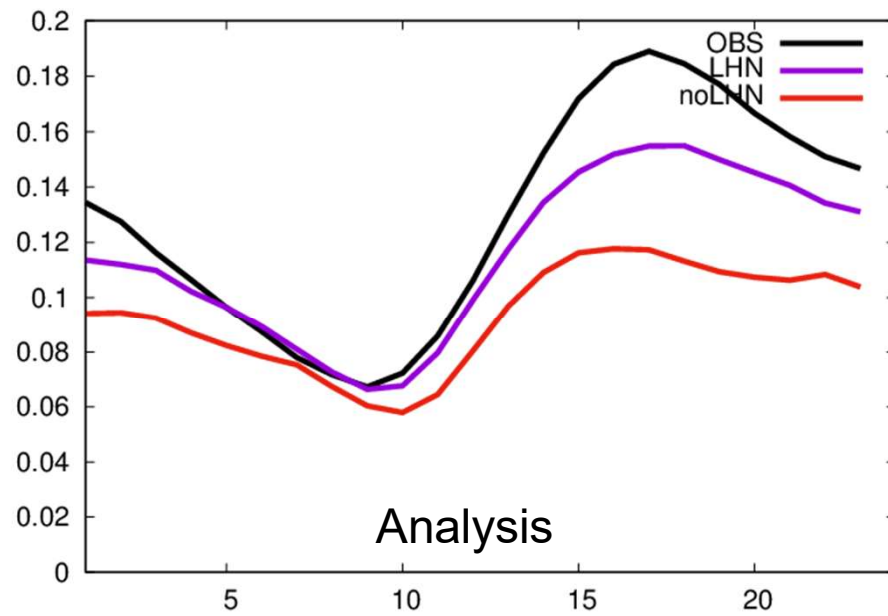
## → Cons:

- LHN adopts the dynamical structure during assimilation, but may lead to imbalances which may lead to spin down effects and different model bias
- Radar observation error are almost not accounted for

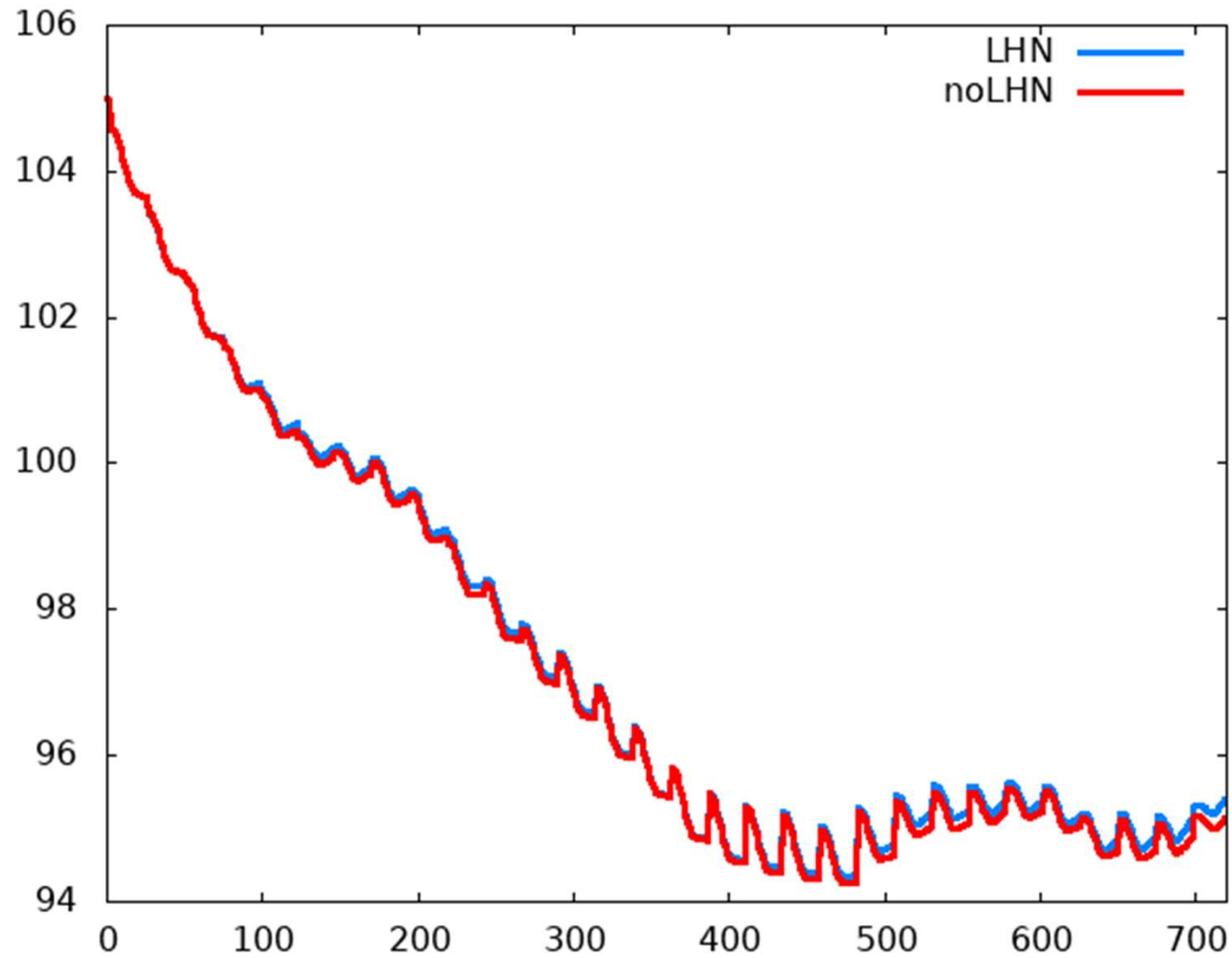
## → **Comparison of two experiments, with and without LHN for June 2021**

- Other setup very close to operational setup.

