
Spatial Verification for Ensemble at DWD

Susanne Theis

Deutscher Wetterdienst (DWD)



Introduction

Spatial Verification of Single Simulations

Box Statistics (e.g. averaging)
Fraction Skill Score
Wavelets (Base Transformation)
MODE, CRA, SAL, DAS

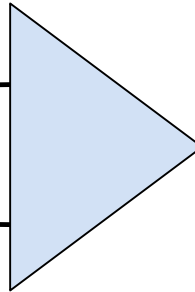
...



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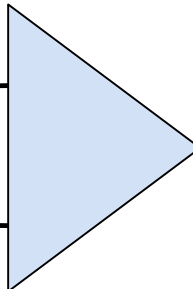
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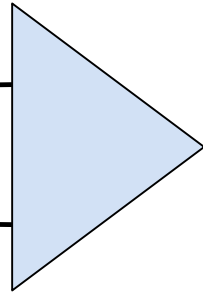


**Verification
of **Spatial Ensemble** Products**

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„multivariate“,
i.e. several locations



scale-related

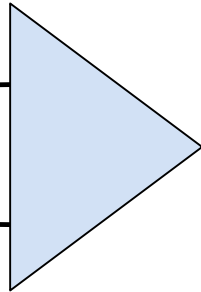
base transformation

object-oriented

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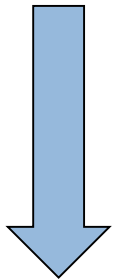


**Verification
of **Spatial Ensemble** Products**

Box Statistics



History: Spatial Ensemble Products at DWD



2009: Awareness, Implementation

2011: Forecaster's Feedback and Verification Results

since 2012: Operational

2015: Evaluation in European Severe Storms Laboratory

2015: Information on DWD Web Site

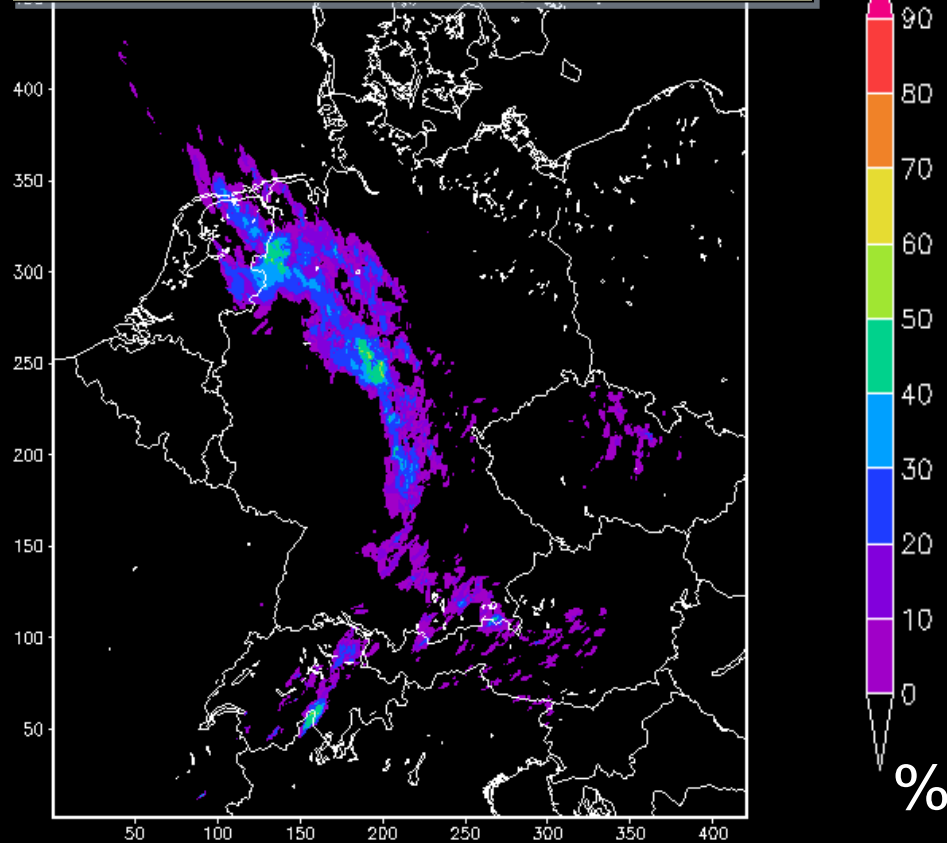
2015: Discovering Similar Issues in Renewable Energies

2016: Discussion at WWRP Working Group on Predictability

Awareness (2009)

