

Recent tests with the operational CNMCA-LETKF system

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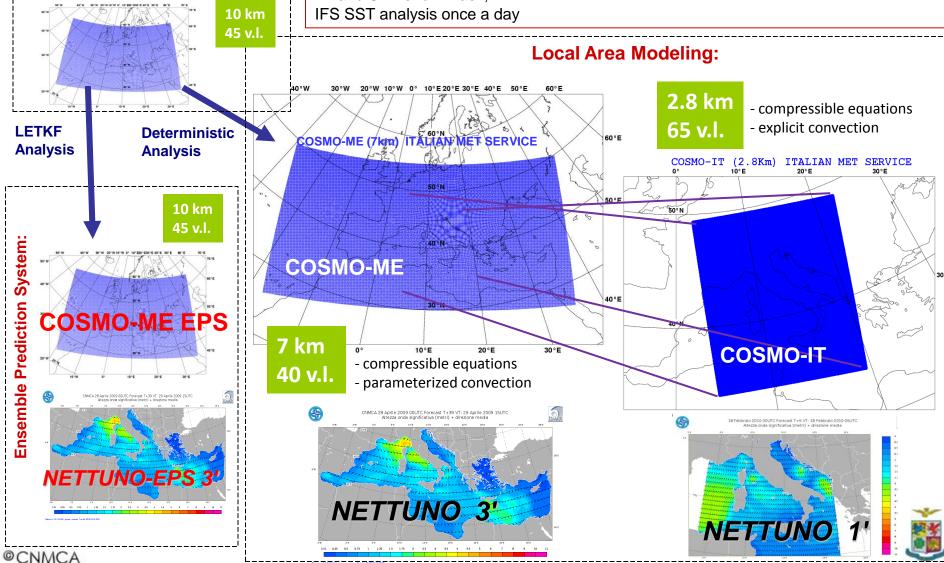
- > Operational CNMCA-LETKF system
- » Experiments
 - new observations assimilation:
 - GPS (ztd)
 - MODE-S
 - DFI
 - SPPT (COSMO reference version)
 - COSMO with single precision real
- Recent changes in operations
 - pseudo-RH variable assimilation (J. Liu,2007)



OPERATIONAL NWP SYSTEM

Ensemble Data Assimilation:

LETKF analysis ensemble (40+1 members) every 6h using RAOB (also 4D), PILOT, SYNOP, SHIP, BUOY, Wind Profilers, AMDAR-ACAR-AIREP, MSG3-MET7 AMV, MetopA-B scatt. winds, NOAA/MetopA-B AMSUA/MHS and NPP ATMS radiances + Land SAF snow mask,

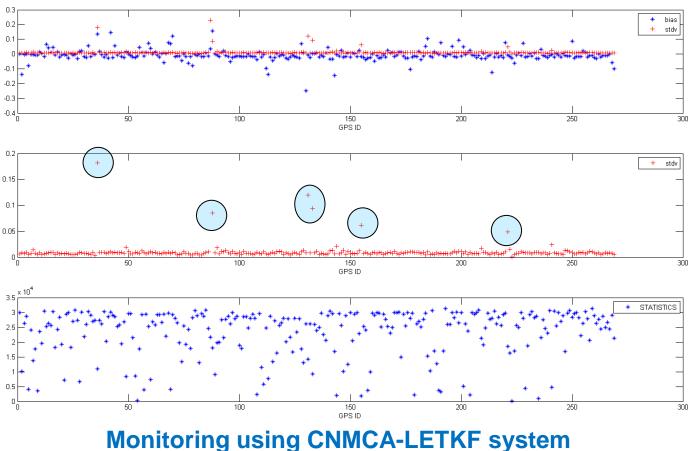


GPS (ztd) MONITORING/ASSIMILATION

Assimilation from 10nov2014 to 10dec2014: MEAN: OBS-FG -0.0225E-02 STDV : OBS-FG 0.9499E-02 NUMBER OF OBSERVATIONS : 33632