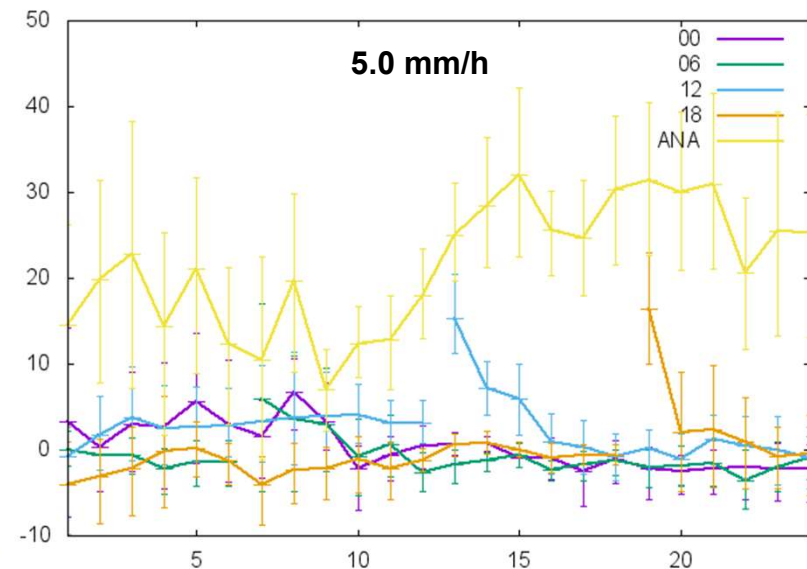
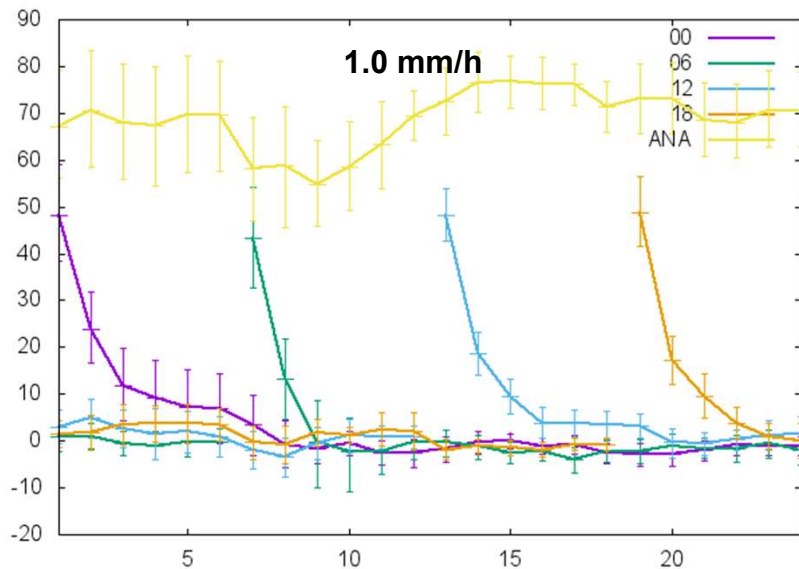
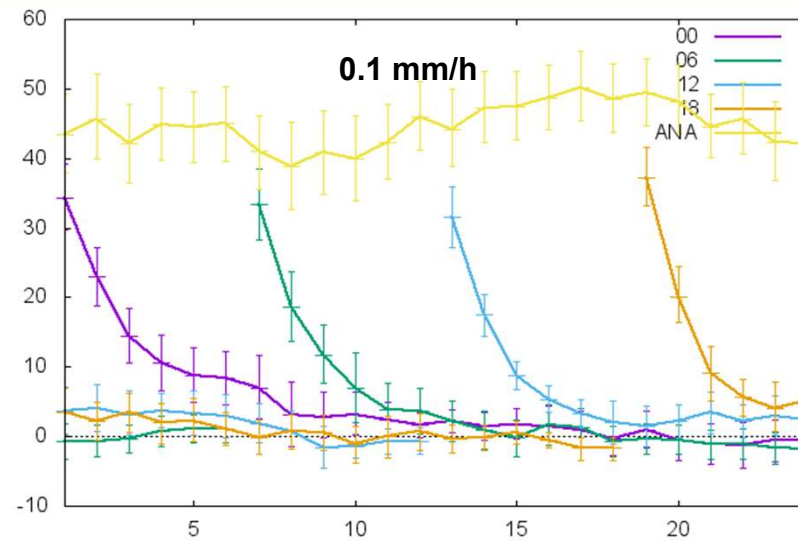
# Correction of precipitation amount

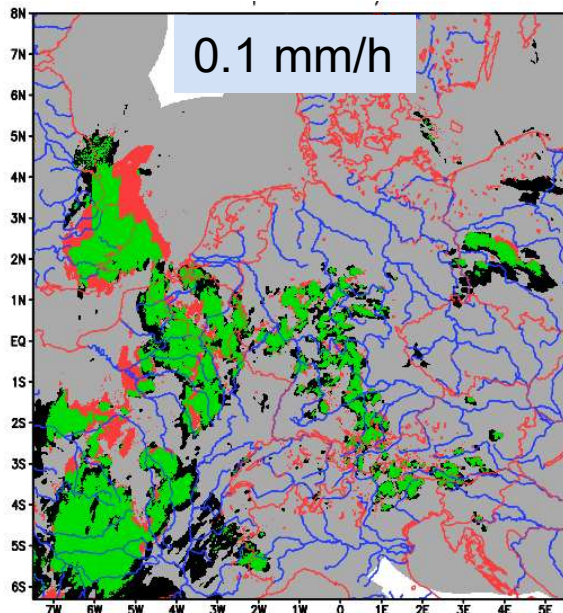


# Influence on soil moisture (5<sup>th</sup> layer)

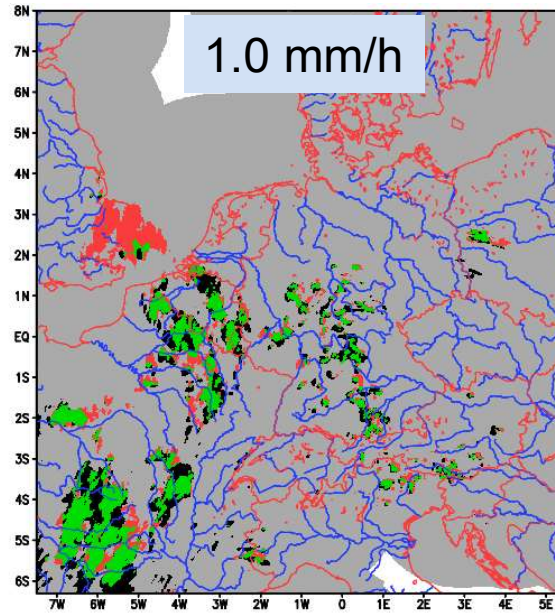


# Improvement in FSS (11 grid points)

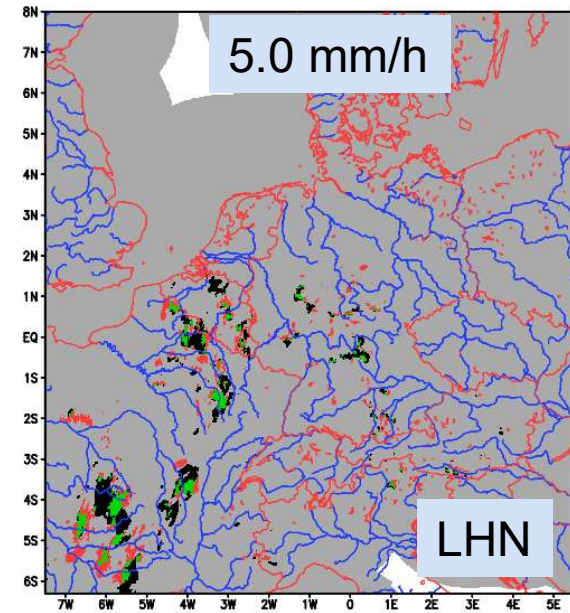




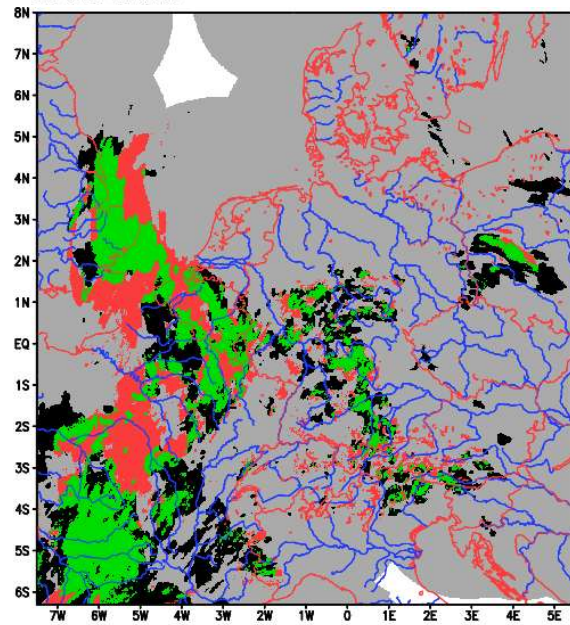
Radar: mean: 0.378 mm/h max: 72.19 mm/h  
 Model: mean: 0.337 mm/h max: 92.50 mm/h  
 missed (black): 33875 false (red): 16772 hits (green): 50249  
 ETS: 0.428 FBI: 0.796