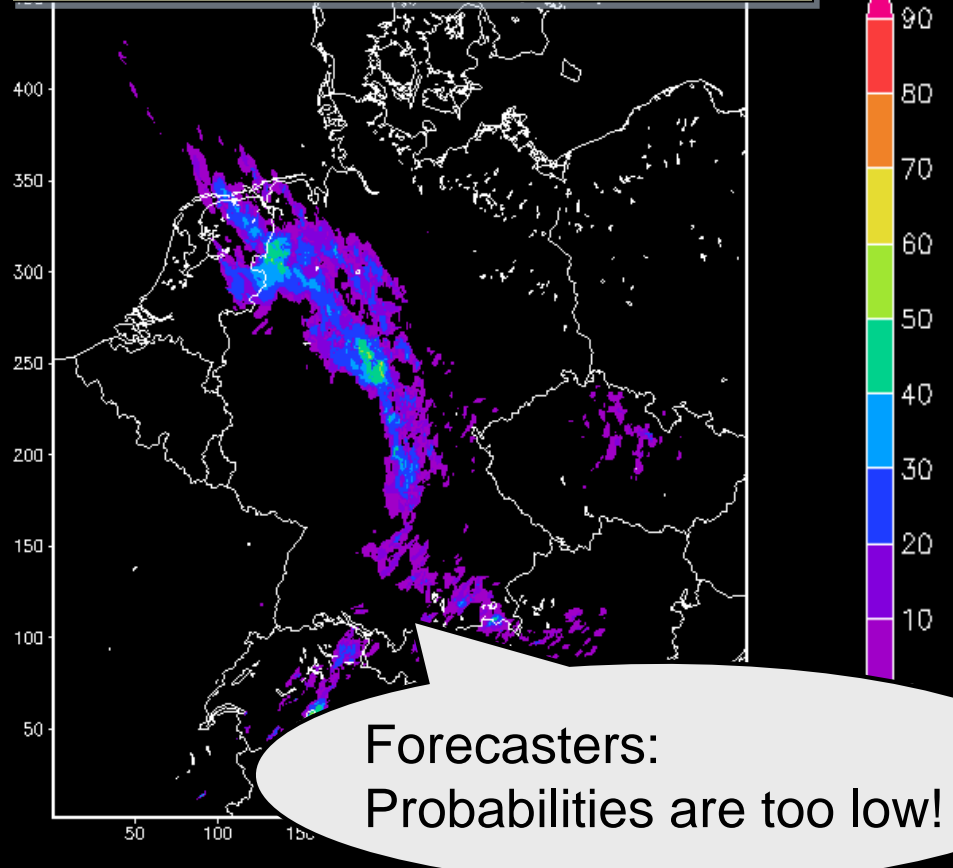
EPS Product Example: Probability Maps

„Event somewhere in 2,8km-Box“



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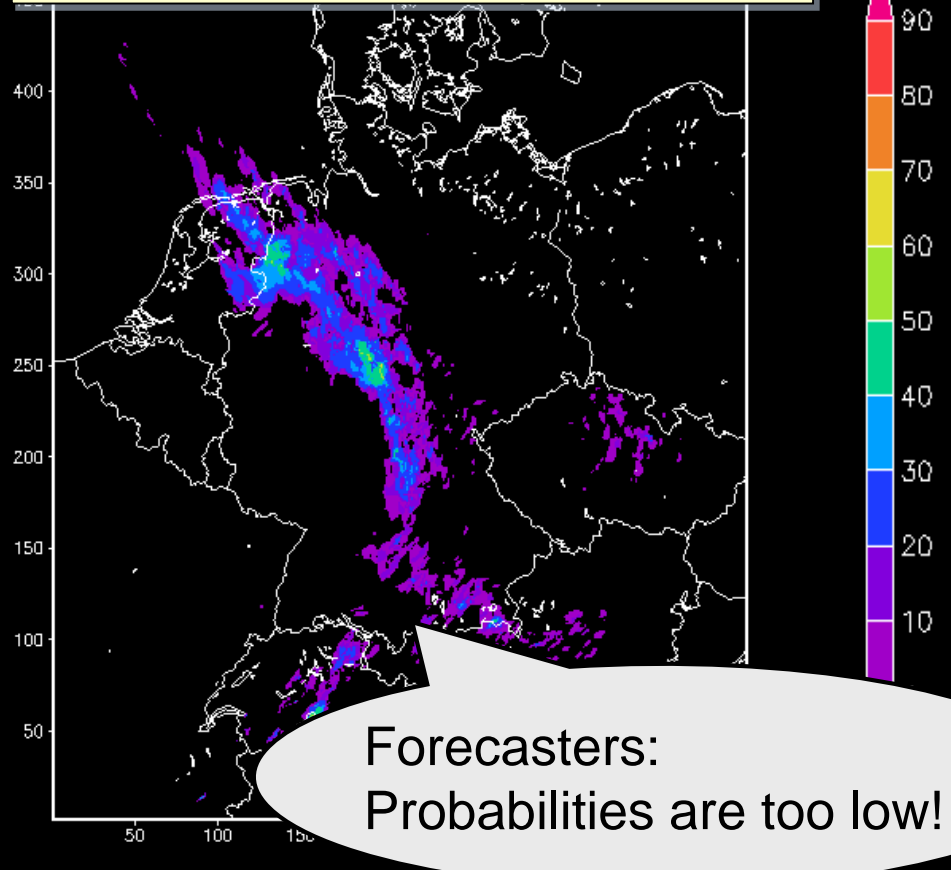


Forecasters:
Probabilities are too low!



EPS Product Example: Probability Maps

„Event somewhere in 2,8km-Box“



Reason:

Forecasters are used to larger reference regions

→ Experiment:

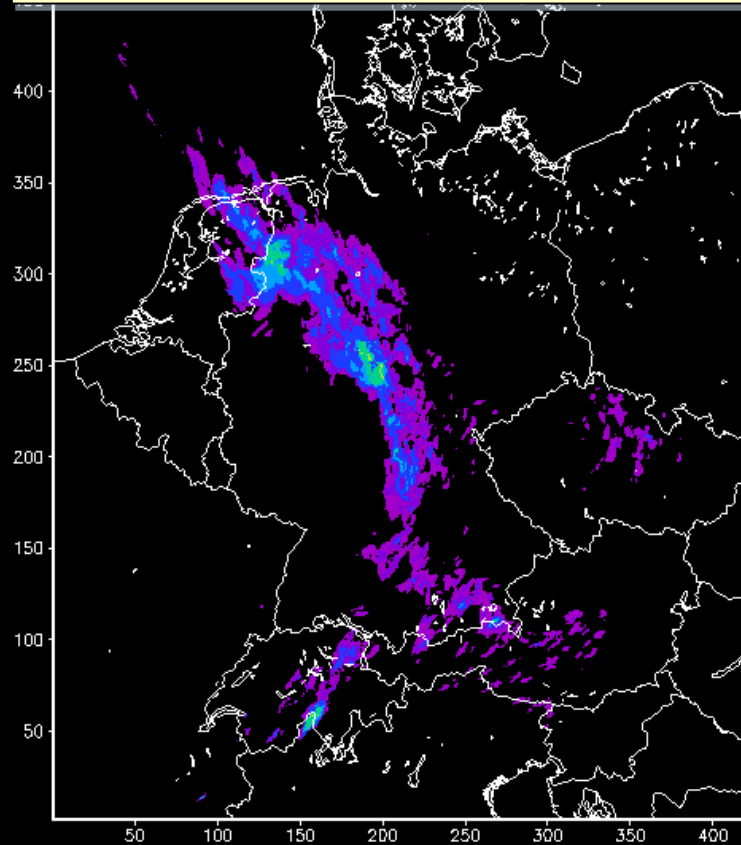
present probabilities on coarser grid

Forecasters:
Probabilities are too low!

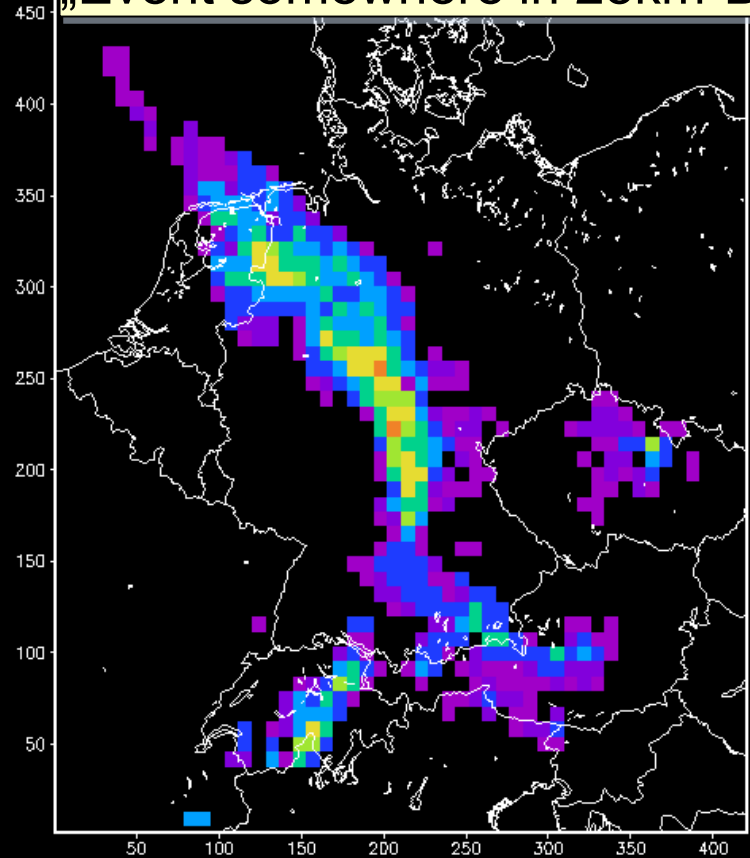


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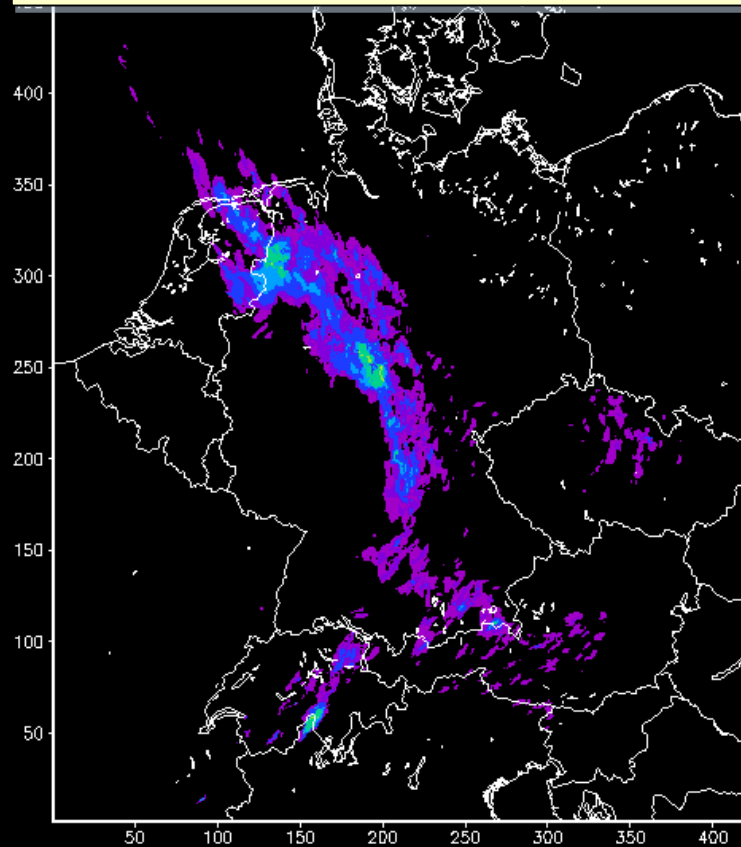