Italian stations

Period : April 2014 - March 2015



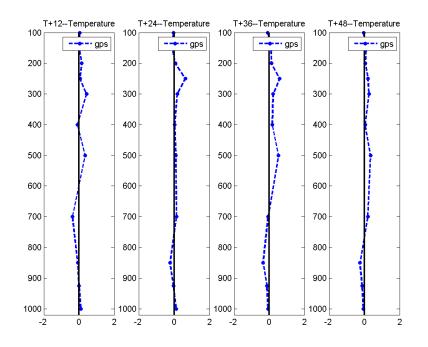
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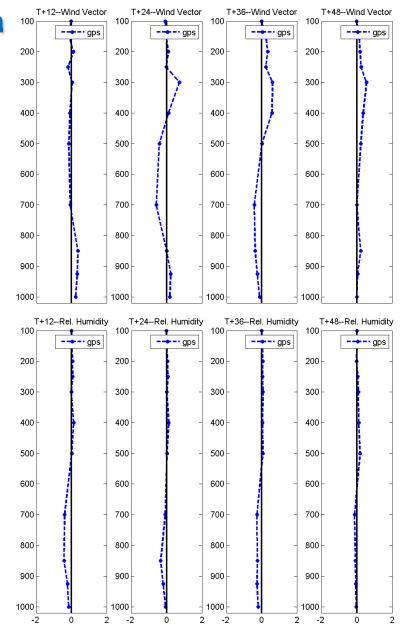
GPS ASSIMILATION

Forecast verification

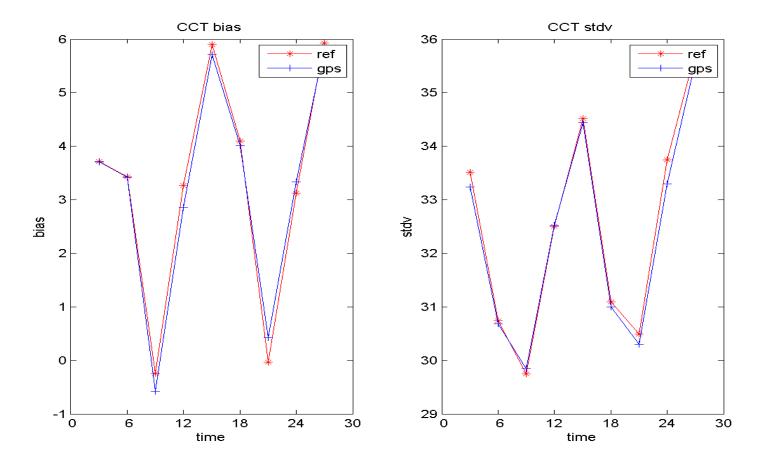
Thinning: 80 km Observation error = 6 mm Static bias correction

Relative difference (%) in RMSE, computed against IFS analysis, with respect to reference run without GPS for 00 UTC COSMO forecasts from 11-nov 2014 to 10 dec 2014 negative value = positive impact







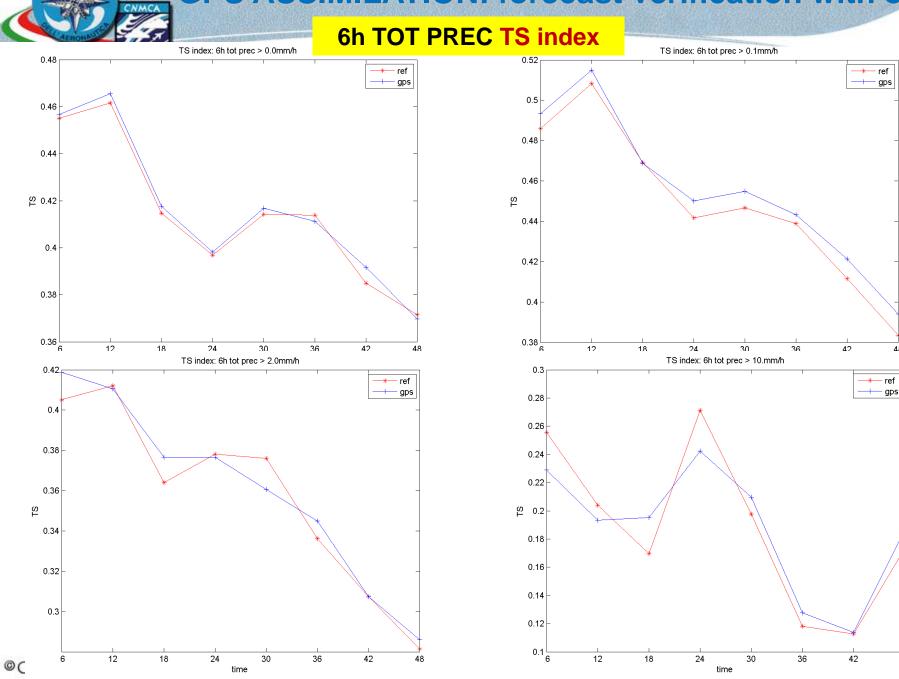




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GPS ASSIMILATION: forecast verification with obs