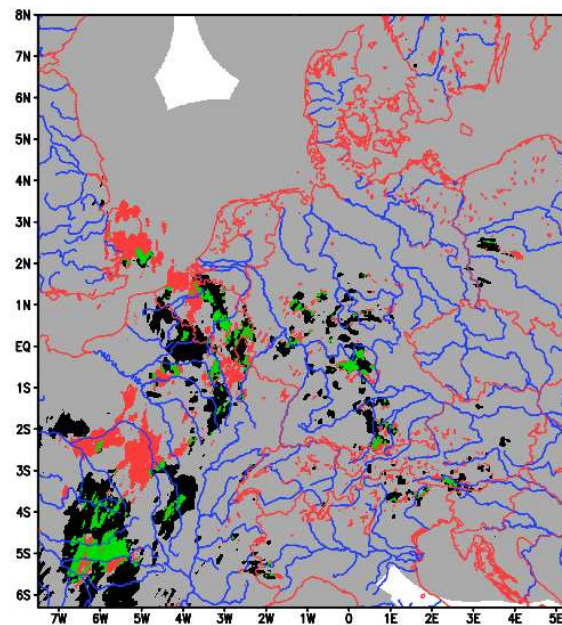
Radar: mean: 0.333 mm/h max: 72.19 mm/h  
 Model: mean: 0.306 mm/h max: 92.50 mm/h  
 missed (black): 14260 false (red): 11907 hits (green): 16832  
 ETS: 0.362 FBI: 0.924



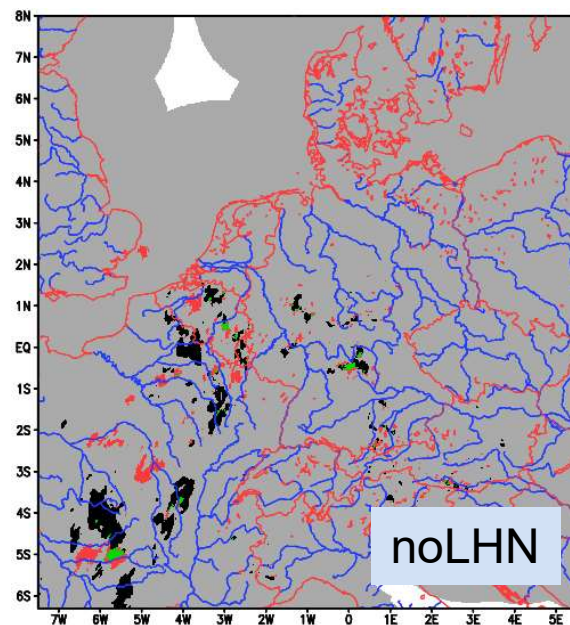
Radar: mean: 0.225 mm/h max: 72.19 mm/h  
 Model: mean: 0.210 mm/h max: 92.50 mm/h  
 missed (black): 6399 false (red): 6589 hits (green): 2828  
 ETS: 0.168 FBI: 1.020



Radar: mean: 0.378 mm/h max: 72.19 mm/h  
 Model: mean: 0.252 mm/h max: 93.63 mm/h  
 missed (black): 43532 false (red): 30343 hits (green): 40592  
 ETS: 0.271 FBI: 0.843



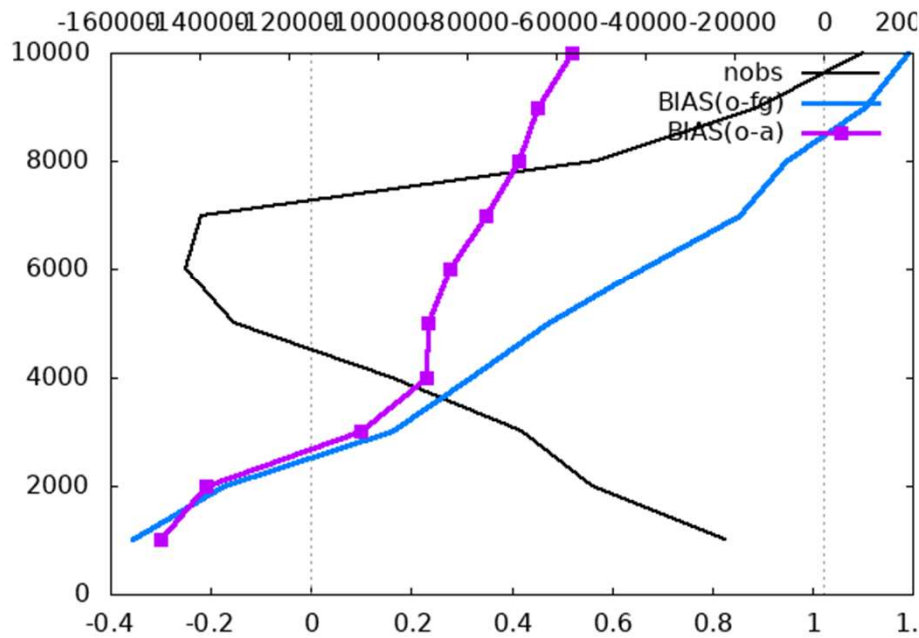
Radar: mean: 0.333 mm/h max: 72.19 mm/h  
 Model: mean: 0.210 mm/h max: 93.63 mm/h  
 missed (black): 24560 false (red): 14489 hits (green): 6532  
 ETS: 0.115 FBI: 0.676



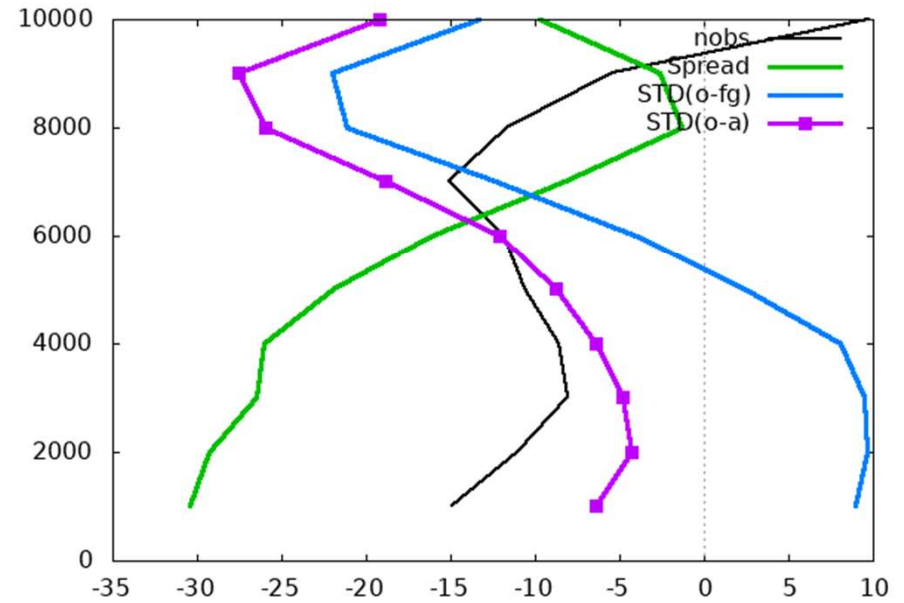
Radar: mean: 0.225 mm/h max: 72.19 mm/h  
 Model: mean: 0.137 mm/h max: 93.63 mm/h  
 missed (black): 8578 false (red): 4808 hits (green): 649  
 ETS: 0.038 FBI: 0.591

