

Features of a New Version of the Nudging Code

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- code modifications and new optional features
- modification to spatial consistency check : a case study







- re-structuring of code:
 - modules for reading NetCDF obs input file + obs pre-processing
 (+ clean interface to 1DVAR creation of retrievals from satellite radiances;
 1DVAR routines will not go into official code due to missing documentation)
 - preparations: observation operators for multi-level reports
 → virtual temperature (instead of T) from RASS used as input in obs operator
- more flexible NetCDF observation input file reading:
 - several files for the same observation type
 - more variables optional instead of mandatory
- optimisations for speed-up on NEC-SX9: nudging part: > 25 % ,

whole nudging run: > 15 % speed-up

- (option:) writing NetCDF feedback (feedobs) files (for LETKF / for verification)
 - \rightarrow additional flags and elements (e.g. solar zenith angle)







- height diff. betw. station / model orography considered in a more consistent way (for grid point assignment, station selection, obs errors, ...)
- new flag words, more consistent setting of flags / monitoring statistics (for a passive obs / report, reason for rejection now always indicated)
- after checking for redundancy, the redundancy check loop is re-run with different settings to put TEMP or PILOT parts A, B, C, D together
- no redundancy between 1 RASS + 1 wind profiler, or 2 different ships
- quality control: no temporal consistency check \rightarrow 1 case greatly improved
- latitude dependent reduction of geostrophic wind correction introduced, in order to get reasonably small geostrophic increments near the equator
- many bug fixes
 - prevent vertically collocated levels after redundancy check
 - condition to reject AMDAR obs with reported height below model orography: replaced by pressure condition, because reported height is ficticious
 - avoid array bound violations, etc.







- new options:
 - writing NetCDF feedback (feedobs) files (for LETKF / for verification)
 - mobile TEMP / PILOT
 - GPS IWV obs from NetCDF obs input files
 - \rightarrow can specify preference of processing centers
 - scatterometer 10-m wind
 - new balancing: pressure increments balancing wind analysis increments geostrophically (for scatterometer wind (and in-situ 10-m wind))
 - new weighting for multiple observation / observation types :







$$\frac{\partial}{\partial t}\psi(\underline{x},t) = F(\underline{\psi},\underline{x},t) + G_{\psi} \cdot \sum_{k_{(obs)}} W_k \cdot [\psi_k - \psi(\underline{x}_k,t)]$$

weight W_k for model grid point (\underline{x},t) depends on

- time difference to the observation (w_t)
- space distance to the observation (w_{xy}, w_z)
- observation and model errors (q_k)
- new weighting for multiple observations

$$W_{k} = \frac{W_{k}}{\sum_{j} W_{j}} \cdot W_{k}$$
$$W_{k} = W_{k} \cdot W_{yy} \cdot W_{z} \cdot q$$

$$= \frac{w_k + 1}{\sum_j w_j + 1} \cdot w_k$$

 compute net increments and weights separately for different pre-specified sets of observing systems

$$\frac{\sum \left(w_j^2 + w_j c\right) \cdot \left[\psi_k - \psi(\underline{x}_k, t)\right]}{\sum (w_k + c)} = \frac{\sum \left(w_i^2 + w_i c\right)}{\sum (w_l + c)} \cdot \frac{\sum \left(w_k^2 + w_k c\right) \cdot \left[\psi_k - \psi(\underline{x}_k, t)\right]}{\sum \left(w_j^2 + w_j c\right)}$$

 W_k





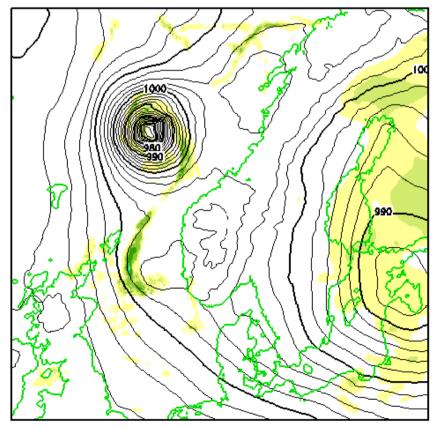
Modification to the quality control : A case study