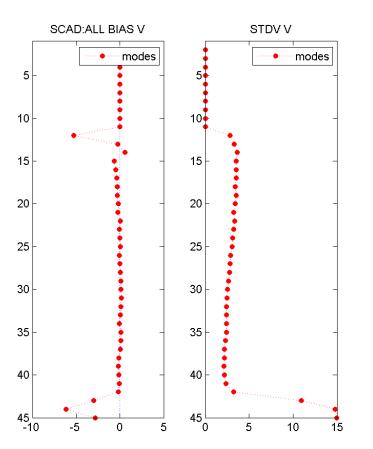




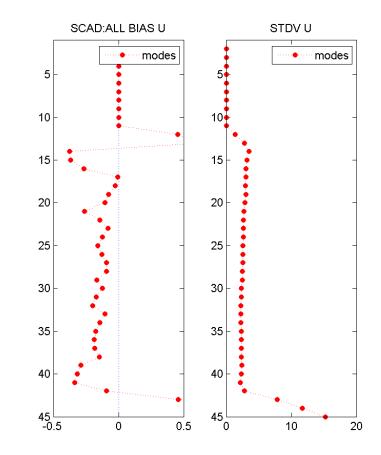
MODE-S MONITORING

1 JAN - 1 APR 2015

MODES in BUFR format from KNMI



Monitoring using CNMCA-LETKF system

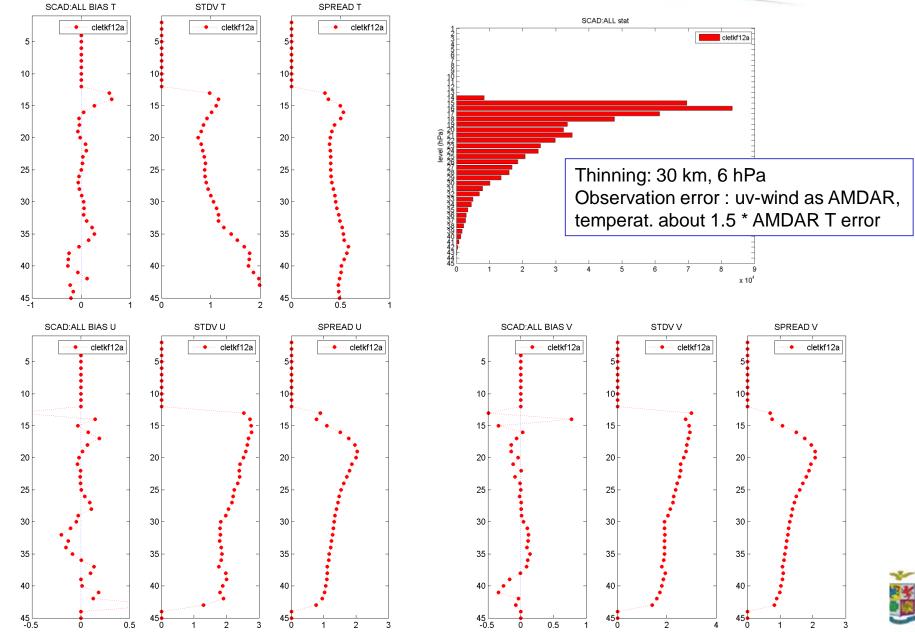






MODE-S ASSIMILATION

MODE-S OBS INCR STATISTICS from 10nov2014 to 10dec2014





MODE-S ASSIMILATION

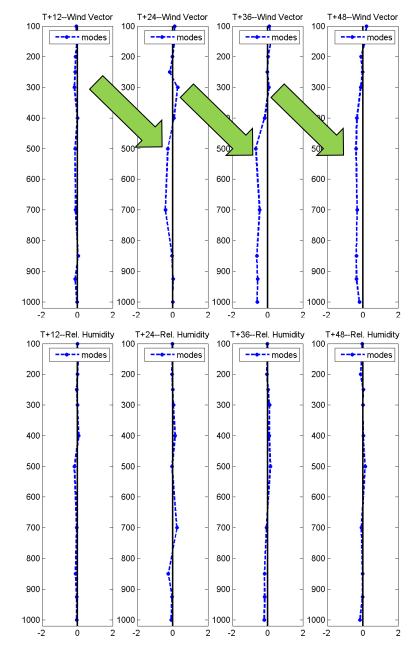
verification

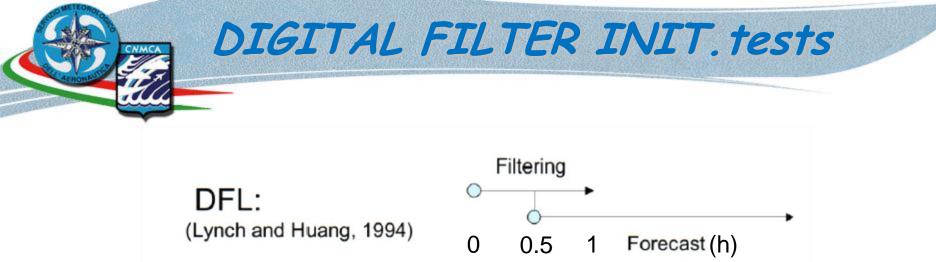
Forecast

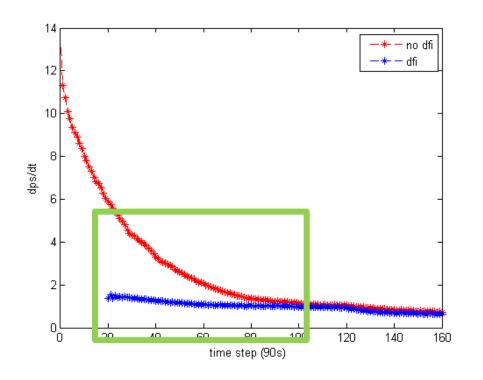
Thinning: 30 km