„Event somewhere in 28km-Box“

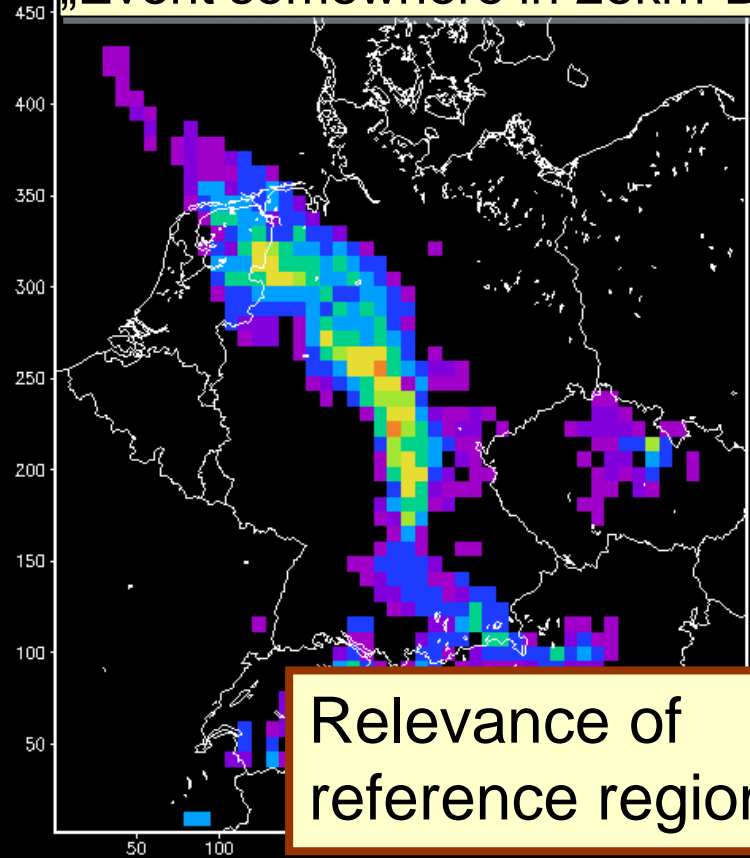


EPS Product Example: Probability Maps

„Event somewhere in 2,8km-Box“



„Event somewhere in 28km-Box“

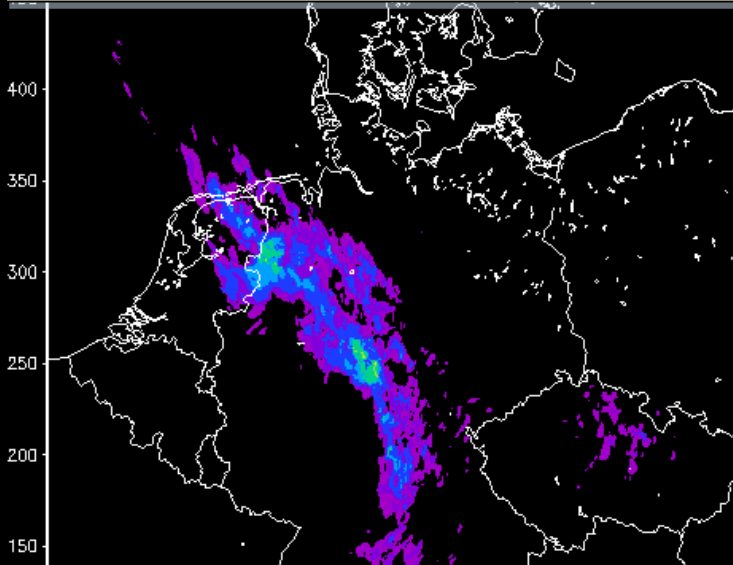


Relevance of reference region!

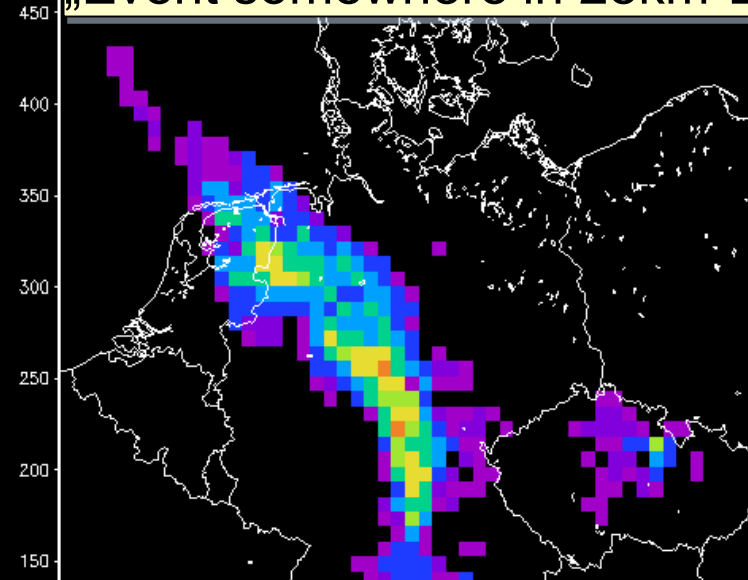


EPS Product Example: Probability Maps

„Event somewhere in 2,8km-Box“



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Implementation of a Spatial Ensemble Product



Forecaster's Feedback at DWD (2011)



Forecasters' Feedback

→ what they **prefer to use**:

→ 90%-quantile of precipitation

→ precipitation probabilities for an area (10x10 grid points)



Forecasters' Feedback

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Key Product of COSMO-DE-EPS

Verification Results (2011)

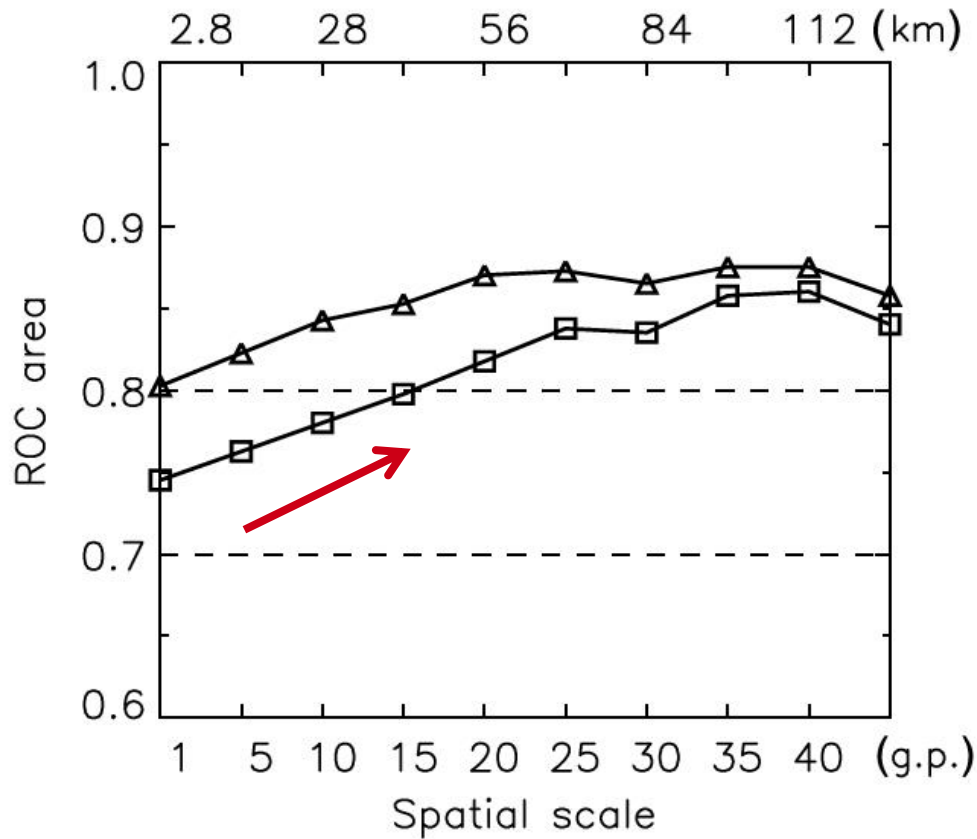
Ben Bouallègue, Z. (2011):

***Upscaled and fuzzy probabilistic forecasts: verification results.** COSMO Newsletter 11, 124-132.*

Ben Bouallègue, Z. and S.E. Theis (2014):

Spatial Techniques Applied to Precipitation Ensemble Forecasts: From Verification Results to Probabilistic Products. Meteorological Applications, 21, 922-929.