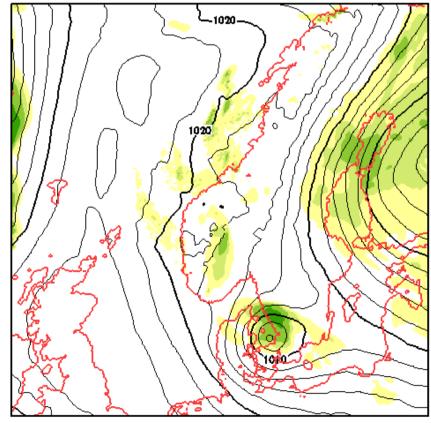
The problem: large errors in COSMO-EU analyses and forecast on 1 – 2 March 2010

plots by Klaus Stephan

COSMO-EU analysis, 2 March 2010, 0 UTC



36-h forecast for 3 March 2010, 12 UTC





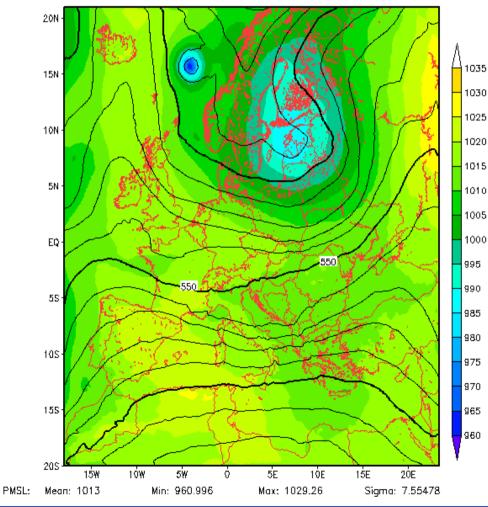




Start time: 02.03.2010 00:00 UTC Forecast time: 02.03.2010 00:00 UTC MSL Pressure [hPa] (shaded)

COSMO-EU Parallel

Geopot. at 500 hPa [gpdm] (dist. isol. 5gpdm)



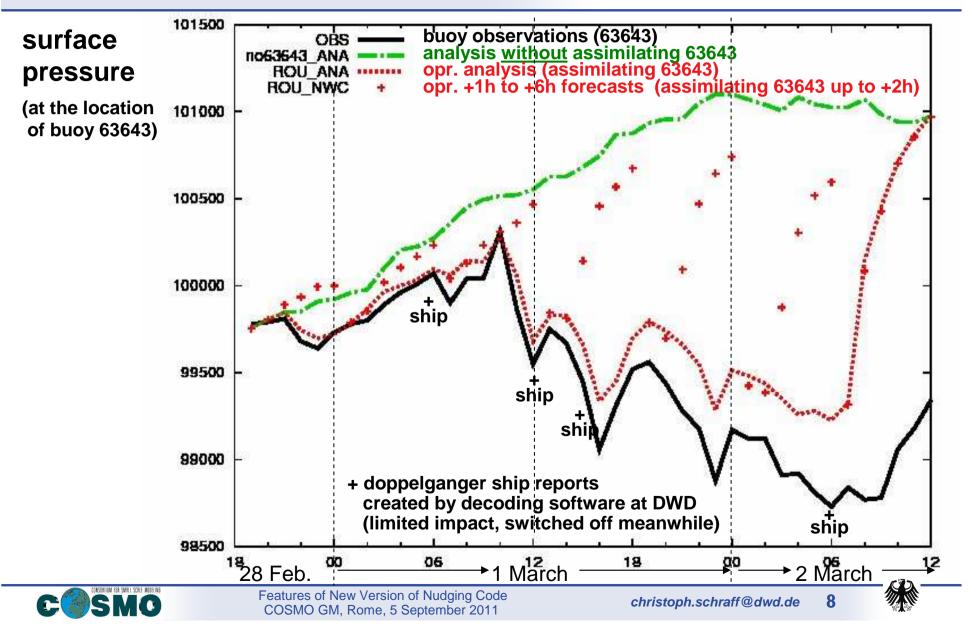
- error in the pressure field (analysis 2 March 2010, 0 UTC) :
 - surface pressure ca. 40 hPa,
 - 500 hPa geopotential ca. 10 gpdm
 - erroneous polar low
- similar error in the analysis at 2 March 2010, 12 UTC
- no such errors in the GME analyses and forecasts
- reason: assimilation of erroneous observations from buoy 63643