Relative difference (%) in RMSE, computed against IFS analysis, with respect to reference run without MODE-S for 00 UTC COSMO forecasts from 11-nov 2014 to 10 dec 2014 negative value = positive impact

T+36--Temperature T+12--Temperature T+24--Temperature T+48--Temperature ---- modes ---- modes ---- modes ---- modes -2 -2 -2 -2







DFI original:

All prognostic variables are filtered

DFI new:

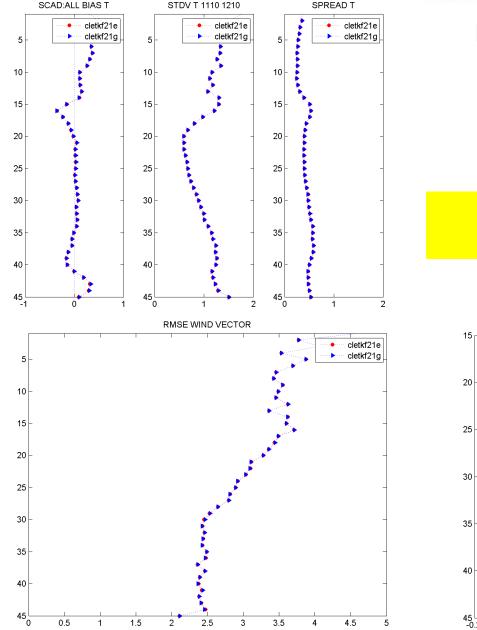
- qv filtered but corrected to mantain saturated grid point at 0.5h step of filtering run