# Benefit on 3d radar data assimilation

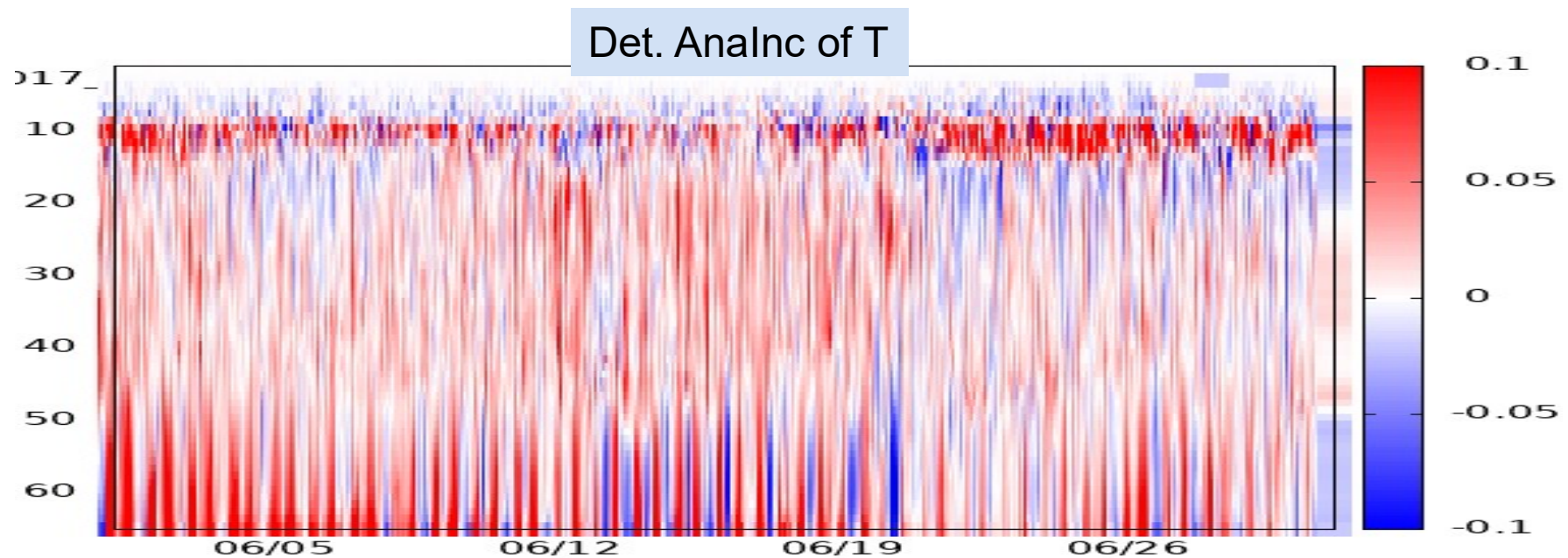
Change of BIAS in RADREFL\_RADAR  
ilam0014\_jun21 vs. ilam0017\_jun21