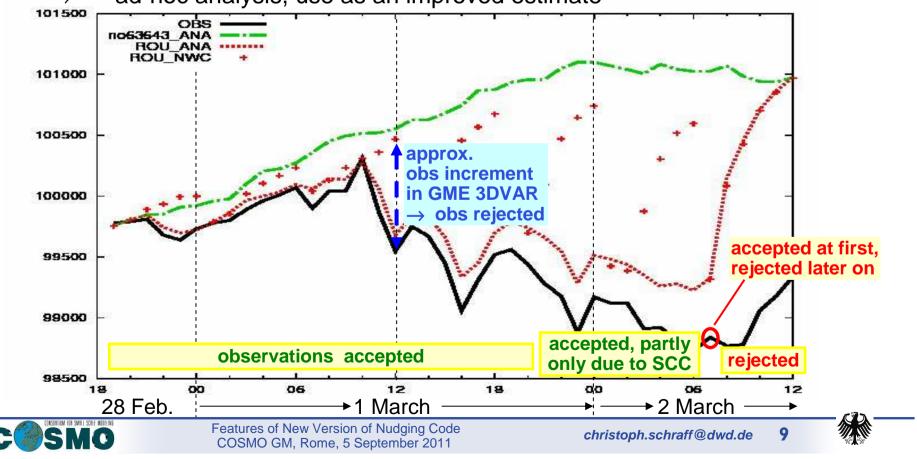
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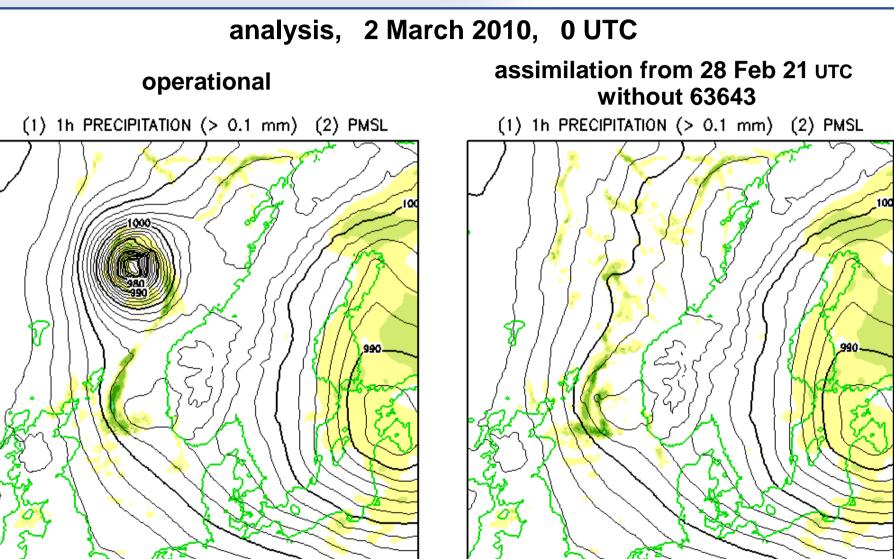


QC checks: deviation of obs from estimate of truth:

- estimate = model value (first guess) : bad obs flagged
- spatio-temporal consistency check (SCC) : correct model value by using all obs within ±1h except for the obs to be checked
 → ad-hoc analysis, use as an improved estimate