 - qx initialized with instantaneous values valid at 0.5h step of filtering run



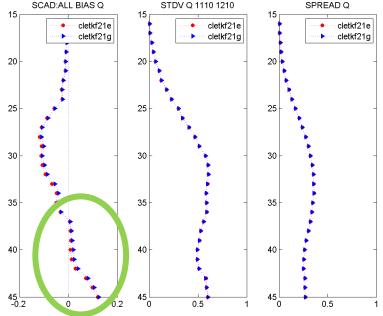


DIGITAL FILTER INIT. tests



RAOB OBS INCR STATISTICS from 10nov2014 to 10dec2014





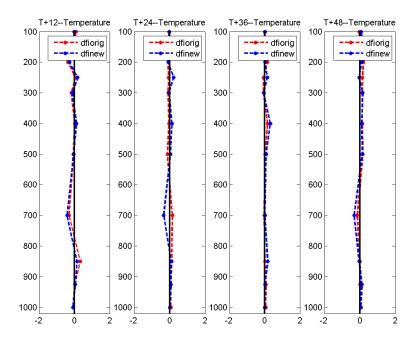


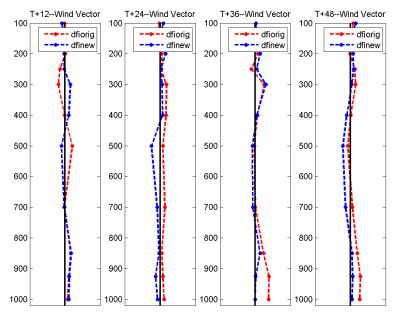
DIGITAL FILTER INIT. tests

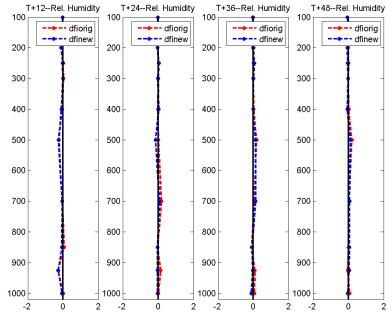
Relative difference (%) in RMSE, computed against IFS analysis, with respect to the reference run without DFI for 00 UTC COSMO forecasts from 11-nov 2014 to 10 dec 2014 negative value = positive impact

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dfi_new vs dfi_orig







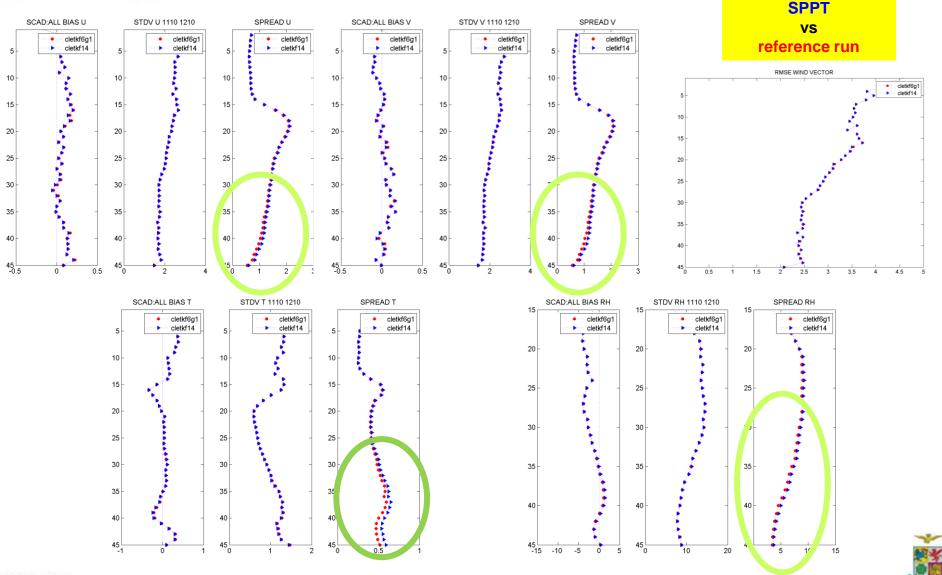
Stochastic Perturbed Physics Tendency Model uncertainty could be represented also with a stochastic physics scheme (Buizza) et al, 1999; Palmer et al, 2009) implemented in the prognostic model This scheme perturbs model physics tendencies by adding perturbations, which are ٠ proportional in amplitude to the unperturbed tendencies **Xc**: Xp=(1+r μ)Xc *r*_{m.n} defined on a coarse grid (ex. DL=4Dx)*r*_{*m,n*} changed every *n time steps* (ex. DT=6Dt) time Model grid

Included in COSMO Reference Version (Torrisi et al)

Random numbers are drawn on a horizontal coarse grid from a Gaussian distribution with a stdv (0.1-0.5) bounded to a certain value (range= ± 2-3 stdv) and interpolated to the model grid to have a smoother pattern in time and horizontally in space. Same random pattern in the whole column and for u,v,t,qv variables.