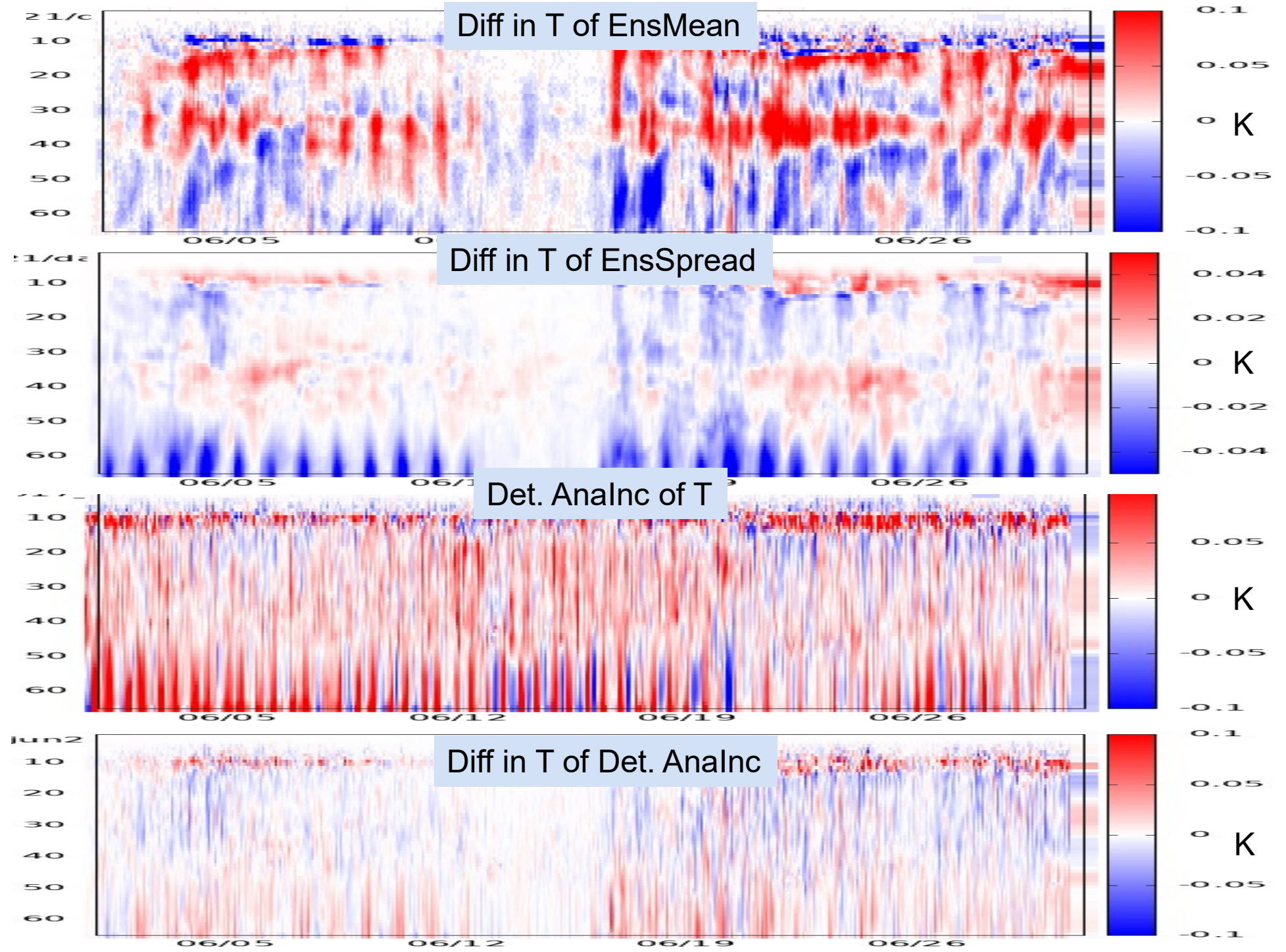


Relative Improvement in RADREFL\_RADAR  
ilam0014\_jun21 vs. ilam0017\_jun21

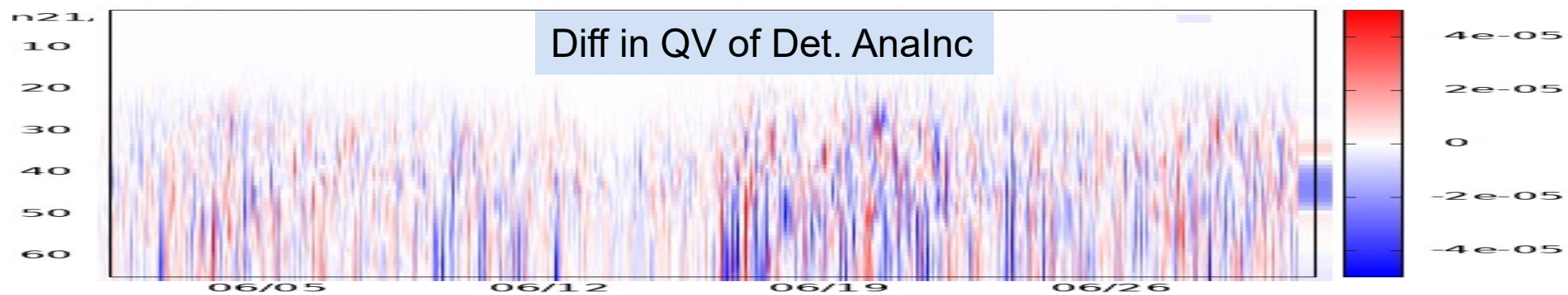
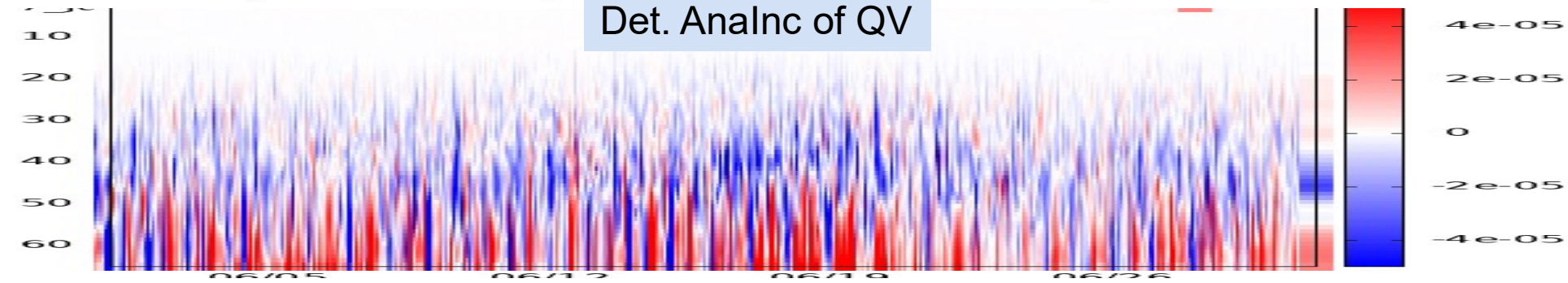
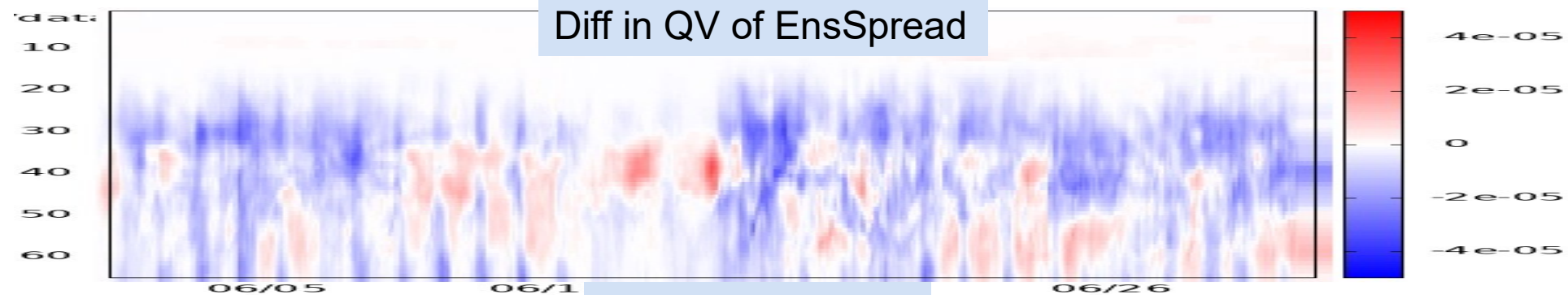
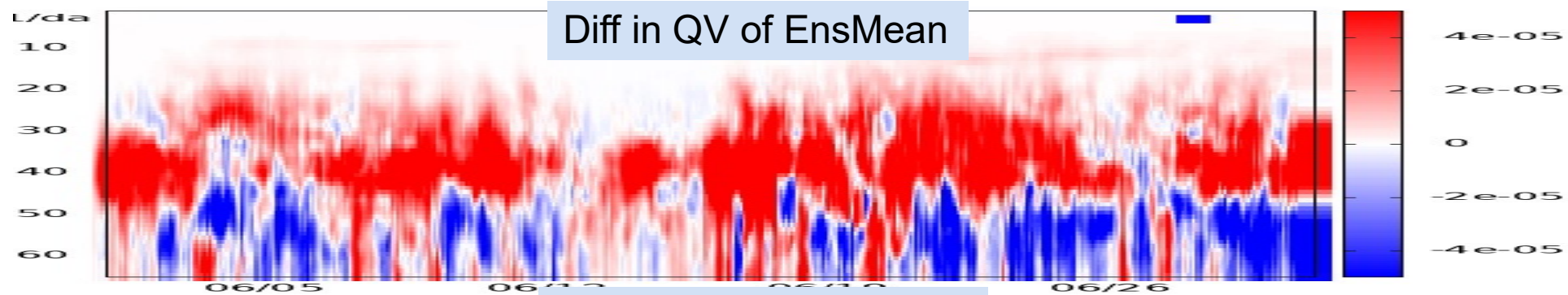


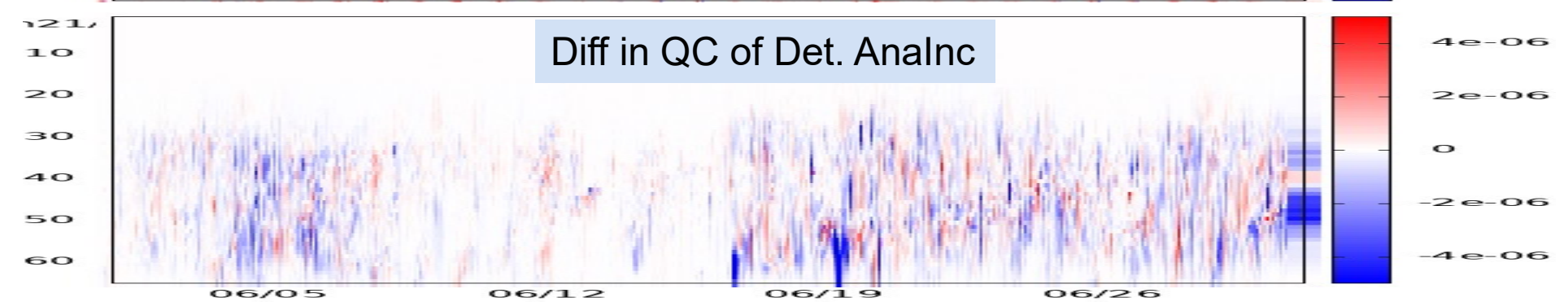
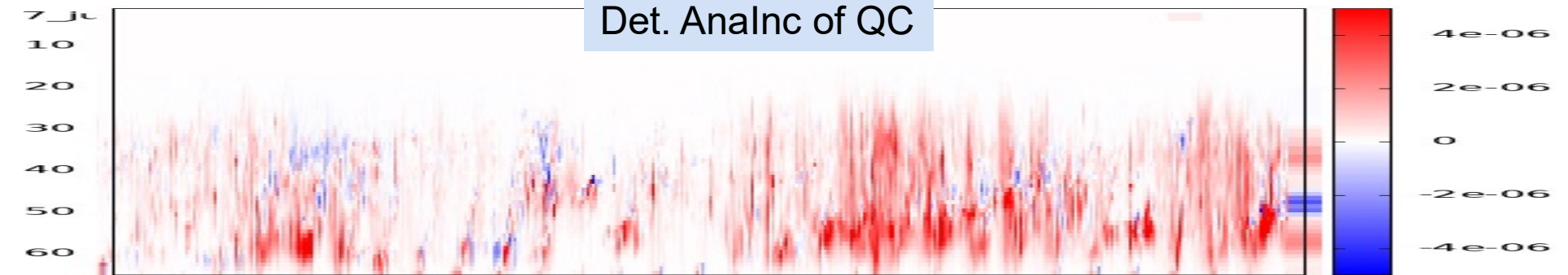
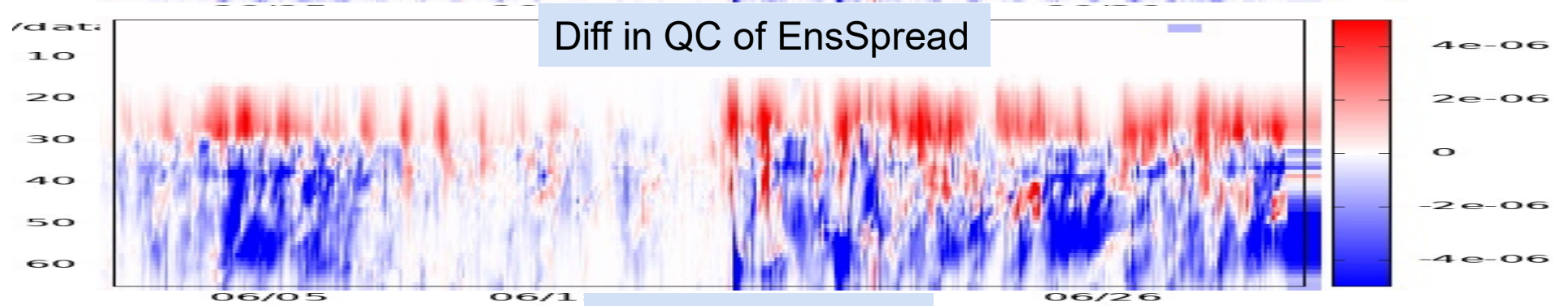
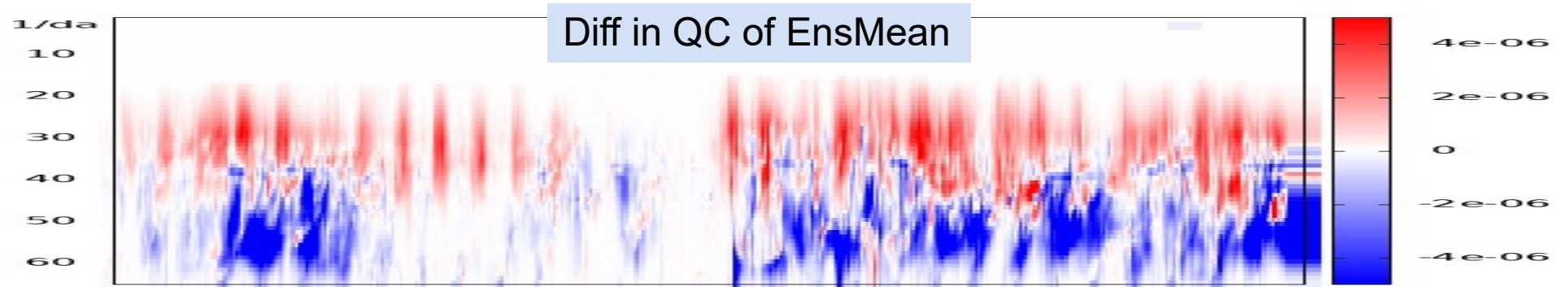
- Evaluation of model state can be done in different ways.
  - Verification of analyses or forecasts against observations
  - Investigation temporal and spatial averages of meteorological parameter.
  - In terms of LETKF, this are Ensemble mean, ensemble spread and analysis increments