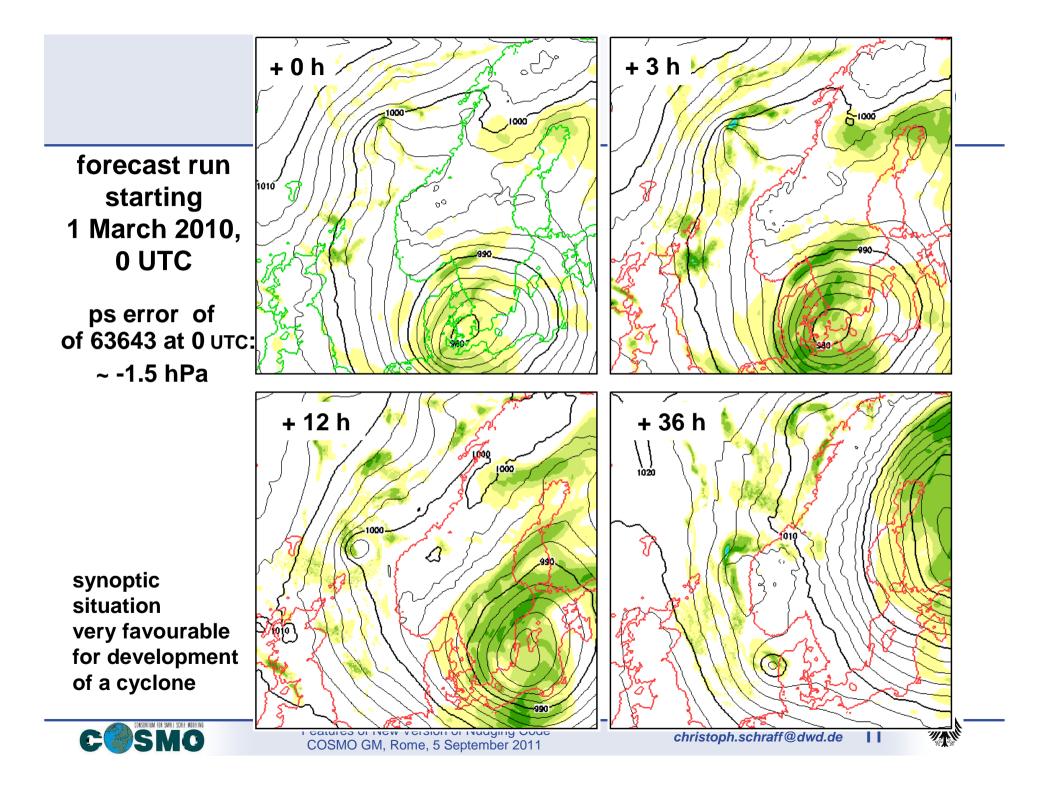














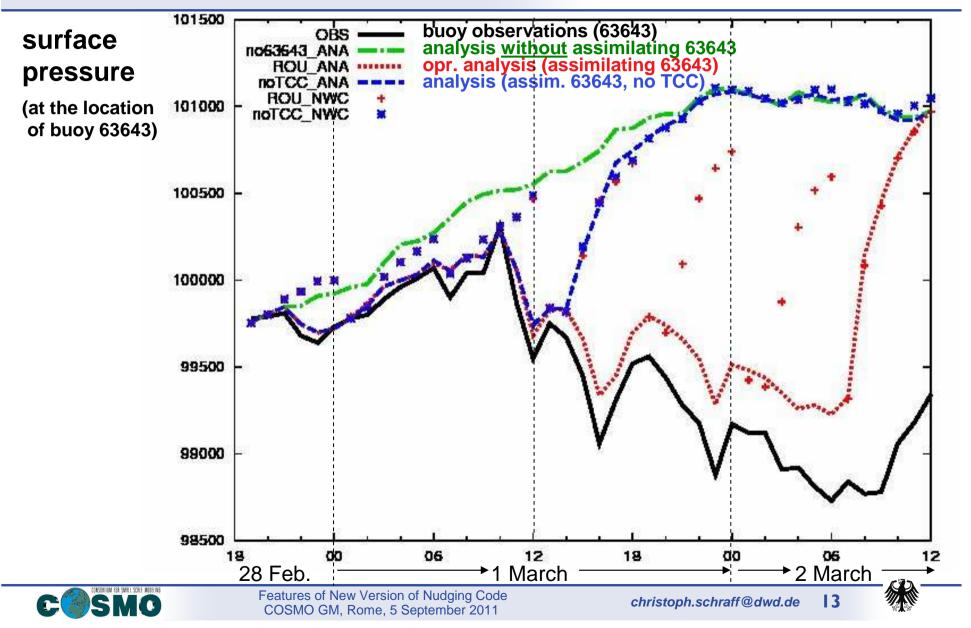
- avoid use of the obs with identical station id from ± 1 h for ad-hoc analysis in the spatial temporal consistency check
 - \rightarrow experiment 'no TCC' : without checking the temporal consistency
- assimilation of scatterometer (10-m wind) data : similar impact as 'no TCC'