STOCHASTIC PERTURBED PHYSICS TENDENCIES (SPPT)

RAOB OBS INCR STATISTICS from 10nov2014 to 10dec2014



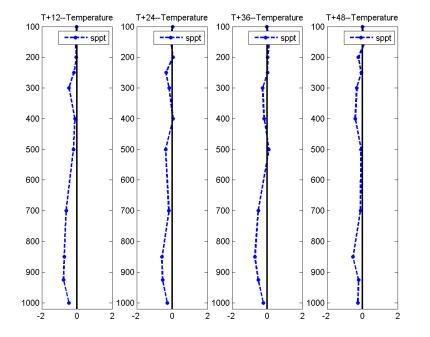
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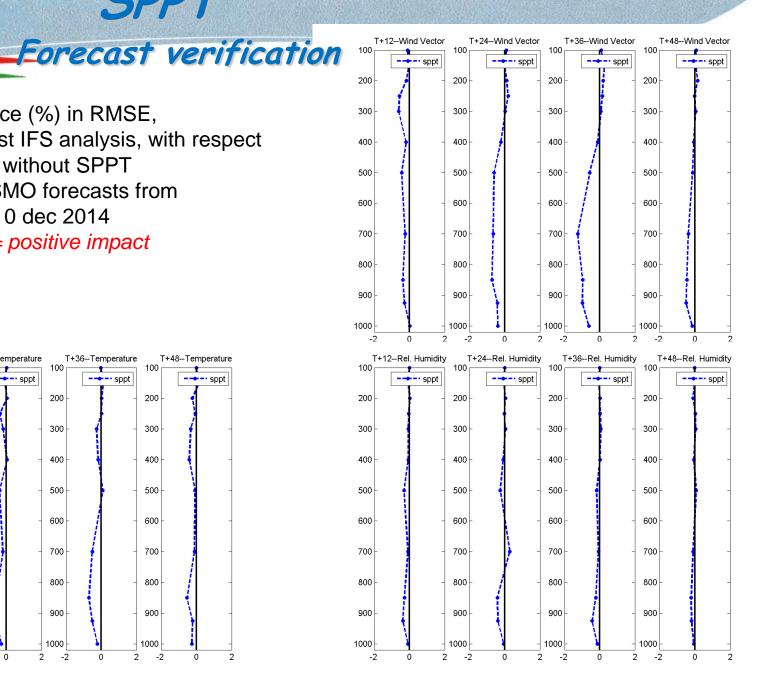
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Relative difference (%) in RMSE, computed against IFS analysis, with respect to reference run without SPPT for 00 UTC COSMO forecasts from 11-nov 2014 to 10 dec 2014 negative value = positive impact