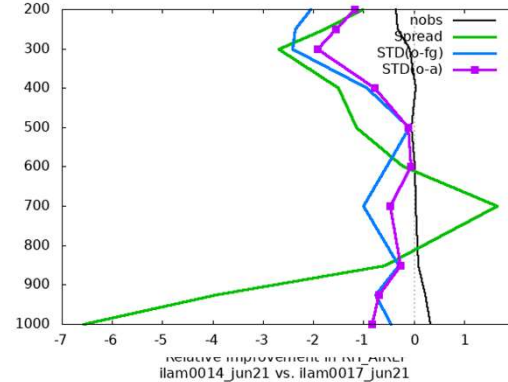
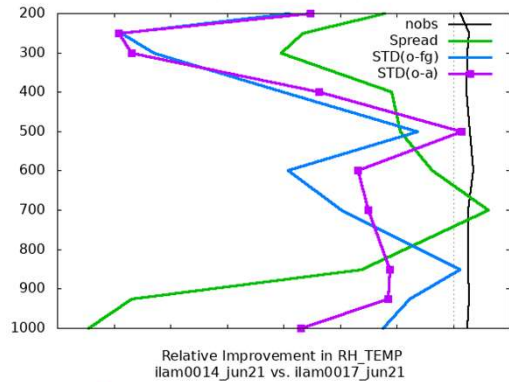


# Assimilation cycle against Observations

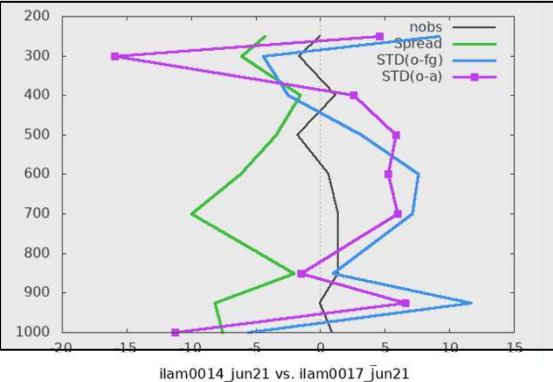
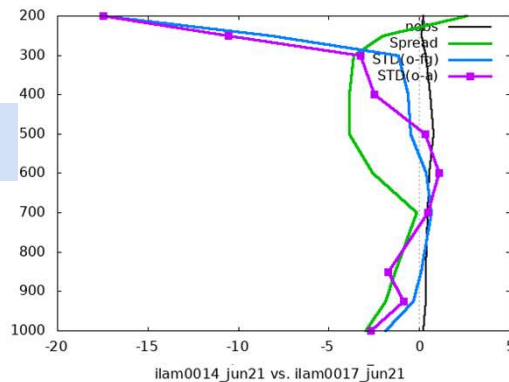
## Radiosondes

## Aireps

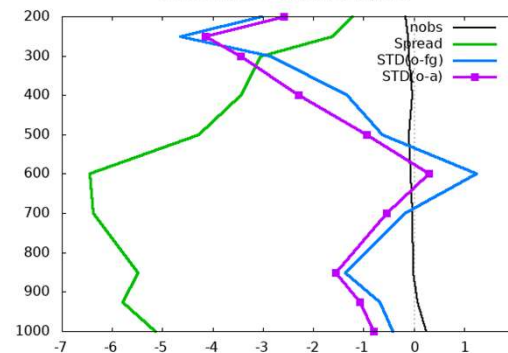
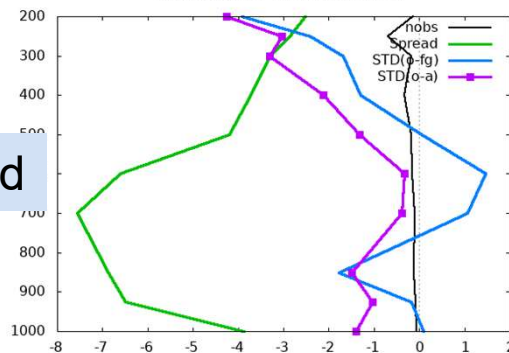
T



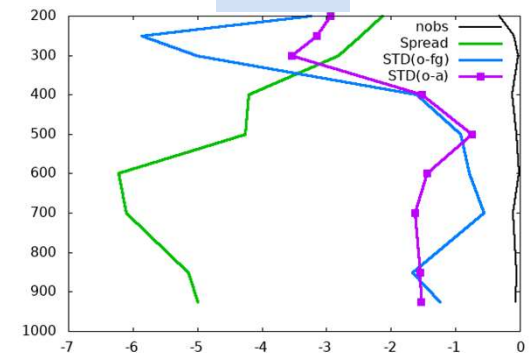
RH



Wind



## Pilot



- Slightly negative for LHN:
- Reduction in Spread and active observations
- Increasing STD of both, Analyse and FG