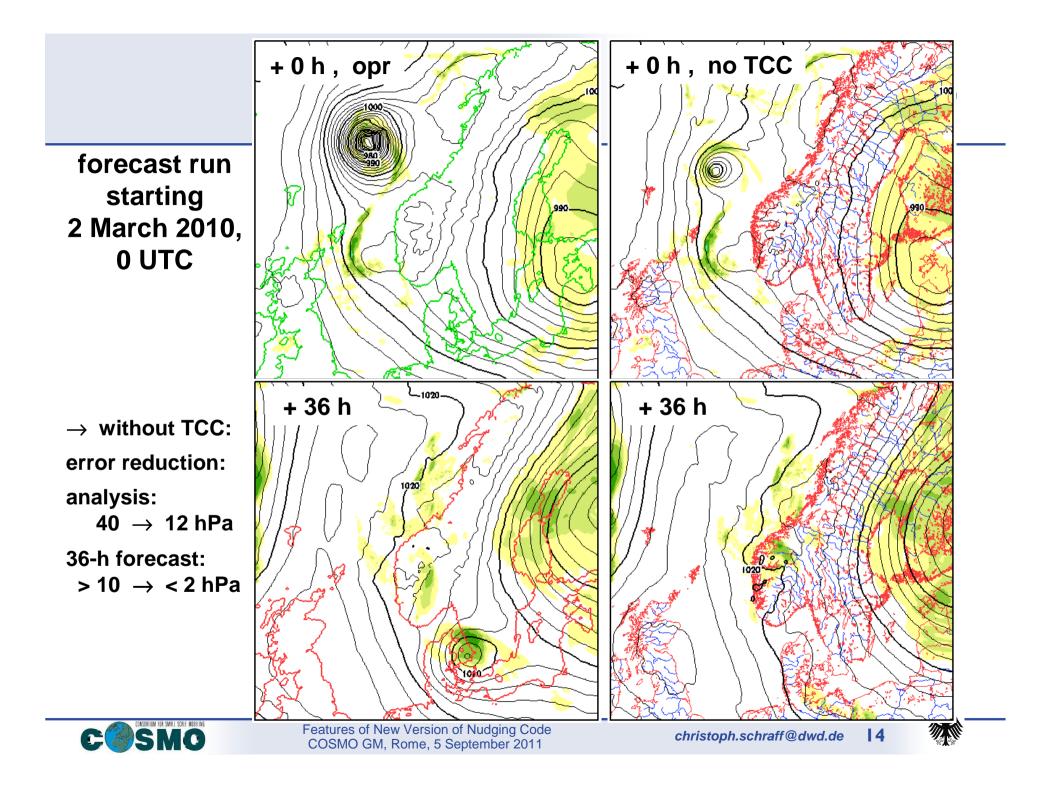


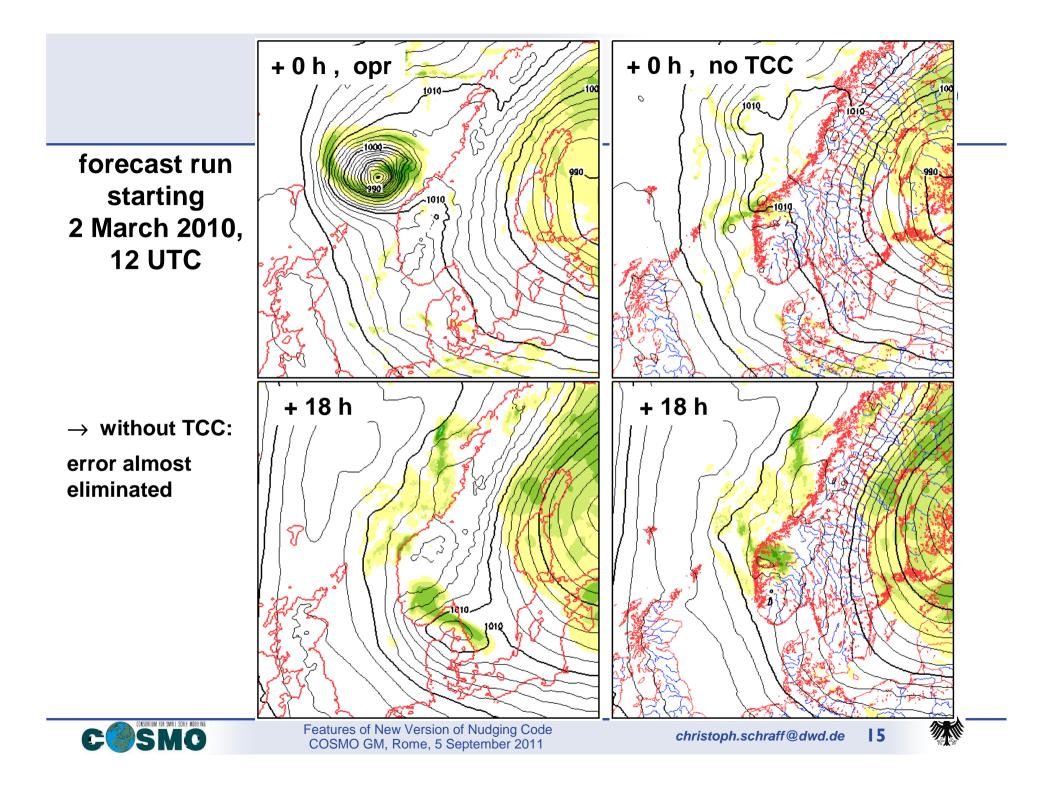






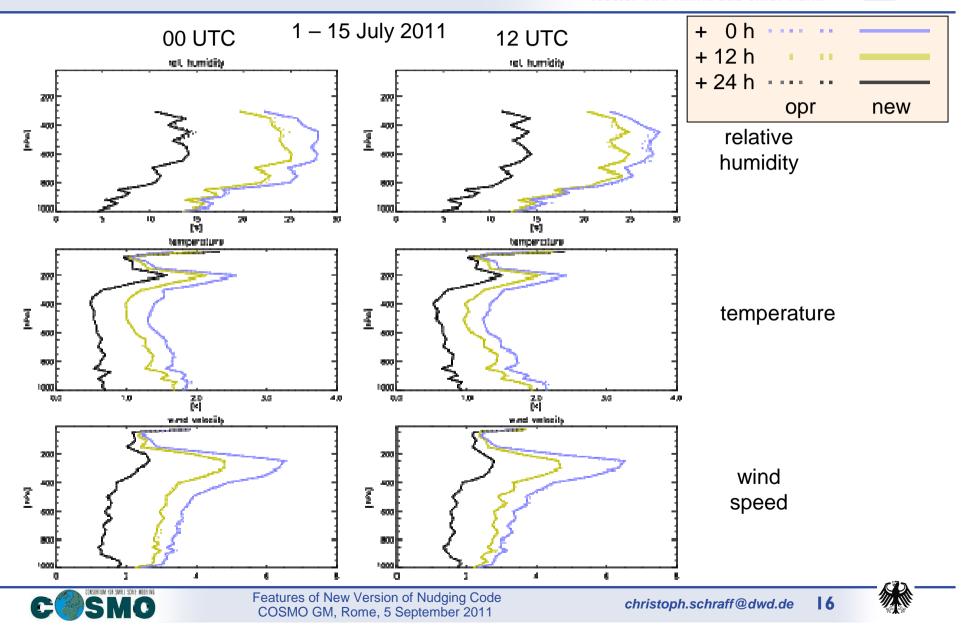






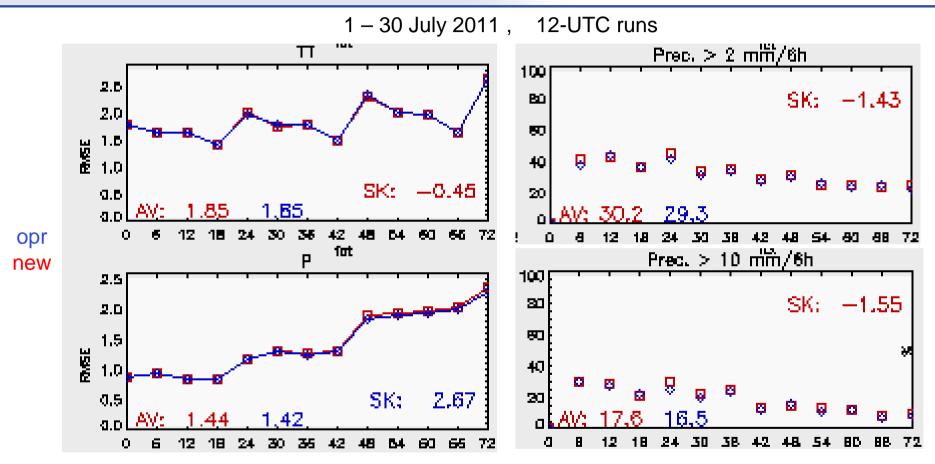
verification results for new version of nudging code

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verification results for new version of nudging code





differences in 0 UTC runs are even smaller

 \rightarrow overall verification result : neutral, as expected