Observations:
Radar data,
upscaled in the same way

Figure 6. ROC area as a function of the window size used for the upscaling process. The triangles refer to a threshold of 10 mm (6 h)^{-1} and the squares to a threshold of 20 mm (6 h)^{-1} .

- **„upscaling“** → substantial quality gain
(looking at ROC area, „high“ precipitation thresholds)

- **optimal window size:**

balance between

good verification results

and access to fine-grid information

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Looked at Quality of Spatial Ensemble Product



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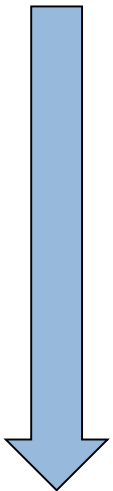
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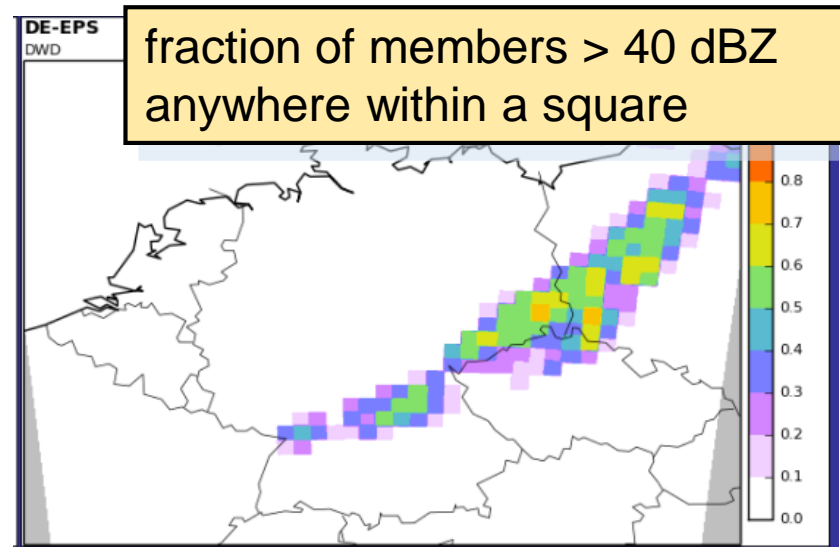
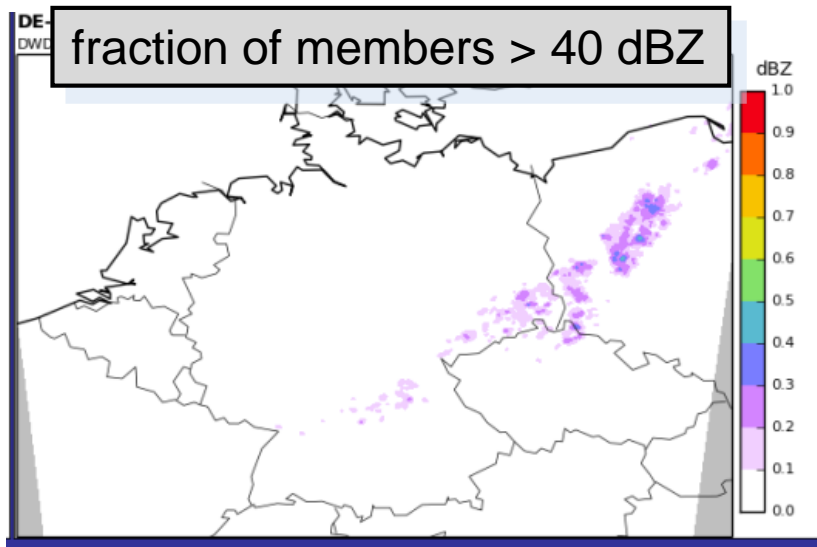
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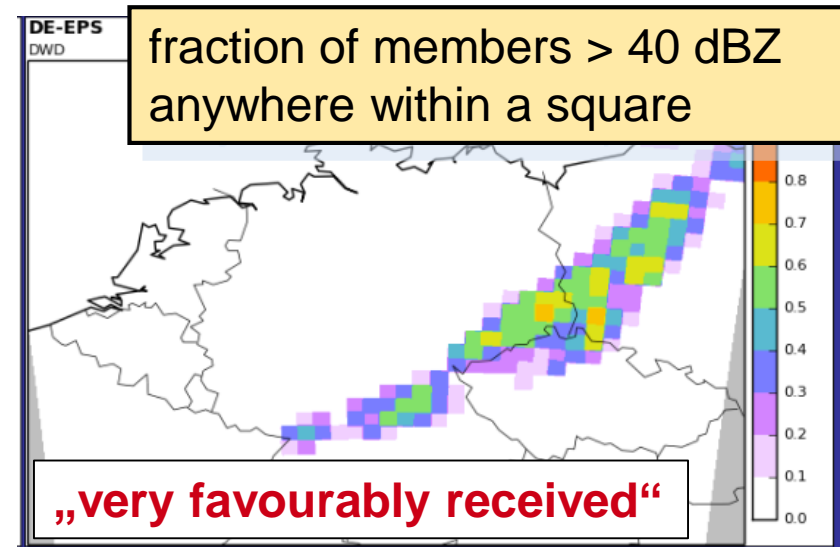
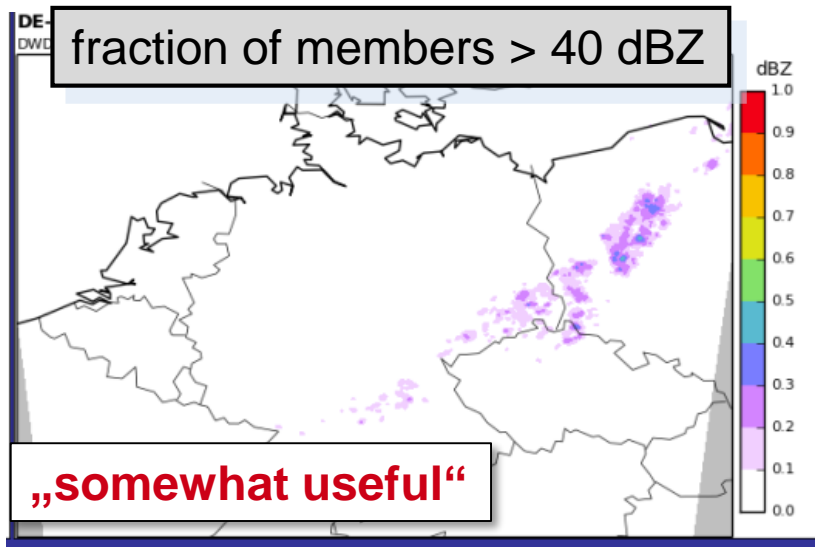


Evaluation at ESSL (2015)