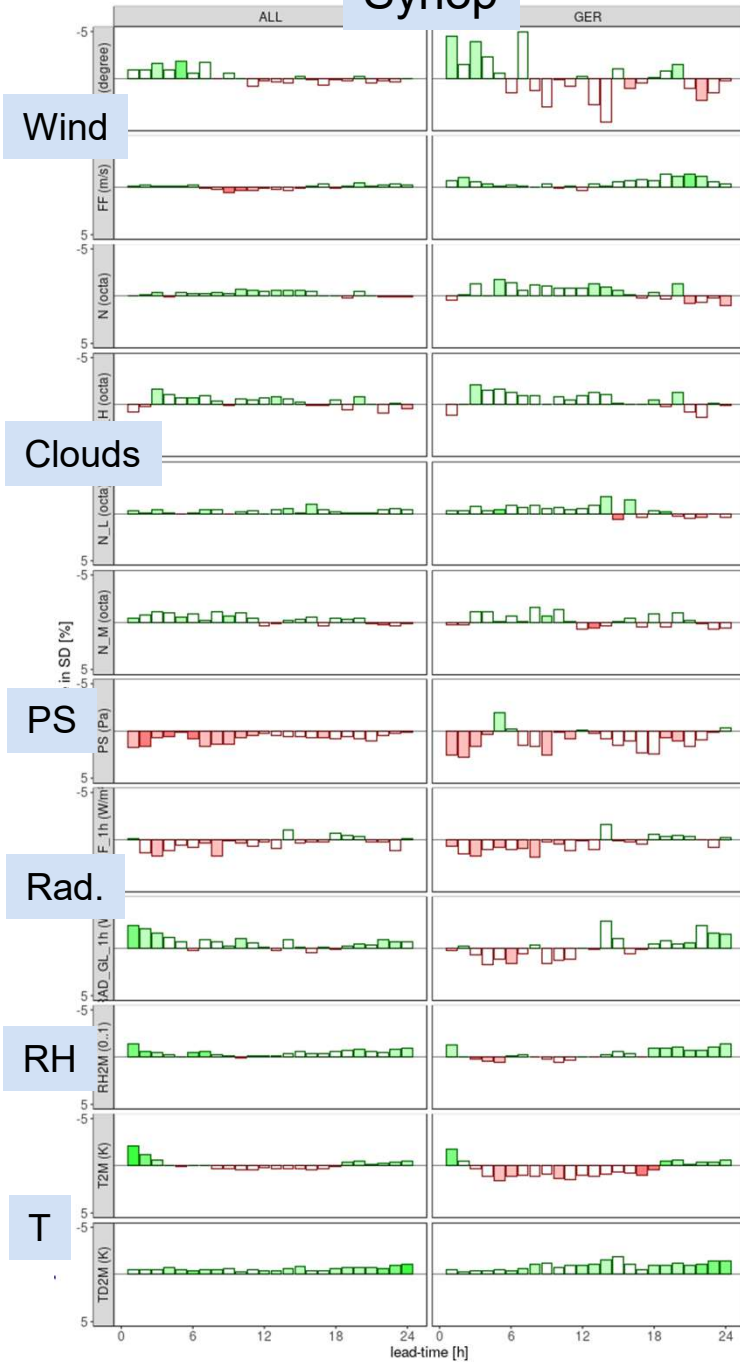


# Forecasts cycle against Observations

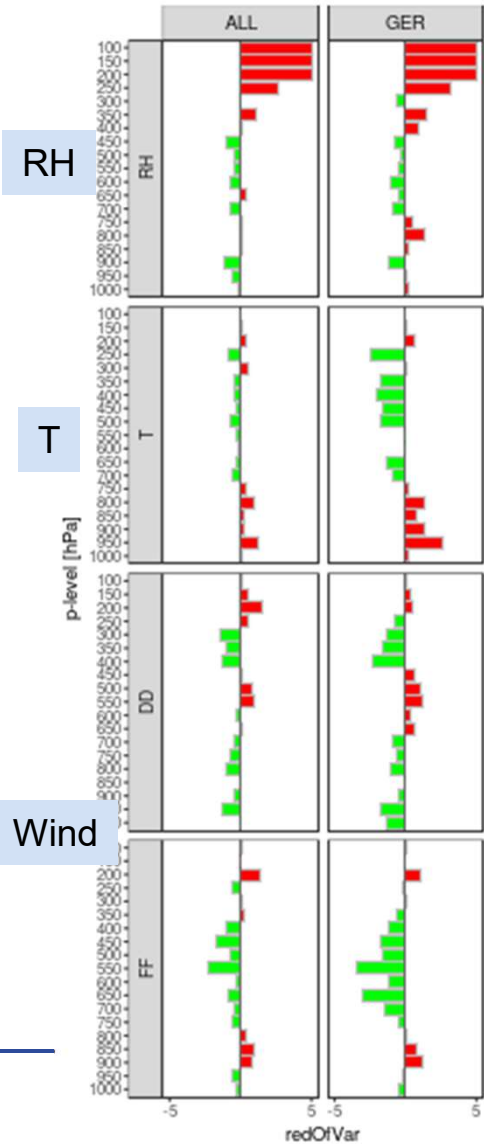
Wetter und Klima aus einer Hand



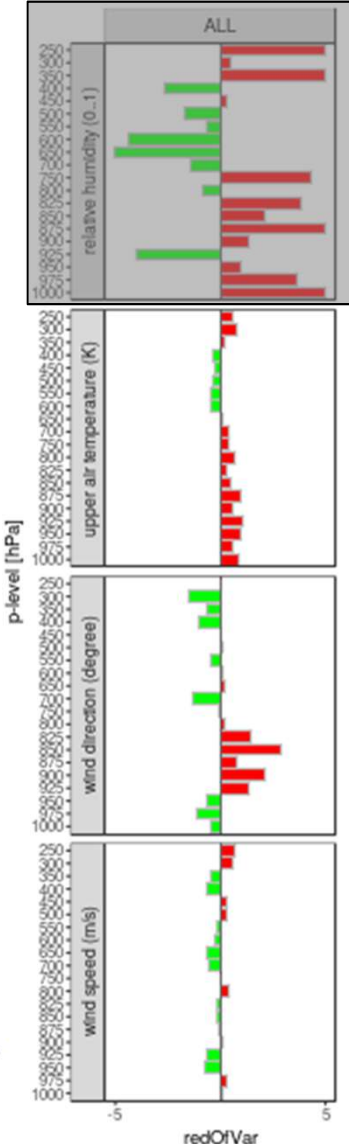
## Synop



## Radiosondes



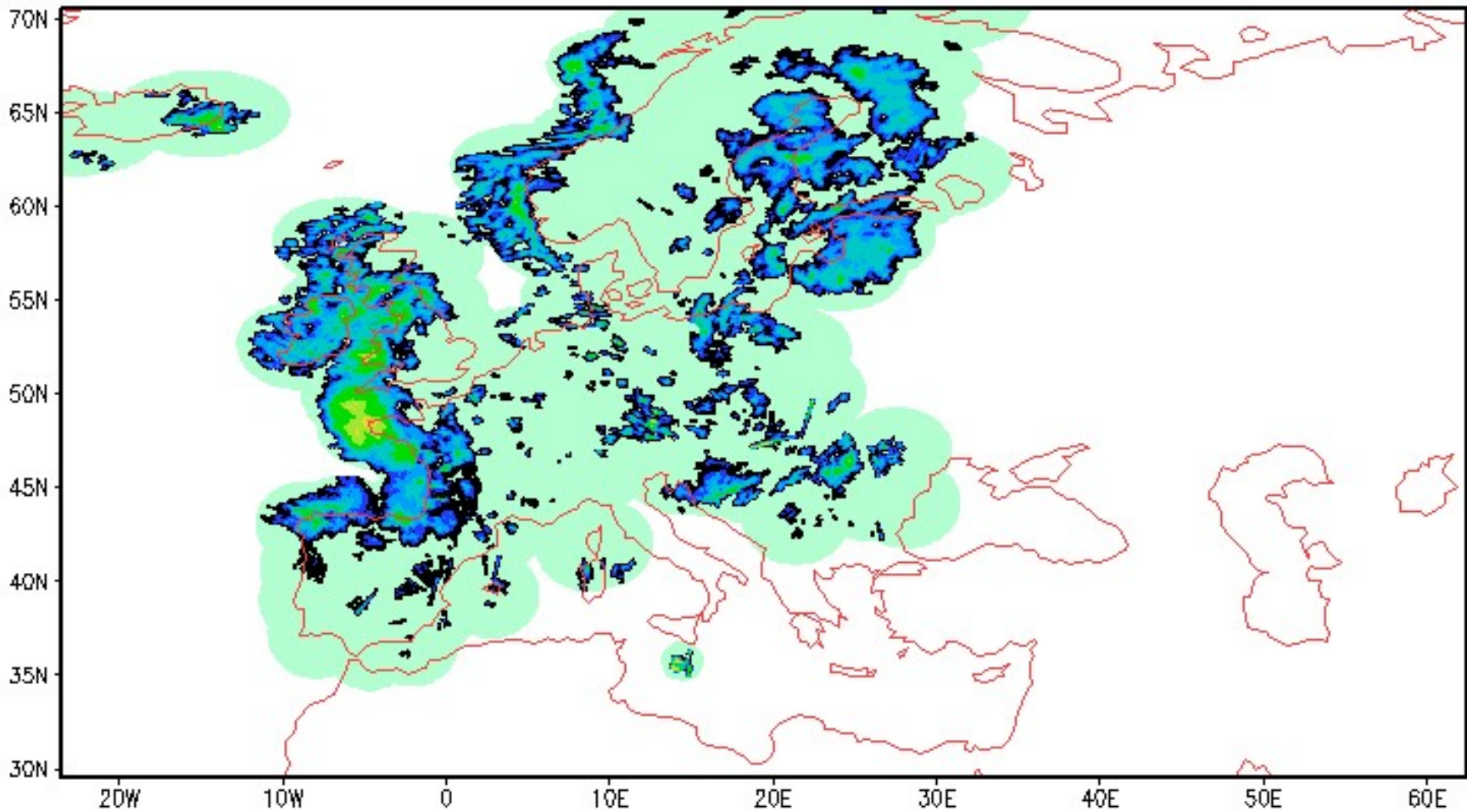
## Aireps



## Conclusion

- LHN in ICON LAM does improve precipitation during assimilation and within the first hours of free forecast. Socres remains longer than improvements in amount
- Effects on soil moisture less pronounced due to the relaxation to ICON-EU (every day at 3 UTC)
- LHN leads to cooling and drying within the boundary layer, a warming and moistening further above.
- LHN leads to a reduction in spread
- Scores against observations are slightly negative for assimilation cycle but neutral too slightly positive for forecasts.
- Interaction with 2 moment scheme under development (too much graupel high above, stronger bias in surface precipitation and vertical precipitation flux.
- If you consider to apply LHN, you may think about using OPERA rain rate composite ...





Mean: 0.258541                      Min: 0                      Max: 17.6801  
Dims: x: 1-1377 y: 1-657 z: 1-1



## Here some facts

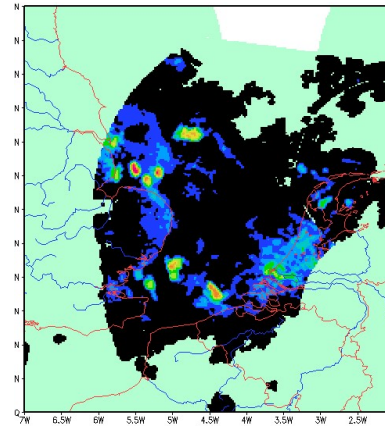