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SPPT

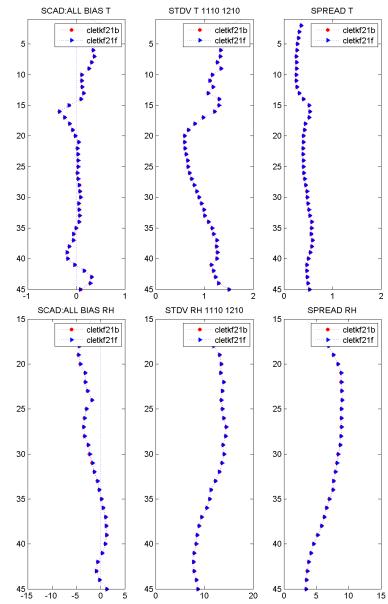




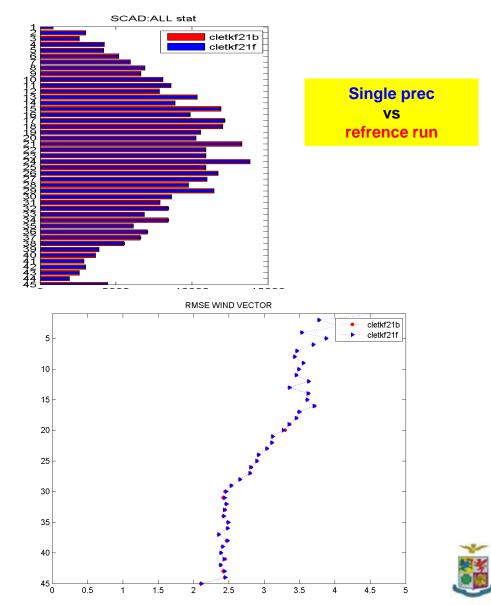
COSMO with Single Precision Real

Not in the deterministic run

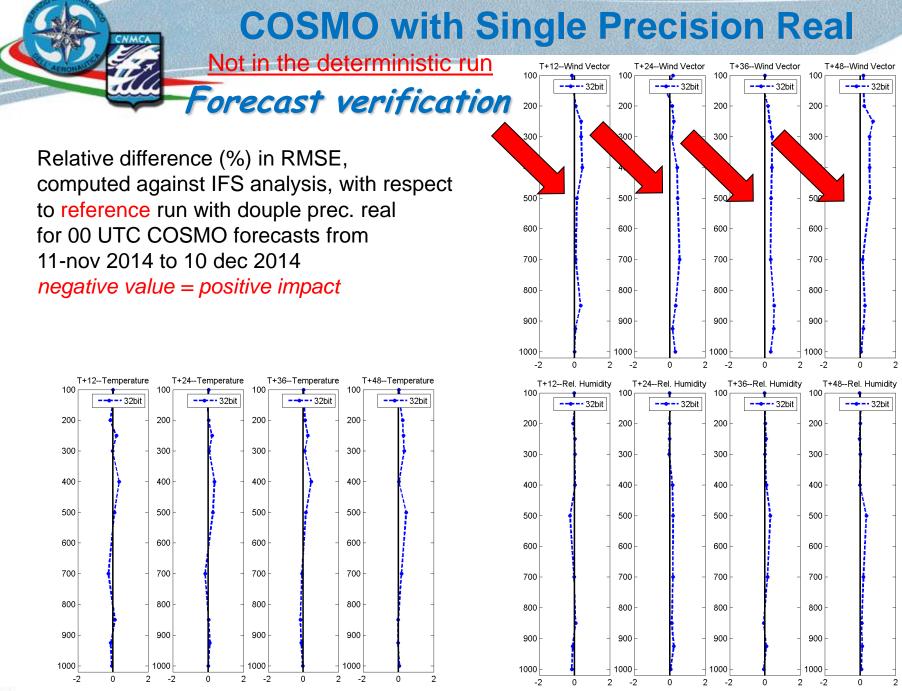
RAOB OBS INCR STATISTICS from 10nov2014 to 10dec2014



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Changes in CNMCA-LETKF system

PSEUDO-RH VARIABLE

Among the other choices of humidity variable types, the best result is from pseudo-RH assimilation. The error distribution of pseudo-RH is more Gaussian than specific humidity observations. It has similar error distribution as the relative humidity observations, but unlike relative humidity observations, it has no error correlation with the other observation variables (J. Liu, 2007, PhD thesis)

1- NEW pseudo-RH variable (J. Liu formulation) : specific humidity observations normalized by the mean saturated specific humidity (qi / q_sat_mean)

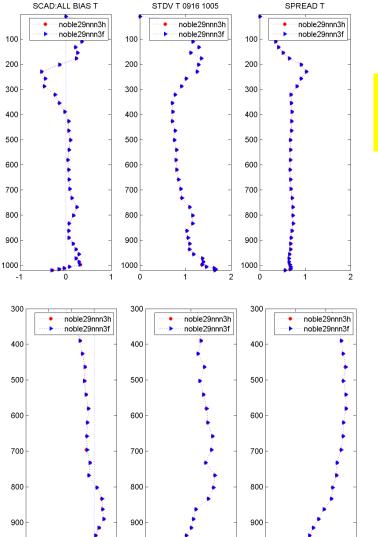
2- OLD pseudo-RH variable qi / qi_sat, defined for each i-member \rightarrow change of variable: used both in weight computation and linear combination