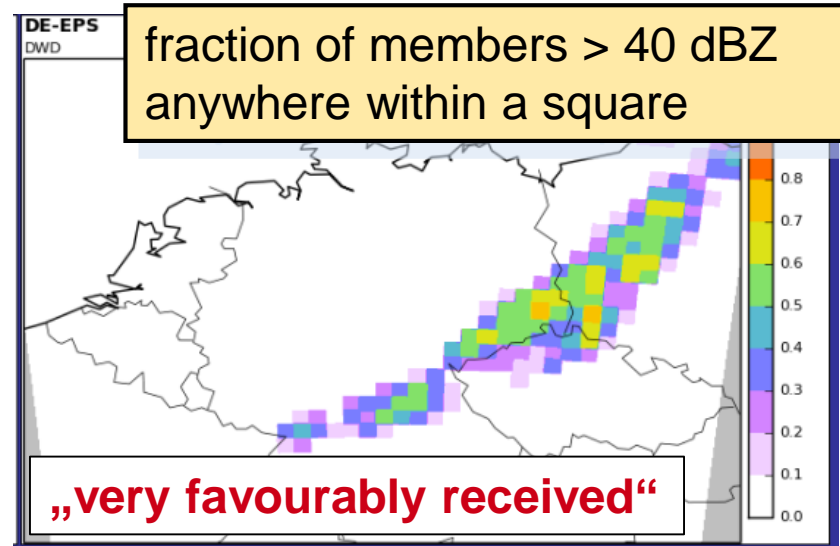
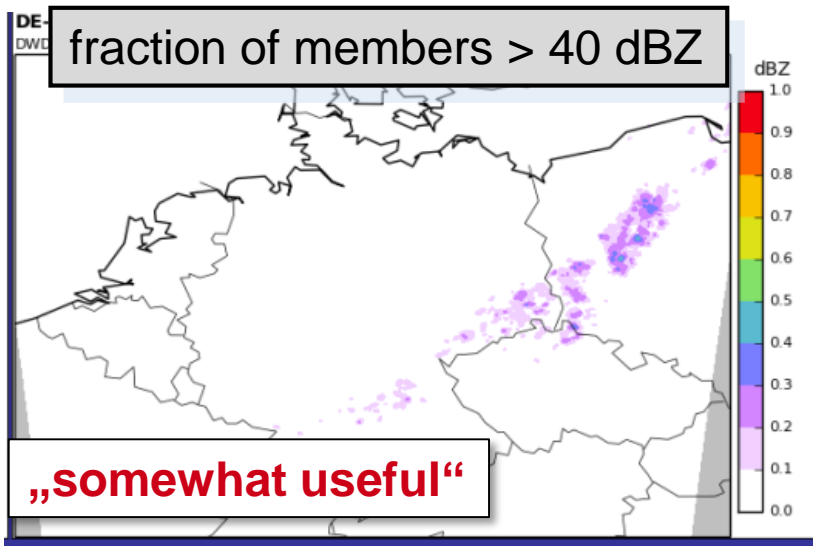
simulated reflectivity, 06 UTC Run on May 12th, + 15 hours forecast



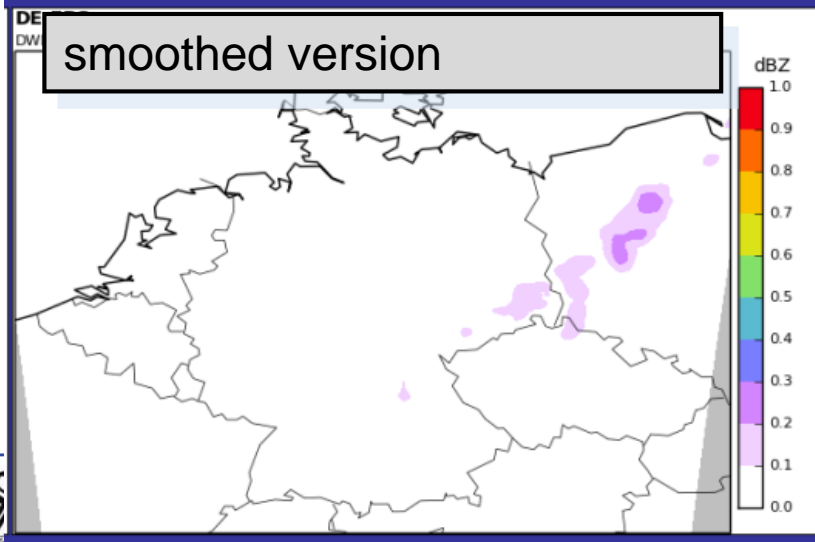
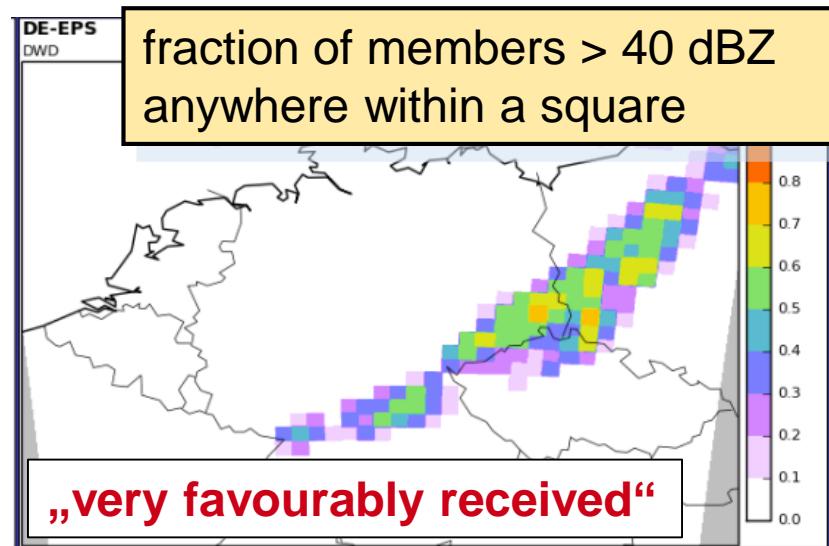
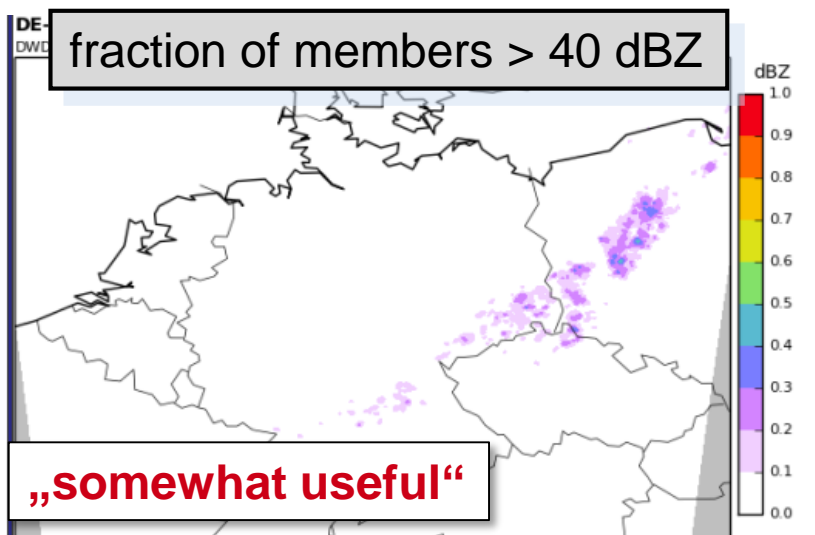
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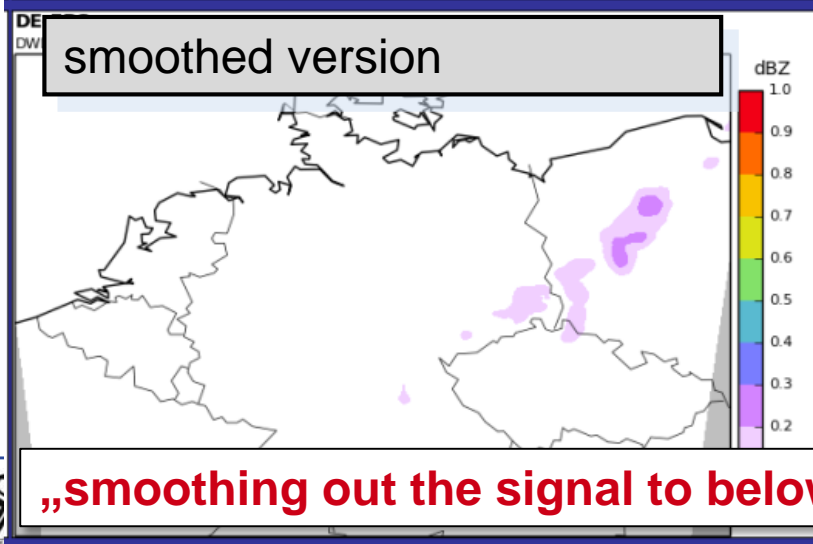
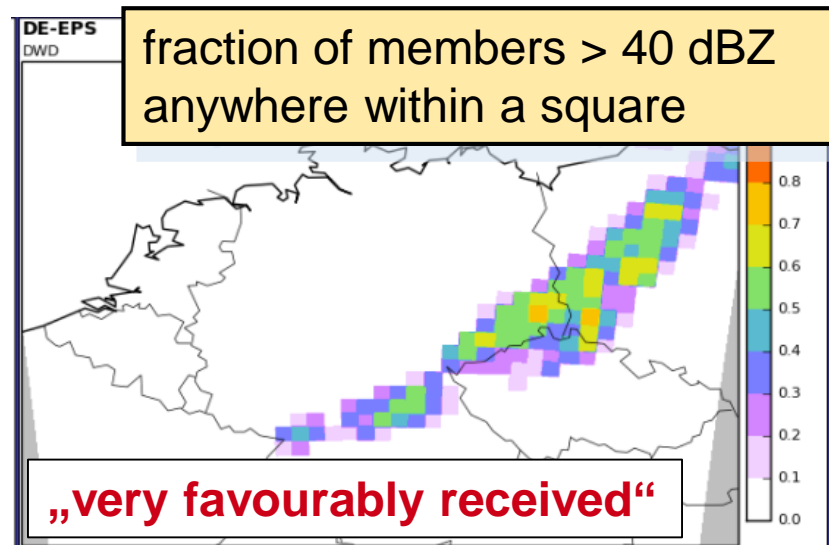
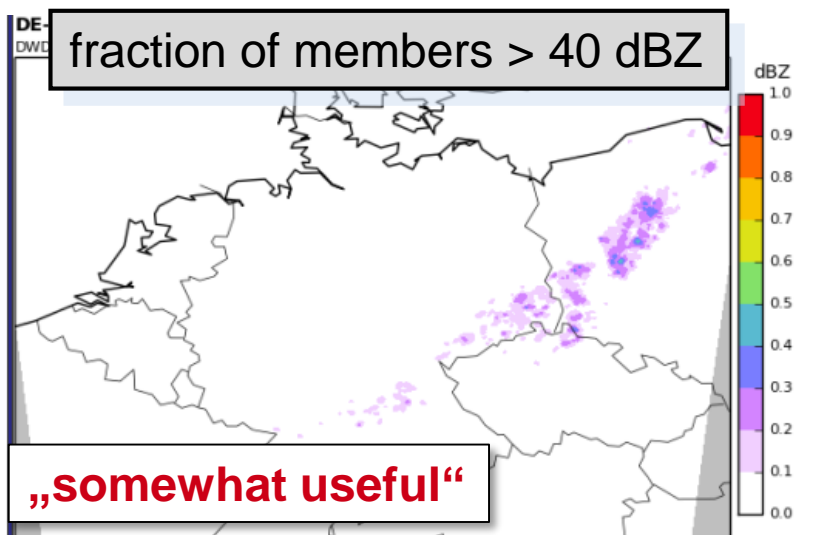
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somewhat related to