- Consists of about 150 radar stations all over Europe
  - Differ in age, manufacture, maintenance, post processings
  - Inhomogeneous quality
- Precipitation product is calculated from the best as possible reflectivity volume data. Data are weighted according to distance to composite grid point. So mainly the lowest elevation will win. Z is transformed to R by standard relation.
- Product available every 15 minutes and with 2x2 km<sup>2</sup> grid. A more frequent production is envisaged.
- ECMWF do not recommend using the data without further adjustments. DWD is using it in the almost outer areas of ICON-D2 domain, applying blacklisting and bright band detection

# Forecast quality vs. data quality

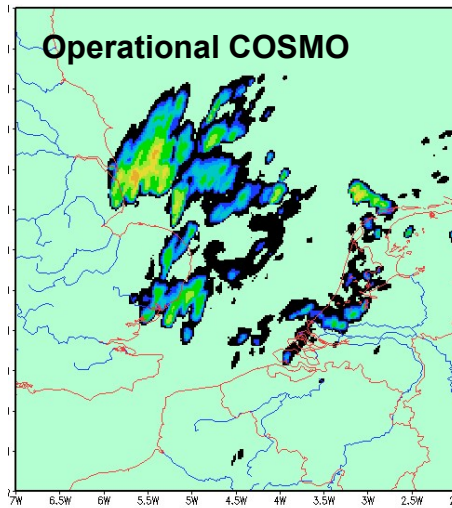
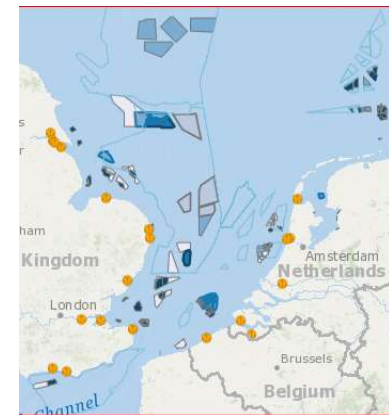
Satellite image



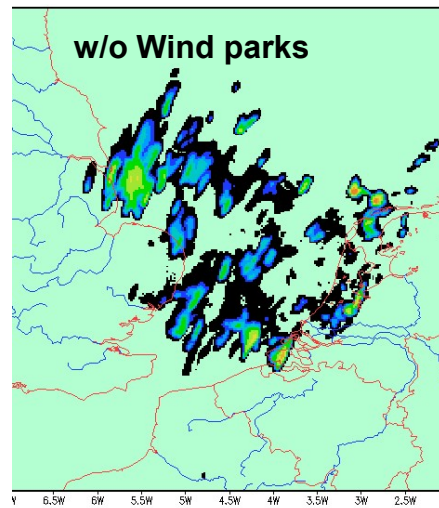
Dutch Radar



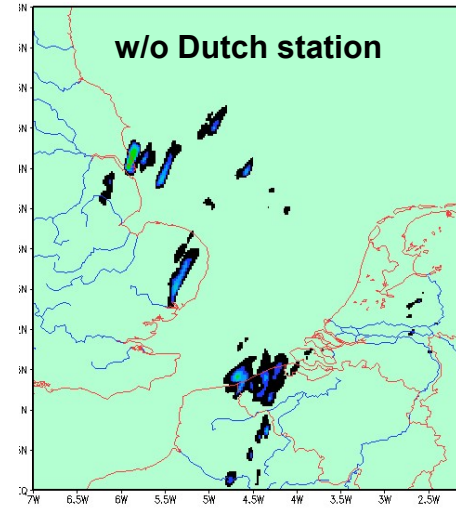
Offshore Wind parks



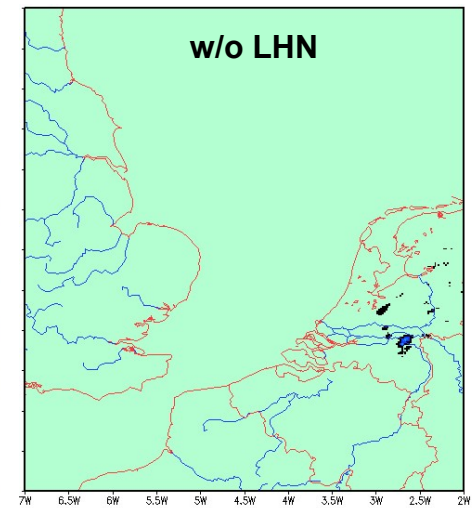
Mean: 0.178335 Min: 0 Max: 19.8691  
 Dims: x: 26-276 y: 316-616 z: 0-0



Mean: 0.11148 Min: 0 Max: 27.4082  
 Dims: x: 26-276 y: 316-616 z: 0-0



Mean: 0.00582962 Min: 0 Max: 4.35742  
 Dims: x: 26-276 y: 316-616 z: 0-0



Mean: 0.000130888 Min: -0.00012207 Max: 0.79248  
 Dims: x: 26-276 y: 316-616 z: 0-0