LIU PSEUDO-RH VARIABLE

VS

RAOB OBS INCR STATISTICS from 16-09-2012 to 05-10-2012



1000

0

1000

0

10

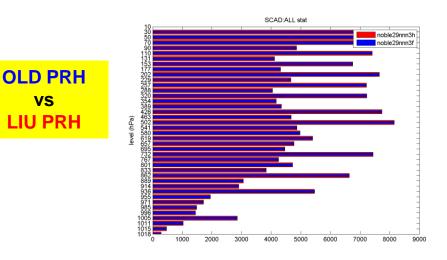
5

15

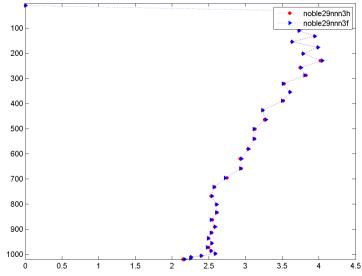
20

10

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RMSE WIND VECTOR



1000

-15 -10 -5 0 5

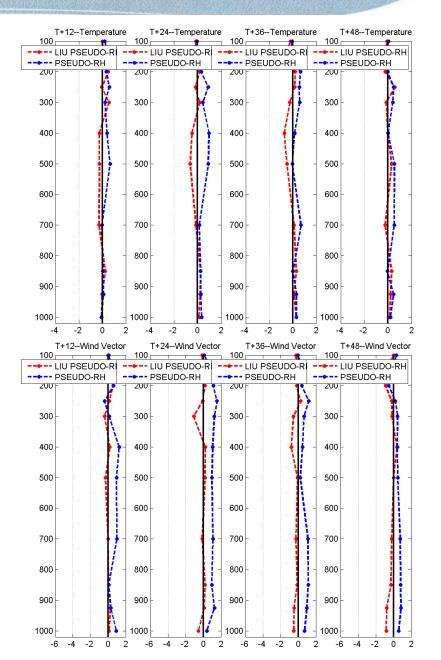


LIU PSEUDO-RH VARIABLE

Relative difference (%) in RMSE computed against IFS analysis with respect to the reference run with qv for 00 UTC COSMO forecasts from 16-09-2012 to 05-10-2012

negative value = positive impact

T+12--Rel. Humidity T+24--Rel. Humidity T+36--Rel. Humidity T+48--Rel. Humiditv _____ 100 ____ - 100 --100 -100 -1 11 --+-- LIU PSEUDO-RI --+-- LIU PSEUDO-RI ----- LIU PSEUDO-RI ----- LIU PSEUDO-RH ---- PSEUDO-RH ---- PSEUDO-RH ---- PSEUDO-RH ---- PSEUDO-RH 200 200 200 300 300 300 300 400 400 400 400 500 500 500 500 600 600 600 600 700 700 700 700 800 800 800 800 900 900 900 900 1000 1000 1000 1000 -4 -2 0 2 -4 -2 0 2 -4 -2 2 -4 -2 0 0



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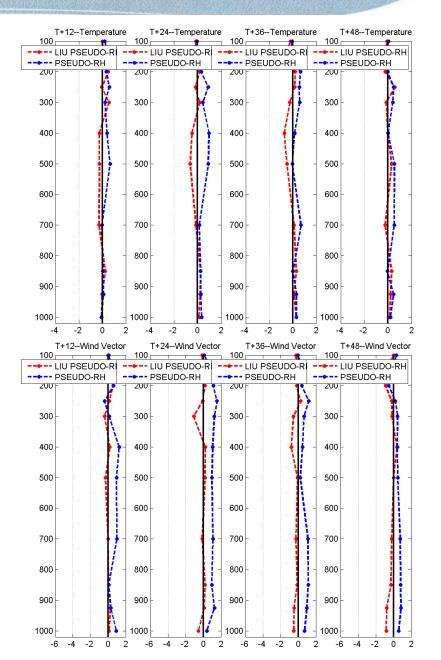


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- Tests using COSMO single precision real
- Assimilation of GPS ground stations and MODES is under investigation.
- Monitoring of local automatic stations and satellite derived soil moisture (H-SAF)
- Improvementent of radiance vertical localization
- Self-evolving additive inflaction/SPPT
- H-SAF soil moisture assimilation affecting low level variables
- Shorter assimilation window using KENDA





Thanks for your attention!



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