- Fraction Skill Score
- Neighbourhood Method

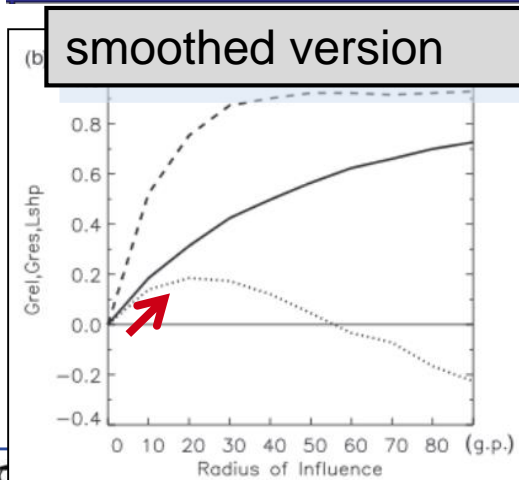
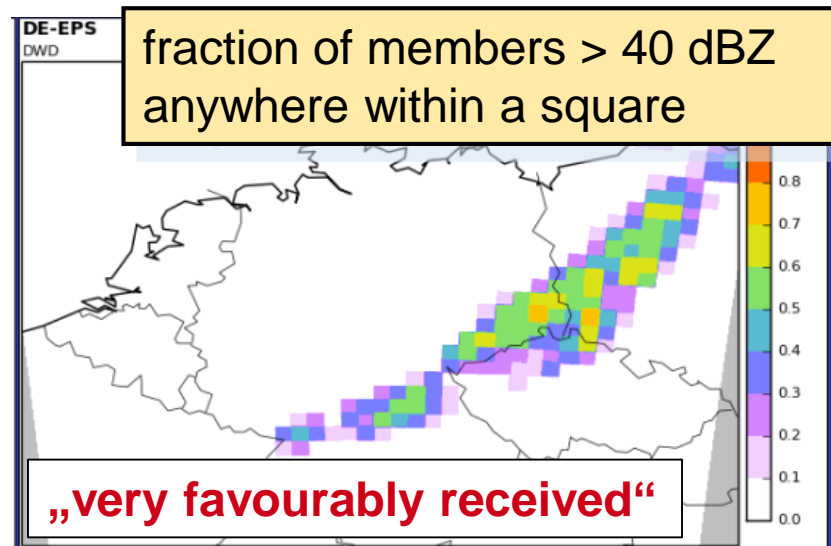
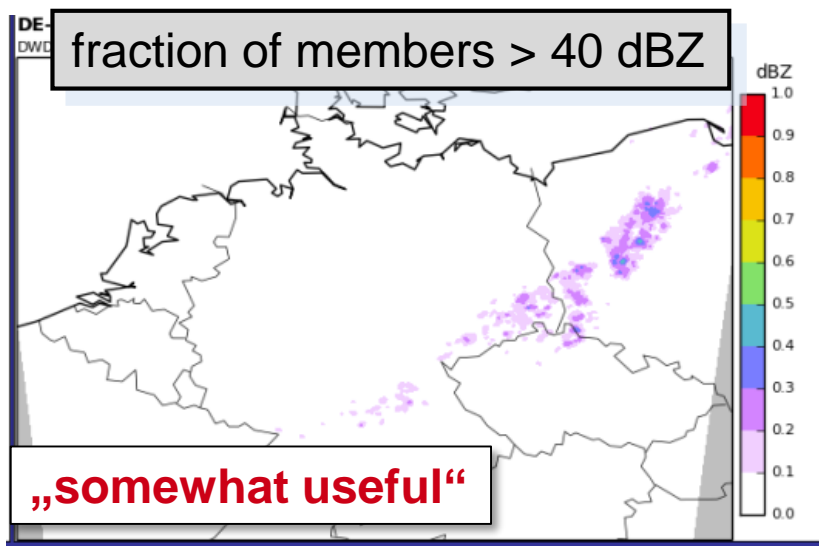
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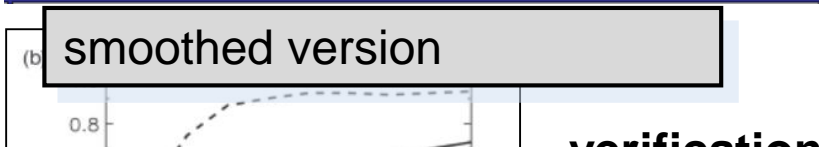
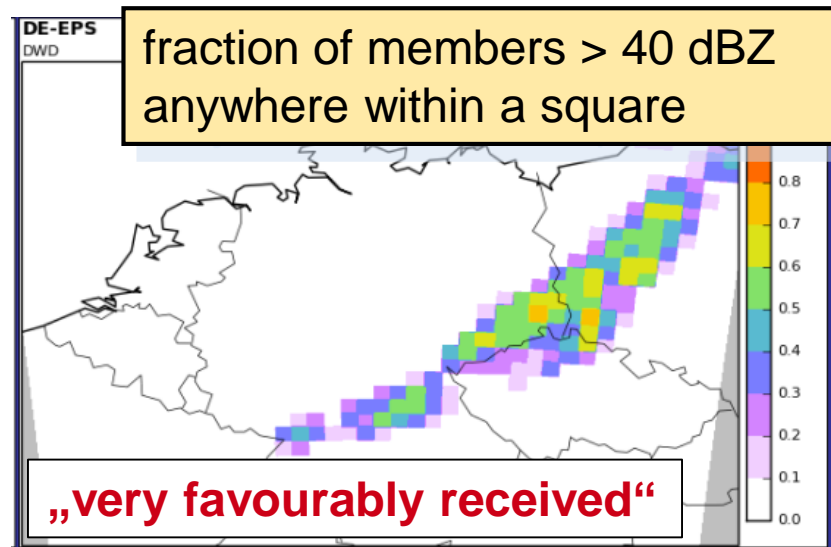
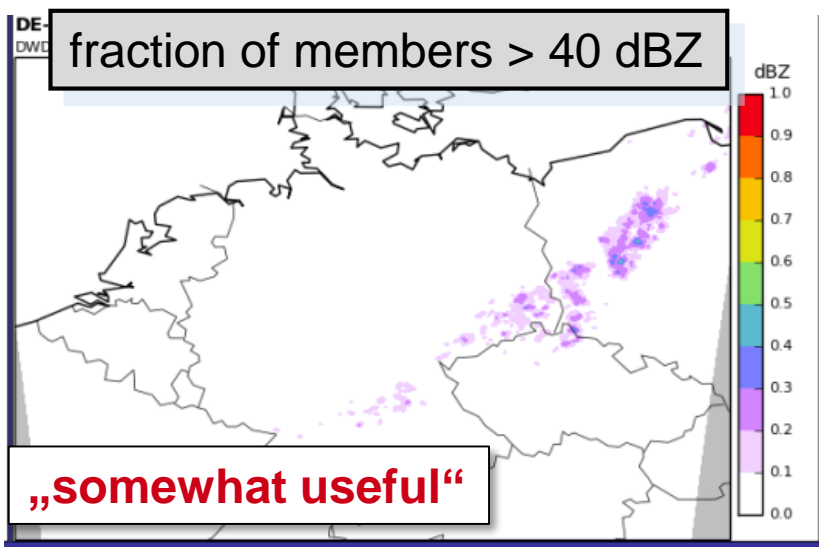
**despite critical evaluation,
verification result still favourable**

Precip thres: 10mm/6h, Reference: COSMO-DE-EPS

(Ben Bouallègue and Theis, 2014)



simulated reflectivity, 06 UTC Run on May 12th, + 15 hours forecast



Relevance of Evaluation

0 10 20 30 40 50 60 70 80 (g.p.)
Radius of Influence

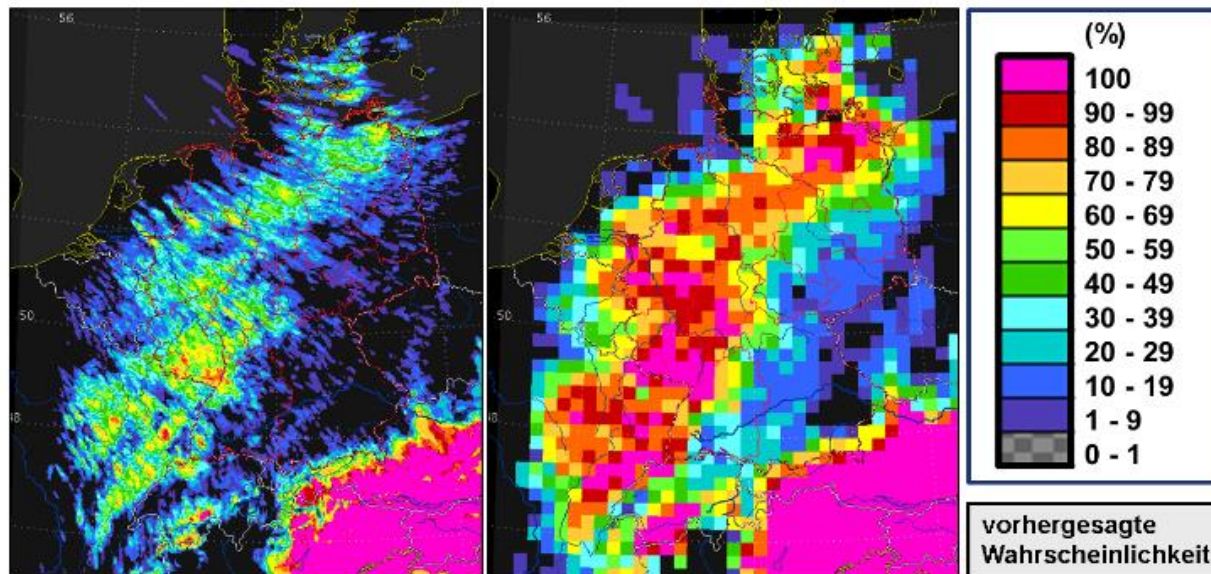


Information on DWD web site (2015)



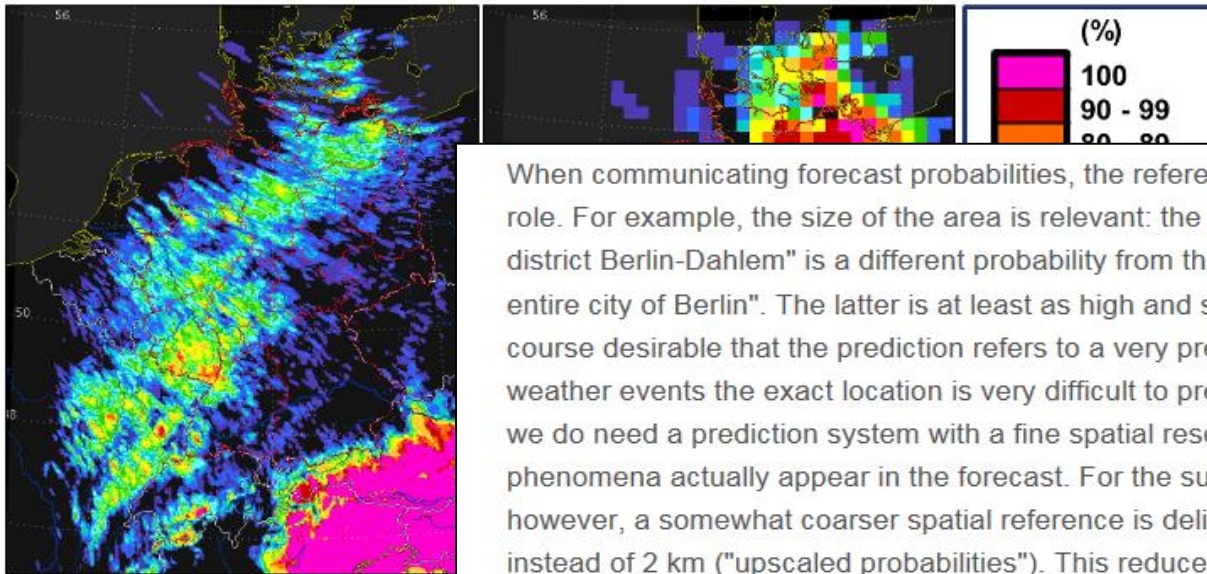
www.dwd.de → English (klick on „En“ at the top)

- RESEARCH
- WEATHER FORECASTING
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- ENSEMBLE PREDICTION



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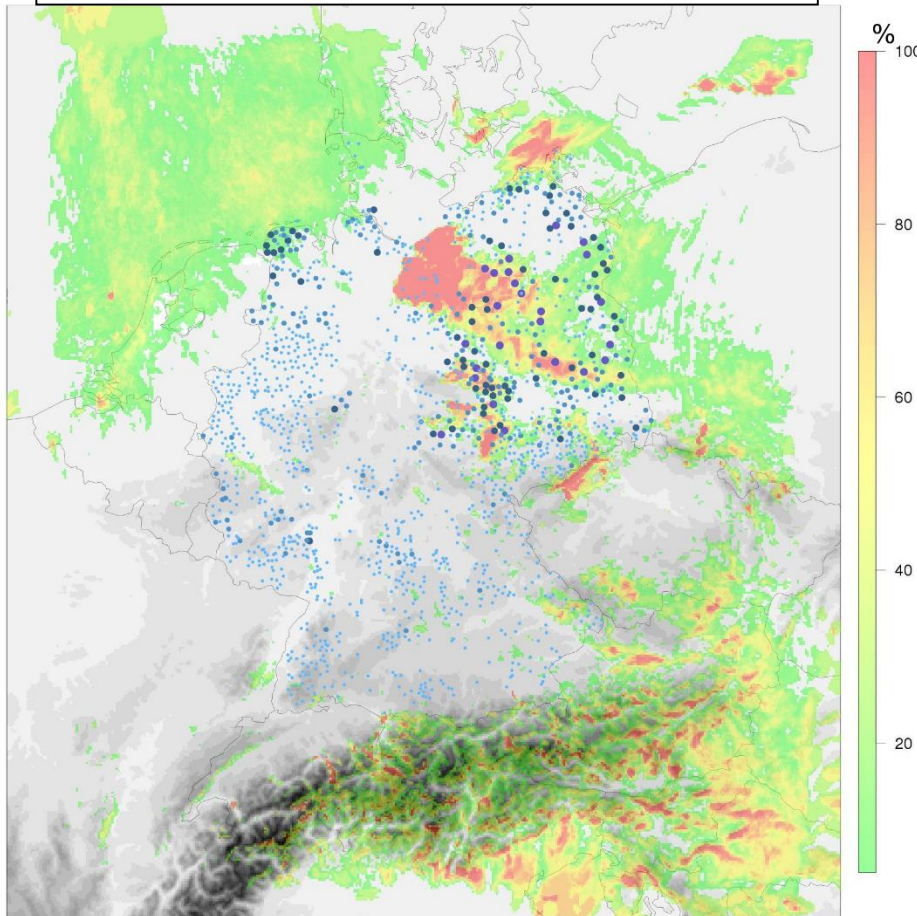


When communicating forecast probabilities, the reference to a space and time interval plays a role. For example, the size of the area is relevant: the probability of "rain somewhere within the district Berlin-Dahlem" is a different probability from the probability of "rain somewhere within the entire city of Berlin". The latter is at least as high and sometimes higher. Generally, it is of course desirable that the prediction refers to a very precise location. However, for some local weather events the exact location is very difficult to predict (e. g. thunderstorms). As a first step, we do need a prediction system with a fine spatial resolution, so that such important weather phenomena actually appear in the forecast. For the subsequent formulation of probabilities, however, a somewhat coarser spatial reference is deliberately chosen, e.g. a radius of 20 km instead of 2 km ("upscaled probabilities"). This reduces the pretension to high spatial accuracy, and the ensemble members are more likely to form a matching statement, and the resulting probabilities provide a more meaningful warning.

Similar Issues in Forecasts for Renewable Energies (2015)



Probabilistic Wind Ramp Forecast



Colors:

Probability of Windramps

based on COSMO-DE-EPS forecasts

Blue dots:

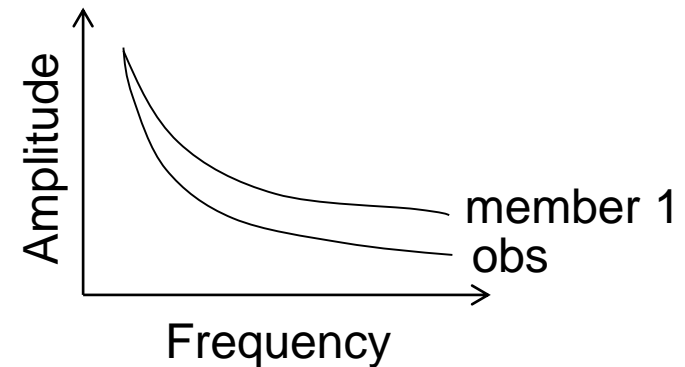
Installed Electric Power per „County“

Wahrscheinlichkeit für das Eintreten einer Windrampe basierend auf einer COSMO-DE-EPS Vorhersage gültig für den 6.12.2012 03 UTC + 3h;

● installierte Leistung pro PLZ (Anlagenstammregister 2012)

Verification of Wind Ramps:

- Wind Ramps directly
- Spectrum of Time Series
- Correlation in Time
- Multivariate Scores:
 - p-Variogram Score,
 - Multivariate Rank Histogram
 - Energy Score



Discussion at WWRP Working Group on Predictability (2016)



...km-scale....probabilistic...high-impact....

Deutscher Wetterdienst
Wetter und Klima aus einer Hand



„Default“ Product:

Probabilities for each grid point and time



Source: WWRP PDEF WG meeting, Exeter, 2016

...km-scale....probabilistic...high-impact....

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Probabilities for each grid point and time

Questions:

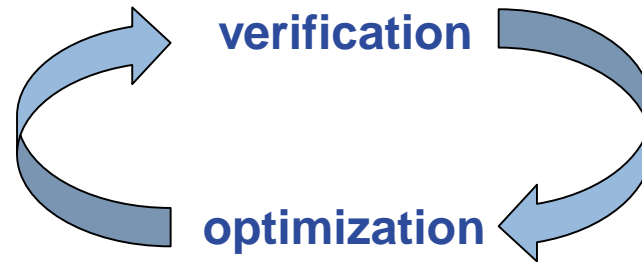
- Does „high-impact“ involve any spatial or temporal „structure“?
- Are we interested in the *rough* time and location?

→ High-impact Event not necessarily visible in „standard probabilities“



„Default“ Product:

Probabilities for each grid point and time



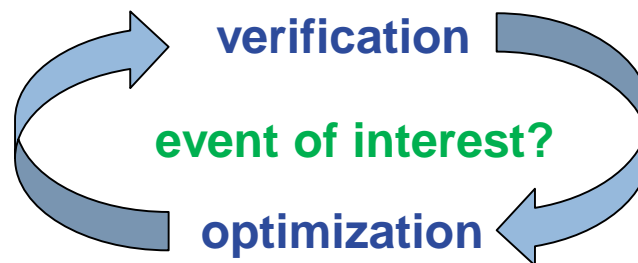
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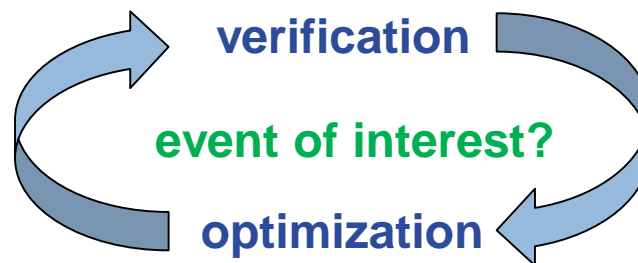
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thoughtful definition of event + targeted verification

